

Lecture #17 Convolution Theorem, Signal Processing and Discrete Fourier Transforms

I. Convolution Theorem Applications

A. Ex: Green's Function for Poisson Eq

1. $\phi(\underline{r}) = \frac{1}{4\pi} \int \frac{\rho(\underline{r}')}{|\underline{r}-\underline{r}'|} d^3r'$ ← Form of a convolution.

2. Use $\int g(\underline{r}') f(\underline{r}-\underline{r}') d^3r' = \int F(\underline{k}) G(\underline{k}) e^{-i\underline{k}\cdot\underline{r}} d^3k$ Convolution Theorem

where $g(\underline{r}') = \rho(\underline{r}')$ and $f(\underline{r}) = \frac{1}{r} \Rightarrow f(\underline{r}-\underline{r}') = \frac{1}{|\underline{r}-\underline{r}'|}$

3. $F(\underline{k}) = [f(\underline{r}-\underline{r}')]^T = \frac{1}{(2\pi)^{\frac{3}{2}}} \frac{4\pi}{k^2}$ (20.42), $G(\underline{k}) = \rho^T(\underline{k})$

4. Thus $\phi(\underline{r}) = \frac{1}{(2\pi)^{\frac{3}{2}}} \int \frac{\rho^T(\underline{k})}{k^2} e^{-i\underline{k}\cdot\underline{r}} d^3k$ May be easier to evaluate

B. Ex: Two-Center Overlap Integral

1. $S_{ab} = \int \phi_a^*(\underline{r}-\underline{A}) \phi_b(\underline{r}-\underline{B}) d^3r$

a. Scalar product of two atomic orbitals: ϕ_a centered at \underline{A} , ϕ_b at \underline{B} .

2. Change coordinates to original \underline{A} : $\underline{r}' = \underline{r} - \underline{A}$

a. Thus $\underline{r}-\underline{B} = \underline{r}' - (\underline{B}-\underline{A}) \equiv \underline{r}' - \underline{R}$ where $\underline{R} = \underline{B}-\underline{A}$ is separation!

b. Yields $S_{ab} = \int \phi_a^*(\underline{r}') \phi_b(\underline{r}' - \underline{R}) d^3r'$

$\underline{R}-\underline{r}'$ would yield standard convolution form!

c. Use (20.50), $[\phi_b(-[\underline{R}-\underline{r}'])]^T = \phi_b^T(-\underline{k})$

3. Use Conv. Thm, $S_{ab} = \int \phi_a^{*T}(\underline{k}) \phi_b^T(-\underline{k}) e^{-i\underline{k}\cdot\underline{R}} d^3k$

I. B. (Continued)

Hanes ②

4. If we assume Slater-type orbitals (STOs) of the form

a. $\phi = \phi^* = e^{-\zeta r}$ with screening parameter ζ .

b. $\phi^T = \frac{1}{(2\pi)^{3/2}} \frac{8\pi\zeta}{(k^2 + \zeta^2)^2}$

5. Thus, $S_{ab} = \frac{(8\pi\zeta)^2}{(2\pi)^3} \int \frac{e^{-i\mathbf{k}\cdot\mathbf{R}}}{(k^2 + \zeta^2)^4} d^3\mathbf{k}$

a. Evaluated at single point \mathbf{k} with spacing R in complex exponential.

b. Use spherical wave expansion of $e^{-i\mathbf{k}\cdot\mathbf{R}}$: (6.61)

$$e^{i\mathbf{k}\cdot\mathbf{R}} = 4\pi \sum_{l=0}^{\infty} \sum_{m=-l}^l i^l j_l(kR) Y_l^m(\Omega_{\mathbf{R}}) Y_l^{m*}(\Omega_{\mathbf{k}})$$

a. Using similar procedure as last #6, I.B., after integration over all $d^3\mathbf{k}$, only Y_0^0 term survives.

b. Simplifies to $S_{ab} = \frac{(8\pi\zeta)^2}{(2\pi)^3} \int_0^{\infty} \frac{j_0(kR)}{(k^2 + \zeta^2)^4} 4\pi k^2 dk$

7. This integral can be expressed in terms of modified spherical Bessel function $k_2(\zeta R)$ [see (20.82) in case 7], yielding

$$S_{ab} = \frac{\pi R^3}{3} k_2(\zeta R) = \frac{\pi e^{-\zeta R}}{3\zeta^3} (\zeta^2 R^2 + 3\zeta R + 3)$$

C. Multiple Convolutions

1. Consider convolution of $f(x)$ with $[g*h](x)$

$$[f*(g*h)](x) = \frac{1}{2\pi} \int_{-\infty}^{\infty} dy \int_{-\infty}^{\infty} dz f(y) g(z-y) h(x-z)$$

2. Convolution Theorem $[f*g*h]^T(\omega) = F(\omega)G(\omega)H(\omega)$

a. Functions $f, g, & h$ can be convolved in any order \rightarrow same result

I. C. (Continued)

Haves (3)

$$B. \int_{-\infty}^{\infty} dy \int_{-\infty}^{\infty} dz f(y) g(z-y) h(x-z) = (2\pi)^{1/2} \int_{-\infty}^{\infty} F(\omega) G(\omega) H(\omega) e^{-i\omega x} d\omega$$

4. Ex: Interaction of Two Charge distributions

a. $V = \int d^3r' \int d^3r'' \frac{\rho_1(r') \rho_2(r'')}{|r'' - r'|}$ ← Double convolution with $x=0$ and sign change in argument of ρ_2 .

b. Taking $f(x) = \frac{1}{r}$, $g(r) = \rho_1(r)$, $h(r) = \rho_2(r)$, we obtain

$$V = 4\pi \int \frac{d^3k}{k^2} \rho_1^T(k) \rho_2^T(-k) \leftarrow \text{Single 3D integral}$$

NOTE: $e^{ik \cdot x} = 1$ ($x=0$)

D. Transform of a Product

1. Fourier transform of a product \Rightarrow Convolution of Fourier Transforms

$$[f(x)g(x)]^T = (F * G)(\omega)$$

2. This arises when Fourier transforming a nonlinear equation.

a. Nonlinear term yields a convolution.

b. In practice, in numerical simulations, equations are transformed from Fourier space back to physical space to evaluate nonlinear terms.

II. Signal Processing

A. Concepts

1. Consider a time series $f(t)$

a. Each frequency ω contributes $F(\omega) e^{i\omega t}$, so

$$f(t) = \frac{1}{2\pi} \int_{-\infty}^{\infty} F(\omega) e^{i\omega t} d\omega$$

II A (Continued)

2. What do negative frequencies mean?

a. Mathematical consequence of not using two functions (sin & cos) to define the signal. \rightarrow Needed to get phase correct.

3. Alternate definitions

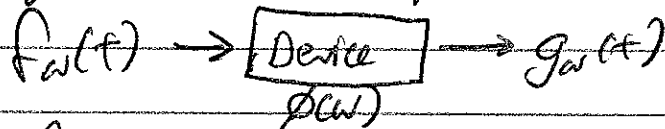
$$f(t) = \frac{1}{2\pi} \int_{-\infty}^{\infty} F(\omega) e^{i\omega t} d\omega$$

$$F(\omega) = \int_{-\infty}^{\infty} f(t) e^{-i\omega t} dt$$

a. Normalization & sign of exponent changed from previous definition.

B. Transfer Function

1. For a single frequency signal $f_{\omega}(t)$, consider a device which can change its amplitude & phase (but not ω) to yield $g_{\omega}(t)$.



2. Linear Response

a. We're $g_{\omega}(t)$ is at same frequency ω as input $f_{\omega}(t)$

b. We're sales linearly with input

c. Result is independent of other frequencies

$$g_{\omega}(t) = \phi(\omega) f_{\omega}(t)$$

\rightarrow Transfer Function: Characteristic of device.

3. For full spectrum of ω ,

$$g(t) = \frac{1}{2\pi} \int_{-\infty}^{\infty} \phi(\omega) F(\omega) e^{i\omega t} d\omega$$

4. Let $\Phi(t) = \frac{1}{2\pi} \int_{-\infty}^{\infty} \phi(\omega) e^{i\omega t} d\omega$

a. By Conv. Thm, we may obtain

$$g(t) = \int_{-\infty}^{\infty} f(t') \Phi(t-t') dt'$$

II, B. (Continued)

5. Causality:

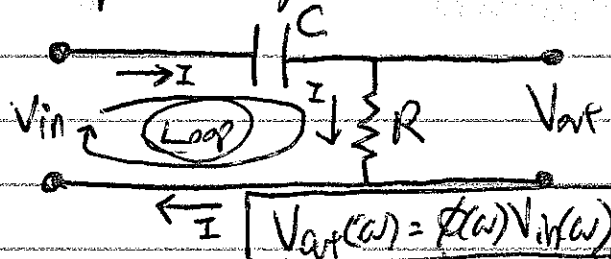
$g(t) = \int_{-\infty}^{\infty} f(t') \Phi(t-t') dt'$ Howes (5)
 a. Since the effect at time t on $g(t)$ must only depend on times $t' < t$ due to causality, $\Phi(t-t') = 0$ $t' > t$

6. Thus,
$$g(t) = \int_{-\infty}^t f(t') \Phi(t-t') dt'$$

7. Reality of $\Phi(t)$: a. Since $g(t)$ must be real, given a real input $f(t)$, the $\Phi(t)$ must also be real!

Causality and Reality are important properties of transfer functions $\Phi(t)$

8. Example: High-Pass Filter a. Linear response at frequency ω



- i. Input: $V_{in}(\omega) e^{i\omega t}$
- ii. Output: $V_{out}(\omega) e^{i\omega t}$
- iii. Current: $I(\omega) e^{i\omega t}$

$V_{out}(\omega) = \phi(\omega) V_{in}(\omega)$

coefficients \uparrow may be complex.

b. Electrical Circuit Analysis: Kirchhoff's Law: Potential around closed loop = 0.

$$V_{in} e^{i\omega t} = \int dt \frac{I}{C} e^{i\omega t} dt + R I e^{i\omega t}$$

c. Differentiate with respect to time to eliminate integral.

$$V_{in} \frac{d}{dt} e^{i\omega t} = \frac{I}{C} e^{i\omega t} + R I \frac{d}{dt} e^{i\omega t}$$

$$i\omega V_{in} e^{i\omega t} = \frac{I}{C} e^{i\omega t} + i\omega R I e^{i\omega t}$$

d. Solve for Current: $I = \frac{i\omega C V_{in}}{1 + i\omega R C}$

strictly function of real constants RC

e. $V_{out} = I R$, so
$$\phi(\omega) = \frac{V_{out}(\omega)}{V_{in}(\omega)} = \frac{i\omega R C}{1 + i\omega R C}$$

$\lim_{\omega \rightarrow \infty} \phi(\omega) = 1$
 $\lim_{\omega \rightarrow 0} \phi(\omega) = 0$

II. (Continued)

C. Restrictions on $\Phi(\omega)$

Forward transform using
convenience in this section! Hawes (6)

1. $\Phi(\omega) = \int_0^{\infty} \Phi(t) e^{-i\omega t} dt$ Recall $\Phi(t) = 0$ for $t < 0$.

2. Separate Re & Im: $\Phi(\omega) = U(\omega) + iV(\omega)$

a. We separate real & imaginary since $\Phi(t)$ is real:

$$U(\omega) = \int_0^{\infty} \Phi(t) \cos \omega t dt \quad \leftarrow \text{Cosine transform}$$

$$V(\omega) = \int_0^{\infty} \Phi(t) \sin \omega t dt \quad \leftarrow \text{Sine transform}$$

3. Inverse Cosine & Sine Transforms yield

a.
$$\begin{aligned} \Phi(t) &= \frac{2}{\pi} \int_0^{\infty} U(\omega) \cos \omega t d\omega \\ &= -\frac{2}{\pi} \int_0^{\infty} V(\omega) \sin \omega t d\omega \end{aligned} \quad \text{for } t > 0$$

b. Thus, $\int_0^{\infty} U(\omega) \cos \omega t d\omega = -\int_0^{\infty} V(\omega) \sin \omega t d\omega, \quad t > 0$

Requirements for Causality & Reality lead to an interdependence of real & imaginary parts of transfer function $\Phi(\omega)$

III. Discrete Fourier Transforms

A. Motivation

1. Using a Fourier space representation for numerical simulation, we must use Fourier transforms on a discrete set of points.
2. Thus, we need to explore properties of Discrete Fourier Transforms

B. Orthogonality

1. Need to explore orthogonality for a discrete set of points.
 $\Rightarrow \sin, \cos, e^{i\omega t}$ are orthogonal on discrete set of uniformly spaced points!

III. B. (Continued)

Haves (?)

2. Choose

$$x_k = \frac{2\pi k}{N}, \quad k=0, 1, 2, \dots, N-1$$

3. Define $\phi_p(x_k) = e^{ipx_k}$ defined only on points x_k !

4. Scalar Product: Discrete version is sum of products

$$\langle \phi_p | \phi_q \rangle \equiv \sum_{k=0}^{N-1} \phi_p^*(x_k) \phi_q(x_k)$$

5. Substituting for $\phi_p(x_k)$, etc.

a. $\langle \phi_p | \phi_q \rangle = \sum_{k=0}^{N-1} e^{i2\pi k(q-p)/N} = \sum_{k=0}^{N-1} r^k$ where $r = e^{i2\pi(q-p)/N}$

b. Finite Geometric Series: $\langle \phi_p | \phi_q \rangle = \sum_{k=0}^{N-1} r^k = \frac{1-r^N}{1-r}$

c. But, since p and q are integer values, $q-p$ is an integer, and $r^N = \left[e^{i2\pi(q-p)/N} \right]^N = e^{i2\pi(q-p)} = 1$ for any integer $(q-p) \neq 0$

d. If $q-p = nN$, then $r=1$, so $\langle \phi_p | \phi_q \rangle = \sum_{k=0}^{N-1} 1^k = N$.
any integer multiple of N .

e. But, since ϕ_p is defined on N points, only N functions can be linearly independent. \Rightarrow Restrict $0 \leq p, q \leq N-1$.

2. Final Result:

$$\langle \phi_p | \phi_q \rangle = N \delta_{pq} \quad \text{for } 0 \leq p, q, N-1$$

Orthogonality Condition on discrete set of points.

C. Discrete Transforms: 1. Forward:

$$g_p = N^{-1/2} \sum_{k=0}^{N-1} e^{i2\pi k p / N} f_k$$

2. Inverse:

$$f_k = N^{-1/2} \sum_{p=0}^{N-1} e^{-i2\pi k p / N} g_p$$

III. C (Continued)

Hawes (P)

2. Physical space: $f_k \equiv f(x_k)$

Fourier Space: $g_p \equiv g(\omega_p)$

where $\omega_p \equiv \frac{2\pi p}{N}$, $0 \leq p \leq N-1$
 possible frequencies.

3. Verify:

$$f_k = N^{-1/2} \sum_{j=0}^{N-1} e^{-i2\pi k j / N} \left[N^{1/2} \sum_{j=0}^{N-1} e^{i2\pi j p / N} g_j \right] = N^{-1/2} \sum_{j=0}^{N-1} \underbrace{e^{-i2\pi j (k-p) / N}}_{=\delta_{jk}} f_j$$

$$= N^{-1} \sum_{j=0}^{N-1} \delta_{jk} f_j = \frac{N}{N} f_k = f_k \quad \checkmark$$

4. Properties: Similar to continuous Fourier Transform

a. Ext. Translation $[f_{k-j}]_p^T = e^{i2\pi j p / N} g_p$ Translation by j discrete steps.

5. Discrete Convolution Theorem: $[f * g]_p^T = F_p G_p$

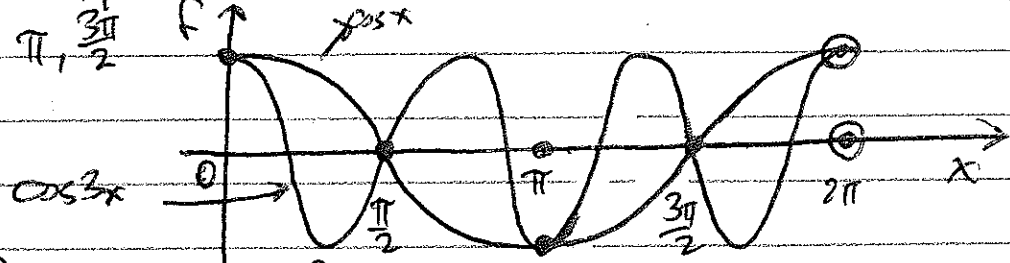
6. Transformation Matrix: Unitary $N \times N$ matrix!

7. Aliasing:

a. On a discrete set of points, higher frequency modes can be mistaken for modes at a lower (resolved) frequency.

b. Consider $f_1(x) = \cos x$ and $f_2(x) = \cos 3x$ on $N=4$ points.

c. $x_k = 0, \frac{\pi}{2}, \pi, \frac{3\pi}{2}$



d. Both $f_1(x) = \cos x$ and $f_2(x) = \cos 3x$ have exactly the same values at all $x_k \Rightarrow$ Cannot be distinguished on $N=4$ points.

e. Any contribution from $f_2(x) = \cos 3x$ will be mistakenly interpreted as due to $f_1(x) = \cos x \Rightarrow$ Power is aliased into resolved frequency range!

8. Fast Fourier Transforms: Cooley & Tukey, Meth. Comput. 19.27 (1965)

a. Efficient routine reduces cost from N^2 to $\frac{N}{2} \log_2 N$. For $N=1024$, saves a factor of $\sim 200!$