

Lecture #9: Particle Motion in Slowly Varying E-fields Haves D Polarization Drift

I. Polarization Drift

A. Consider an Electric field varying slowly in time $\tilde{E}(t)$ with a constant Magnetic field $B = B_0 \hat{B}$.

i. Note $\nabla \times \tilde{B} = \mu_0 \tilde{J} + \epsilon_0 \frac{\partial \tilde{E}}{\partial t}$, we assume $|\tilde{J}| \gg |\epsilon_0 \frac{\partial \tilde{E}}{\partial t}|$, so $\frac{\partial \tilde{B}}{\partial t} \approx 0$.

B. Multiple Time Scale Analysis

$$1. \frac{d\tilde{v}}{dt} = \frac{q}{m} (\tilde{E} + \tilde{v} \times \tilde{B})$$

2.a. Take $\tilde{E}(t)$ varies only on slow timescale $\tau = \epsilon T$

$$b. \tilde{v} = \tilde{v}_1(t) + \epsilon \tilde{v}_2(\tau) + \epsilon^2 \tilde{v}_3(\tau) + \dots$$

$$c. \text{Also assume } \tilde{E}(t) \cdot \tilde{B} = 0$$

3. As before,

$$\frac{d}{dt} = \frac{d}{dt} + \frac{\partial \tau}{\partial t} \frac{\partial}{\partial \tau} = \frac{d}{dt} + \epsilon \frac{\partial}{\partial \tau}$$

4. We'll take a small electric field such that the ExB drift velocity $v_E \ll v$, where v is Larmor orbit velocity.

$$\text{Thus } \frac{d\tilde{v}}{dt} = \frac{q}{m} (\epsilon \tilde{E} + \tilde{v} \times \tilde{B})$$

5. Subsive expanded solution:

$$\frac{\partial}{\partial t} (\tilde{v}_1 + \epsilon \tilde{v}_2 + \epsilon^2 \tilde{v}_3) + \epsilon \frac{\partial}{\partial \tau} (\tilde{v}_1 + \epsilon \tilde{v}_2 + \epsilon^2 \tilde{v}_3) = \epsilon \frac{q}{m} \tilde{E}(t)$$

$$+ \frac{q}{m} (\tilde{v}_1 + \epsilon \tilde{v}_2 + \epsilon^2 \tilde{v}_3) \times \tilde{B}$$

a. Taking $\tilde{B} = B_0 \hat{b}$,

$$\frac{\partial \tilde{v}_1}{\partial t} + \epsilon \frac{\partial \tilde{v}_2}{\partial \tau} + \epsilon^2 \frac{\partial \tilde{v}_3}{\partial \tau} = \epsilon \frac{q \tilde{E}(t)}{m} + \omega_c \tilde{v}_1 \times \hat{B} + \epsilon \omega_c \tilde{v}_2 \hat{b} + \epsilon^2 \omega_c \tilde{v}_3 \hat{b}$$

Lecture 9: (Continued)

Haves ②

I.B. (Continued)

$$6. O(1): \frac{\partial \underline{v}}{\partial t} = \omega_c \underline{v}_\perp + \hat{\underline{b}}$$

a. This is just the usual, fast timescale Larmor gyration about the magnetic field.

b. The general solution for this motion can be written

$$\underline{v}_\parallel = V_\parallel \cos(\omega_c t + \phi) \hat{\underline{e}}_1 - V_\parallel \sin(\omega_c t + \phi) \hat{\underline{e}}_2 + V_{\parallel\parallel} \hat{\underline{b}}$$

For a right-handed coordinate system s.t. $\hat{\underline{e}}_1 \times \hat{\underline{e}}_2 = \hat{\underline{b}}$

$$7. O(\epsilon): \underline{Q} = \cancel{\frac{q}{m} \underline{E}(\tau)} + \epsilon \frac{q B_0}{m} \underline{v}_2 \times \hat{\underline{b}}$$

a. This is just the slow timescale $\underline{E} \times \underline{B}$ drift.

b. Dividing by $\hat{\underline{b}}$ on either side gives:

$$\cancel{\frac{q}{m} \hat{\underline{b}} \times \underline{E}(\tau)} = \frac{q B_0}{m} \hat{\underline{b}} \times (\underline{v}_2 \hat{\underline{b}}) = b_0 (V_2 (\hat{\underline{b}} \cdot \hat{\underline{b}}) - V_{2\parallel} \hat{\underline{b}})$$

or

$$\underline{v}_2 = V_{2\parallel} \hat{\underline{b}} + \frac{\underline{E}(\tau) \times \hat{\underline{b}}}{B_0^2}$$

$$8. O(\epsilon^2): \cancel{\frac{q^2}{m^2} \frac{\partial \underline{v}_2}{\partial t}} = \epsilon^2 \omega_c \underline{v}_3 \times \hat{\underline{b}}$$

a. At this order, the solution \underline{v}_2 is considered to be known.

$$\text{Thus, } \frac{\partial \underline{v}_2}{\partial t} = \cancel{\frac{\partial \underline{v}_{2\parallel}}{\partial t}} \hat{\underline{b}} + \frac{1}{B_0^2} \frac{\partial \underline{E}}{\partial t} \times \hat{\underline{b}} = \frac{\cancel{\frac{\partial \underline{E}}{\partial t}} \hat{\underline{b}}}{B_0^2}$$

$$\text{b. } \frac{1}{B_0^2} \frac{\partial \underline{E}}{\partial t} \times \hat{\underline{b}} = \cancel{\omega_c \underline{v}_3 \times \hat{\underline{b}}}$$

c. Take $\hat{\underline{b}} \times \hat{\underline{b}}$ this equation

$$\frac{1}{B_0^2} \hat{\underline{b}} \times \left(\cancel{\frac{\partial \underline{E}}{\partial t}} \hat{\underline{b}} \right) = \cancel{\omega_c \frac{1}{B_0} \left[\frac{\partial \underline{E}}{\partial t} (\hat{\underline{b}} \cdot \hat{\underline{b}}) - \hat{\underline{b}} \left(\hat{\underline{b}} \cdot \frac{\partial \underline{E}}{\partial t} \right) \right]} = \frac{1}{B_0} \frac{\partial \underline{E}}{\partial t}$$

$$\cancel{\omega_c \hat{\underline{b}} \times (\underline{v}_3 \times \hat{\underline{b}})} = \cancel{\omega_c [V_3 (\hat{\underline{b}} \cdot \hat{\underline{b}}) - \hat{\underline{b}} (V_3 \cdot \hat{\underline{b}})]} = \omega_c (V_3 - V_{3\parallel} \hat{\underline{b}})$$

d. Thus

$$\underline{v}_3 = V_{3\parallel} \hat{\underline{b}} + \frac{1}{\omega_c B_0} \frac{\partial \underline{E}(\tau)}{\partial t}$$

Lecture 9 (Continued)

Howes (3)

I.B. (Continued)

9. Putting the full solution together: (Taking $V_{211} = V_{311} = 0$)

$$\underline{V} = V_1 (\cos(\omega t + \phi) \hat{e}_1 - \sin(\omega t + \phi) \hat{e}_2) + \frac{\underline{E}(t) \times \underline{B}}{B^2} + \frac{1}{\omega c B_0} \frac{d\underline{E}}{dt}$$

Zeroth order Larmor Motion

First-order
 $\underline{E} \times \underline{B}$ drift

Second-order
Polarization Drift

C. Polarization Drift:

1. For slowly varying electric field $\underline{E}(t)$ (slow with respect to the Larmor motion), we define the

Polarization Drift

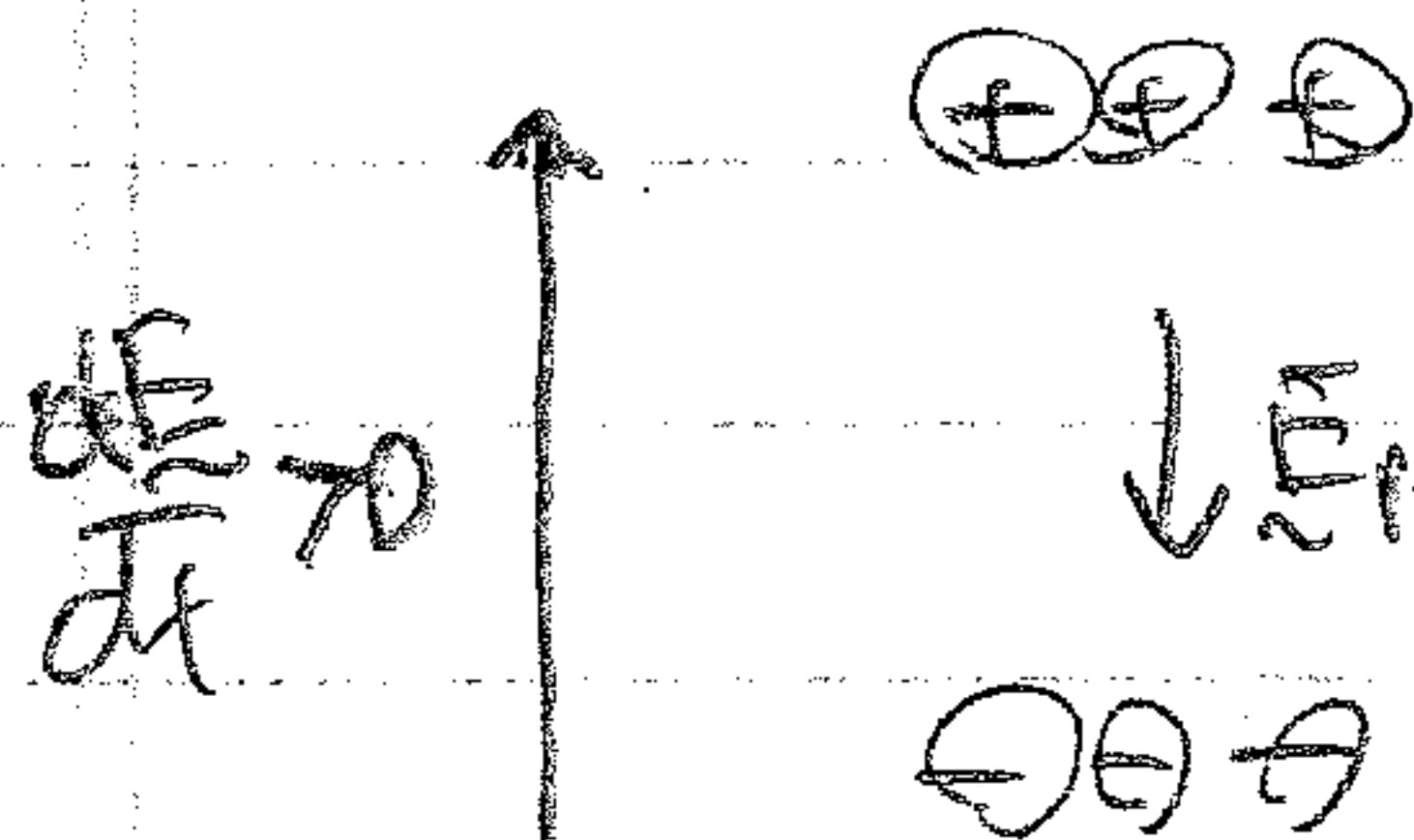
$$V_p = \frac{1}{\omega c B} \frac{d\underline{E}}{dt}$$

2. Using $\omega_c = \frac{qB}{m}$, we have

$$V_p = \frac{m}{q B^2} \frac{d\underline{E}}{dt}$$

a. Polarization drift is charge dependent

⇒ ions and electrons drift in opposite directions



b. Resulting polarization of plasma opposes increasing applied Electric field.

c. Because $m_i \gg m_e$, ions dominate the polarization drift.

3. Polarization Current: $i_p = \sum_s q_s n_s V_p = \sum_s \frac{q_s n_s m_s}{\omega c B^2} \frac{d\underline{E}}{dt}$

a. $i_p = \sum_s \frac{n_s m_s}{B^2} \frac{d\underline{E}}{dt}$

b. Mass dependence means ion contributes more to polarization current.

Lecture #9 (Continued)

I.C.3. (Continued)

Hanes (4)

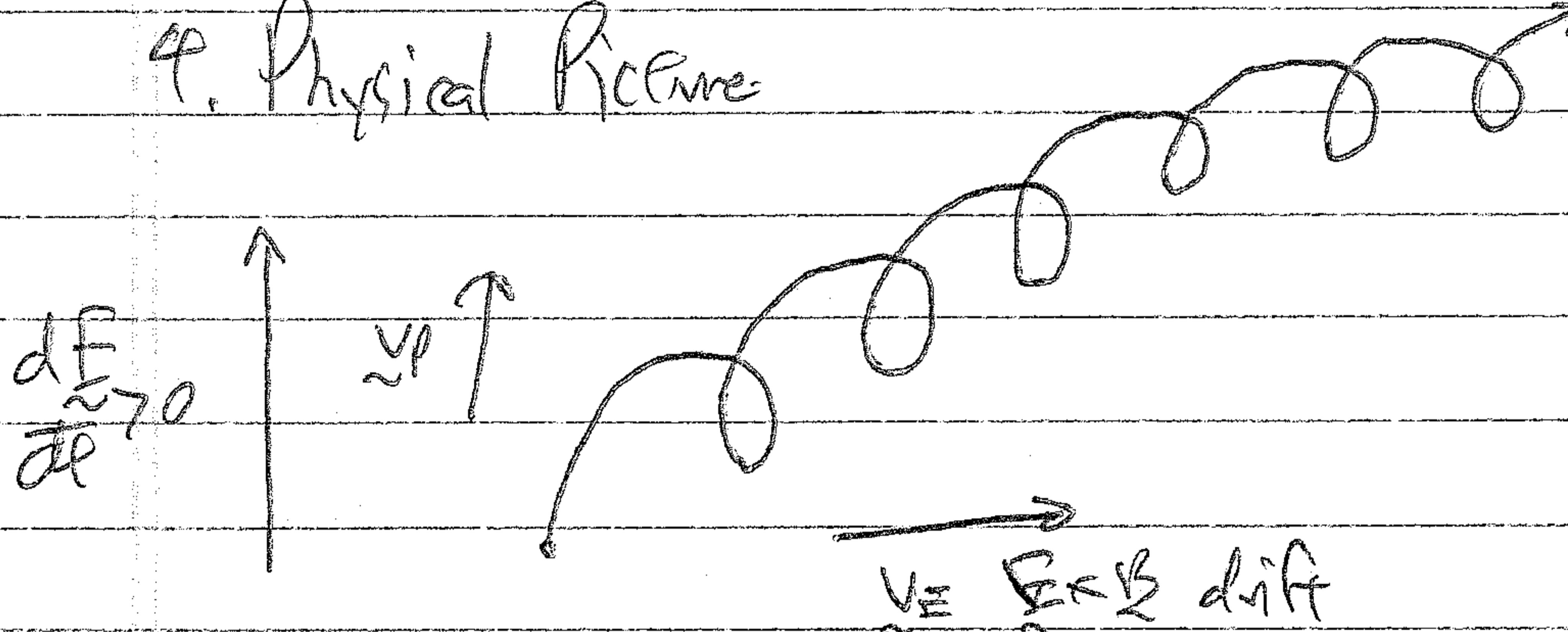
b. NOTE: $E \times B$ velocity is the same for both species, so

it cancels, producing no net current.

$$j_E = \sum_s q_s n_s v_E = \sum_s q_s n_s \frac{E \times B}{B^2} = \frac{E \times B}{B^2} \sum_s q_s n_s = 0$$

by quasineutrality.

4. Physical Picture



5. The Polarization Drift can lead to an increase in energy.

$$a. \frac{dE}{dt} = \vec{v} \cdot \vec{F} = \vec{v} \cdot q(\vec{E} + \vec{v} \times \vec{B}) = q \vec{v} \cdot \vec{E}$$

$$b. = q \left[V_1 \cos(\omega t + \phi) \hat{e}_1 \cdot \hat{e}_1 + V_1 \sin(\omega t + \phi) \hat{e}_2 \cdot \hat{e}_2 \right]$$

$$+ \frac{E(t) \times B}{B^2} \cdot \hat{e}_3 + \frac{1}{\omega c B} \frac{dE}{dt} \cdot \hat{e}_3$$

Average over Larmor orbit $\Rightarrow 0$.

$$c. \text{ Thus } \frac{dE}{dt} = \frac{q}{\omega c B} \frac{d(B^2)}{dt} = \frac{d}{dt} \left[\frac{1}{2} m \left(\frac{E}{B} \right)^2 \right]$$

$$d. \text{ Note: } (V_E)^2 = \frac{E^2}{B^2}, \text{ so this can be written } \frac{d}{dt} \left(\frac{1}{2} m V_E^2 \right) = \frac{dE}{dt}$$

e. The polarization drift leads to the acceleration of particles to achieve the $E \times B$ drift velocity.