

# Lecture #19: Laplace Transforms: More Properties and Convolution Theorem

## I. Laplace Transforms: More Properties

### A. Translation:

1. Consider a time signal  $f(t)$  with Laplace Transform  $F(s) = \mathcal{L}\{f(t)\}$

2. Now, what happens if we multiply by  $e^{-bs}$ ?

a.  $e^{-bs} F(s) = e^{-bs} \int_0^{\infty} dt e^{-st} f(t) = \int_0^{\infty} dt f(t) e^{-s(t+b)}$

b. Change variable  $\tau = t+b \Rightarrow t = \tau - b$

$$e^{-bs} F(s) = \int_b^{\infty} d\tau f(\tau - b) e^{-s\tau}$$

c. But, we assume  $f(t) = 0$  for  $t < 0$ , so

$$\int_b^{\infty} d\tau f(\tau - b) e^{-s\tau} = \int_0^{\infty} d\tau f(\tau - b) e^{-s\tau}$$

d. Thus  $e^{-bs} F(s) = \mathcal{L}\{f(\tau - b)\}$  Translation of argument

3. Instead of relying on  $f(t) = 0$  for  $t < 0$ , insert Heaviside function,  $U(\tau - b) = \begin{cases} 1 & \tau > b \\ 0 & \tau < b \end{cases}$

$$e^{-bs} F(s) = \int_0^{\infty} d\tau e^{-s\tau} f(\tau - b) U(\tau - b) \leftarrow \text{Heaviside Shifting Theorem}$$

### 4. Example: Electromagnetic Waves

a. For an electromagnetic wave ( $E_y$  or  $E_z \rightarrow E$ ) propagating in  $x$ -direction,

$$\frac{\partial^2 E(x,t)}{\partial x^2} - \frac{1}{v^2} \frac{\partial^2 E(x,t)}{\partial t^2} = 0$$

b. Source: At  $x=0$ ,  $E_s(0,t)$  is given

c. Initial Conditions:  $E(x,0) = 0 \quad \left. \frac{\partial E(x,t)}{\partial t} \right|_{t=0} = 0$

# IA. 4. (Continued)

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d. Assume wave propagates in +x direction

e. Performing Laplace transform in time!

$$\frac{\partial^2}{\partial x^2} \mathcal{L}\{E(x,t)\} - \frac{s^2}{v^2} \mathcal{L}\{E(x,t)\} + \frac{s}{v^2} E(x,0) + \frac{1}{v^2} \left. \frac{\partial E(x,t)}{\partial t} \right|_{t=0} = 0$$

d.  $\frac{\partial^2}{\partial x^2} \mathcal{L}\{E(x,t)\} = \frac{s^2}{v^2} \mathcal{L}\{E(x,t)\}$

e. General Solution:  $\mathcal{L}\{E(x,t)\} = F_1(s) e^{-\frac{s}{v}x} + F_2(s) e^{+\frac{s}{v}x}$   
 corresponds to different propagation directions!

f. Let  $F_2(s) = 0$ , so  $\mathcal{L}\{E(x,t)\} = F_1(s) e^{-\frac{s}{v}x}$

g. By translation property  $\mathcal{L}\{F_1(s) e^{-\frac{s}{v}x}\} = E(x, t - \frac{x}{v})$

i. At  $x=0$ ,  $\mathcal{L}\{F_1(s)\} = E(0,t) = E_s(0,t)$

ii. So,  $F_1(s) = \mathcal{L}\{E_s(0,t)\} \leftarrow$  Known source at  $x=0!$

iii. Thus  $E(x, t - \frac{x}{v}) = E_s(0, t - \frac{x}{v})$   
 $\leftarrow$  translated time!

b. Solution:

$$E(x,t) = \begin{cases} E(0, t - \frac{x}{v}) & + z \frac{x}{v} \\ 0 & + < \frac{x}{v} \end{cases}$$

$\leftarrow$  At  $x > vt$ , signal has not yet reached position  $x!$

Waveform of  $E(0,t)$  moving with velocity  $v$  at position  $x=vt!$

i. If  $F_2(s) \neq 0$ , will have component moving at velocity  $-v$   
 $\Rightarrow$  inconsistent with specified condition (d) above!

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### B. Derivative of a Laplace Transform

1. If  $F(s) = \int_0^{\infty} e^{-st} f(t) dt$  is uniformly convergent,

we may differentiate  $F(s)$  with respect to  $s$ ,

a.  $F'(s) = \frac{\partial}{\partial s} \left[ \int_0^{\infty} e^{-st} f(t) dt \right] = \int_0^{\infty} \frac{\partial}{\partial s} [e^{-st} f(t)] dt = \int_0^{\infty} e^{-st} [-t f(t)] dt$

b. Thus  $F^{(n)}(s) = \mathcal{L} \{ (-t)^n f(t) \}$

2. Technique can be used to derive new Laplace Transforms.

a. Consider  $f(t) = e^{kt}$ ,  $F(s) = \int_0^{\infty} e^{-st} e^{kt} dt$  (requires  $s > k$  for convergence!)

b.  $F(s) = \frac{1}{s-k}$

c.  $F'(s) = \int_0^{\infty} e^{-st} [-t e^{kt}] dt = \frac{-1}{(s-k)^2} \Rightarrow \mathcal{L} \{ t e^{kt} \} = \frac{1}{(s-k)^2}, s > k$

### C. Integration of a Laplace Transform

1. Again, assume  $F(s) = \int_0^{\infty} e^{-st} f(t) dt$  is uniformly convergent.

2. Now  $\int_s^{\infty} F(x) dx = \int_s^{\infty} dx \int_0^{\infty} e^{-xt} f(t) dt = \int_0^{\infty} dt \left[ \int_s^{\infty} e^{-xt} dx \right] f(t)$

a. NOTE:  $F(\infty) = 0$  due to factor  $e^{-st}$  in integral!

$$\int_s^{\infty} \frac{e^{-xt}}{t} dx = \left[ \frac{e^{-xt}}{-t} \right]_s^{\infty} = \frac{e^{-st}}{t}$$

$$= \int_0^{\infty} e^{-st} \left[ \frac{f(t)}{t} \right] dt$$

3. Thus  $\int_s^{\infty} F(x) dx = \mathcal{L} \left\{ \frac{f(t)}{t} \right\}$

## I. C. (Continued)

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4. NOTE: The limit of the integral  $s$  (the transform variable) must be chosen large enough that Laplace transform converges.

5. Also, either  $\frac{f(t)}{t}$  must be finite at  $t=0$ , or diverge less strongly than  $t^{-1}$ .

## II. Laplace Convolution Theorem

### A. Definition

1. Consider two functions  $f_1(t)$  and  $f_2(t)$  with Laplace transforms  $F_1(s) = \mathcal{L}\{f_1(t)\}$  and  $F_2(s) = \mathcal{L}\{f_2(t)\}$

2. Multiply transforms

$$a. F_1(s)F_2(s) = \left[ \int_0^{\infty} e^{-sx} f_1(x) dx \right] \left[ \int_0^{\infty} e^{-sy} f_2(y) dy \right]$$

Same transform  
variable  $s$

$$= \int_0^{\infty} \int_0^{\infty} e^{-s(x+y)} f_1(x) f_2(y) dx dy$$

b. Change variable:  $t = x+y \rightarrow x = t-y$  and  $dx = dt$   
 $u = y \quad \quad \quad = t-u$

i.  $(x, y) \rightarrow (t, u)$

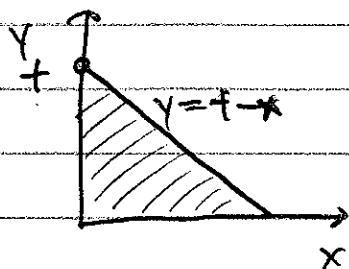
ii. Jacobian  $J = \frac{\partial(x, y)}{\partial(t, u)}$  where  $dx dy = J dt du$

$$iii. J = \begin{vmatrix} \frac{\partial x}{\partial t} & \frac{\partial x}{\partial u} \\ \frac{\partial y}{\partial t} & \frac{\partial y}{\partial u} \end{vmatrix} = \begin{vmatrix} 1 & 0 \\ -1 & 1 \end{vmatrix} = 1 \Rightarrow dx dy = dt du$$

## II. A2, (Continued)

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### iv. Limits of integration



a. Choose  $\int_0^\infty dt$

b. What range of values is covered by  $\int dy$ ?

i. since  $x \geq 0$ , and  $x = t - y$

$$\Rightarrow \int_0^+ dy$$

c. Thus  $\int_0^\infty dx \int_0^\infty dy = \int_0^\infty dt \int_0^+ dy$

c. Thus

$$F_1(s)F_2(s) = \int_0^\infty e^{-st} \left[ \int_0^+ f_1(t-y) f_2(y) dy \right] dt$$

$$F_1(s)F_2(s) = \mathcal{L} \left\{ \int_0^+ f_1(t-y) f_2(y) dy \right\} \equiv \mathcal{L} \{ f_1 * f_2 \}$$

3. Thus, Laplace Convolution

$$f_1 * f_2 \equiv \int_0^+ f_1(t-y) f_2(y) dy$$

4. Laplace Convolution can be used to:

a. Find new transforms

b. Use as an alternative to partial fraction expansion

## B. Ex: Driven, Damped Oscillator

1. Consider a mass  $m$  on a spring ( $k$ ) with damping ( $b$ ) and driving  $f(t)$ ,

$$m x''(t) + b x'(t) + k x(t) = f(t) \quad \begin{array}{l} \text{driving} \\ \text{force applied to system!} \end{array}$$

2. Choose initial conditions:  $x(0) = 0$   
 $x'(0) = 0$

3. Laplace Transform

$$m s^2 X(s) + b s X(s) + k X(s) = F(s) \quad \text{where } F(s) = \mathcal{L} \{ f(t) \}$$

Transform of driving.

## II. B. (Continued)

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4. Solving for  $X(s)$ :

$$X(s) = \frac{F(s)}{m} \frac{1}{\left(s + \frac{b}{2m}\right)^2 + \omega_1^2}$$

where  $\omega_1^2 = \omega_0^2 - \frac{b^2}{4m^2}$  and  $\omega_0^2 = \frac{k}{m}$

5. NOTE: Form of  $X(s)$  is a product of two Laplace Transforms!

a.  $\frac{F(s)}{m} = \mathcal{L}\left\{\frac{f(t)}{m}\right\}$

b. From (20.15B)  $\mathcal{L}\{e^{at} \sin kt\} = \frac{k}{(s-a)^2 + k^2}$ , so

$$\frac{1}{\omega_1} \frac{\omega_1}{\left(s + \frac{b}{2m}\right)^2 + \omega_1^2} = \mathcal{L}\left\{\frac{1}{\omega_1} e^{-\frac{bt}{2m}} \sin \omega_1 t\right\}$$

6. Use Laplace Convolution Theorem to obtain solution in integral form:

$$x(t) = \mathcal{L}^{-1}\{X(s)\} = \frac{1}{m\omega_1} \int_0^t f(t-y) e^{-\frac{by}{2m}} \sin \omega_1 y \, dy$$

a. NOTE: This form is valid for an arbitrary choice of driving force  $f(t)$ !

7. Choose particular forcing  $f(t)$ :

a.  $f(t) = P\delta(t)$ , where  $P$  is momentum imparted by impulse at  $t=0$ .

b.  $x(t) = \frac{1}{m\omega_1} \int_0^t P\delta(t-y) e^{-\frac{by}{2m}} \sin \omega_1 y \, dy = \frac{P}{m\omega_1} e^{-\frac{bt}{2m}} \sin \omega_1 t = x(t)$