

I. Review

A. Calculation of Linear Dispersion Relation

1. Linearize System of Equations (e.g., assume $\rho = \rho_0 + \epsilon \rho_1$ where $\epsilon \ll 1$)
2. Fourier Analysis: Find plane wave solutions $\sim e^{i(\underline{k} \cdot \underline{x} - \omega t)}$
3. Write system of equations as matrix equation
 \Rightarrow Solve Determinant = 0 \Rightarrow yield $\omega = \omega(\underline{k})$.

B. We left off with the following system

- ① $\omega \rho_1 = \rho_0 (\underline{k} \cdot \underline{U}_1)$
- ② $\omega \underline{U}_1 = \underline{k} \left(\frac{\rho_1}{\rho_0} + \frac{\underline{B}_0 \cdot \underline{B}_1}{\mu_0 \rho_0} \right) - \frac{(\underline{B}_0 \cdot \underline{k}) \underline{B}_1}{\mu_0 \rho_0}$ (Note missing term in previous notes)
- ③ $\omega \underline{B}_1 = \underline{B}_0 (\underline{k} \cdot \underline{U}_1) - (\underline{B}_0 \cdot \underline{k}) \underline{U}_1$
- ④ $\omega \rho_1 = \gamma \rho_0 (\underline{k} \cdot \underline{U}_1)$

II. The MHD Dispersion Relation (Continued)

A. Let's simplify these equations

1. Eliminate ρ_1 from ② using ④

$$\textcircled{2} \Rightarrow \textcircled{2a} \quad \omega^2 \underline{U}_1 = \underline{k} \left(\frac{[\gamma \rho_0 (\underline{k} \cdot \underline{U}_1)]}{\rho_0} + \frac{\underline{B}_0 \cdot [\omega \underline{B}_1]}{\mu_0 \rho_0} \right) - \frac{(\underline{B}_0 \cdot \underline{k}) [\omega \underline{B}_1]}{\mu_0 \rho_0}$$

2. Now, use ③ to substitute for $\omega \underline{B}_1$ in ②a

$$\textcircled{2a} \Rightarrow \textcircled{2b} \quad \omega^2 \underline{U}_1 = \underline{k} \frac{\gamma \rho_0 (\underline{k} \cdot \underline{U}_1)}{\rho_0} + \underline{k} \frac{\underline{B}_0 \cdot \underline{B}_0 (\underline{k} \cdot \underline{U}_1)}{\mu_0 \rho_0} - \underline{k} \frac{(\underline{B}_0 \cdot \underline{U}_1) (\underline{B}_0 \cdot \underline{k})}{\mu_0 \rho_0} \\ - \frac{(\underline{B}_0 \cdot \underline{k}) (\underline{k} \cdot \underline{U}_1) \underline{B}_0}{\mu_0 \rho_0} + \frac{(\underline{B}_0 \cdot \underline{k})^2 \underline{U}_1}{\mu_0 \rho_0}$$

3. Use $\underline{B}_0 = B_0 \hat{b}$ to simplify further:

$$\omega^2 \underline{U}_1 = \underline{k} (\underline{k} \cdot \underline{U}_1) \left[\frac{\gamma \rho_0}{\rho_0} + \frac{B_0^2}{\mu_0 \rho_0} \right] - \underline{k} \frac{(\hat{b} \cdot \underline{U}_1) (\hat{b} \cdot \underline{k}) B_0^2}{\mu_0 \rho_0} - \frac{B_0^2 (\hat{b} \cdot \underline{k}) (\underline{k} \cdot \underline{U}_1) \hat{b}}{\mu_0 \rho_0} \\ + \frac{B_0^2 (\hat{b} \cdot \underline{k})^2 \underline{U}_1}{\mu_0 \rho_0}$$

Lecture #18 (Continued)

II. A. (Continued)

4. Defn: DEF: Sound Speed $c_s^2 = \frac{\delta p_0}{\rho_0}$

Alfven Speed $v_A^2 = \frac{B_0^2}{\mu_0 \rho_0}$

5.

$$\omega^2 \underline{U}_1 = (c_s^2 + v_A^2) \underline{k} (\underline{k} \cdot \underline{U}_1) - v_A^2 (\hat{b} \cdot \underline{U}_1) (\hat{b} \cdot \underline{k}) \underline{k} - v_A^2 (\hat{b} \cdot \underline{k}) (\underline{k} \cdot \underline{U}_1) \hat{b} + v_A^2 (\hat{b} \cdot \underline{k})^2 \underline{U}_1$$

a. Thus, we have reached a single (vector) equation for \underline{U}_1 .

b. NOTE: Once we have solved for \underline{U}_1 , ρ_1 is determined by \underline{U}_1 using equation (D).

c. This vector equation represent 3 component equations. Thus, we can simplify to a matrix form:

$$\begin{pmatrix} 3 \times 3 \text{ matrix.} \end{pmatrix} \begin{pmatrix} U_x \\ U_y \\ U_z \end{pmatrix} = 0$$

But, first, we'll explore the solutions in simplified limits.

B. MHD Waves for $\underline{k} = k_{||} \hat{b}$ (Parallel wave vector $\underline{k} \parallel B_0$)

1. In this case, we can simplify: $(\underline{k} \cdot \underline{U}_1) = k_{||} U_z$

$$\hat{b} \cdot \underline{U}_1 = U_z$$

$$\hat{b} \cdot \underline{k} = k_{||}$$

where we take $\hat{b} = \hat{z}$ and $\underline{U}_1 = U_x \hat{x} + U_y \hat{y} + U_z \hat{z}$.

2. Thus,

$$\omega^2 \underline{U}_1 = (c_s^2 + v_A^2) k_{||}^2 U_z \hat{b} - v_A^2 k_{||}^2 U_z \hat{b} - v_A^2 k_{||}^2 U_z \hat{b} + k_{||}^2 v_A^2 \underline{U}_1$$

II. B. (Continued)

3. Splitting into components and putting into matrix form

$$\begin{pmatrix} \omega^2 - k_{||}^2 v_A^2 & 0 & 0 \\ 0 & \omega^2 - k_{||}^2 v_A^2 & 0 \\ 0 & 0 & \omega^2 - k_{||}^2 c_s^2 \end{pmatrix} \begin{pmatrix} U_x \\ U_y \\ U_z \end{pmatrix} = 0$$

4. The determinant $D=0$ is dispersion relation:

$$\boxed{(\omega^2 - k_{||}^2 v_A^2)^2 (\omega^2 - k_{||}^2 c_s^2) = 0}$$

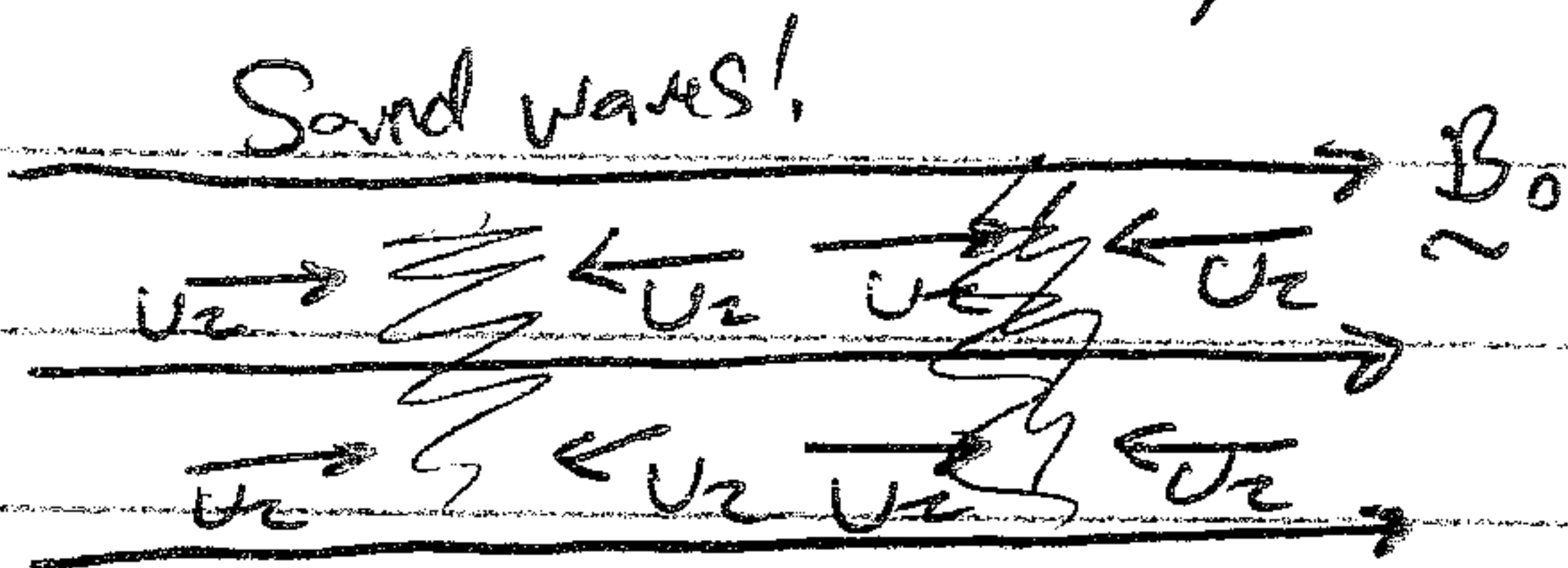
5. There are six solutions to this equation:

a. $\omega = \pm k_{||} v_A$] $\times 2$, one for $U_x \neq 0, U_y = 0$,
another for $U_x = 0, U_y \neq 0$.

b. $\omega = \pm k_{||} c_s$

6. Parallel Motions: Sand Waves

a. If we have $U_z \neq 0$, then $\omega = \pm k_{||} c_s$



b. These are the usual sand waves motion along B_0 .

at sound speed $c_s = \sqrt{\frac{\partial p_0}{\partial \rho_0}}$

c. Since $U_z = U_{z0} e^{i(k_{||}x - \omega t)} = U_{z0} e^{i k_{||}(z \pm c_s t)}$

d. B is unperturbed by motion along B_0 .

e. In this limit of $\underline{k} = k_{||} \hat{b}$, the relevant equations are

\hat{z} -component of Momentum eq: $\rho_0 \frac{\partial U_z}{\partial t} = -\frac{\partial p_1}{\partial x}$

Pressure equation: $\frac{\partial p_1}{\partial t} = -\gamma p_0 \frac{\partial U_z}{\partial z}$

Parallel motion U_z leads to compression
Pressure p_1 acts as restoring force } the usual sand wave!

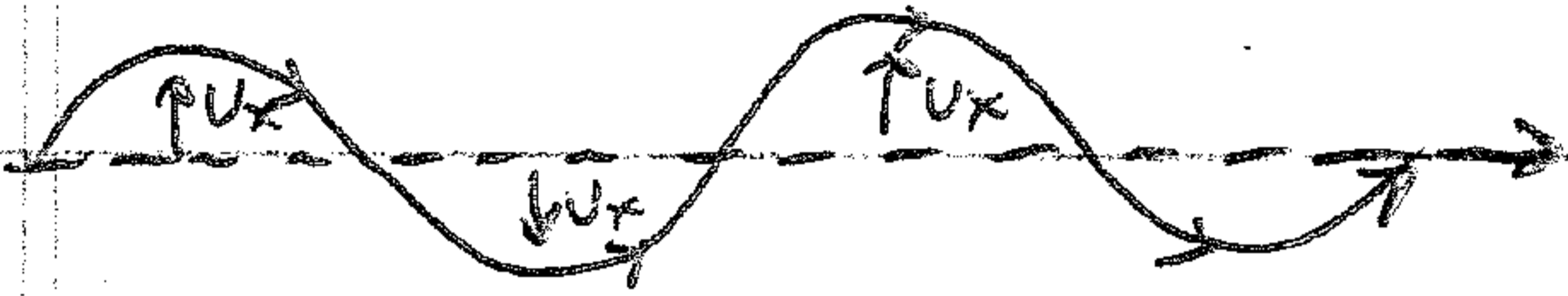
Lecture #18 (Continued)

Alfvén 4

II. B. (Continued)

Alfvén Waves

7. Perpendicular Motions: a. For $U_x \neq 0$, we must have $\omega = \pm k_{\perp} V_A$



Alfvén Speed.

$$V_A = \frac{B_0}{\sqrt{\mu_0 \rho_0}}$$

b. Alfvén waves are like waves on a string, propagating at

c. Relevant equations:

\hat{x} -component of Momentum Eq:

$$\rho_0 \frac{\partial U_x}{\partial t} = \frac{B_0}{\mu_0} \frac{\partial B_x}{\partial z}$$

\hat{z} -component of Induction Eq:

$$\frac{\partial B_x}{\partial t} = B_0 \frac{\partial U_x}{\partial z}$$

Magnetic Tension term.

Motion U_x is perpendicular to B_0 , causing it to bend
Magnetic Tension acts as restoring force

d. Because $\underline{k} \cdot \underline{U}_1 = 0$, this motion is incompressible.

e. We could also have taken $U_y \neq 0$ with $U_x = 0$, and results are analogous. ~~True~~

Two polarizations of Alfvén Wave
in direction perpendicular to B_0

C. MHD Waves for $\underline{k} = \underline{k}_{\perp} = k_{\perp} \hat{x}$ (Perpendicular wavevector $k_{\perp} \perp B_0$)

1. In this case $(\underline{k} \cdot \underline{U}_1) = k_{\perp} U_x$

$$(\hat{b} \cdot \underline{U}_1) = U_z$$

$$(\hat{b} \cdot \underline{k}) = 0$$

2. Thus $\omega^2 \underline{U}_1 = (c_s^2 + v_A^2) k_{\perp}^2 U_x \hat{x} + 0$

II. C. (Continued)

3. Splitting into Component Form:

$$\begin{pmatrix} \omega^2 - k_L^2(c_s^2 + v_A^2) & 0 & 0 \\ 0 & \omega^2 & 0 \\ 0 & 0 & \omega^2 \end{pmatrix} \begin{pmatrix} U_x \\ U_y \\ U_z \end{pmatrix} = 0$$

4. The determinant $\Delta = 0$ gives

$$\omega^4 [\omega^2 - k_L^2(c_s^2 + v_A^2)] = 0$$

5. Again, we have six solutions:

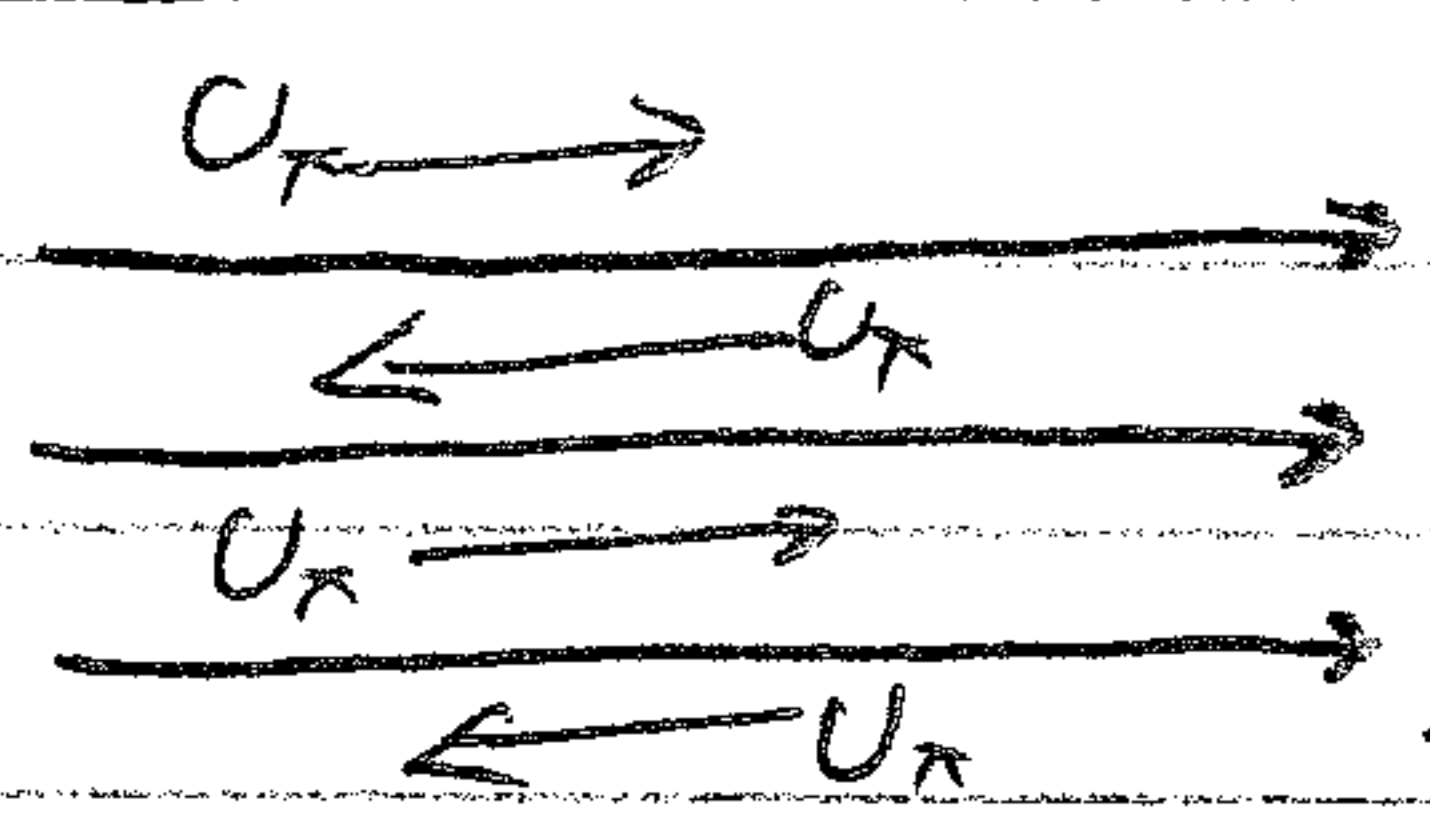
a. For solutions with $\omega \neq 0$

For $U_y \neq 0$ or $U_z \neq 0$.

b. Two solutions with $\omega = \pm k_L (c_s^2 + v_A^2)^{1/2}$ $U_x \neq 0$

6. Zero Frequency Solutions:

a. For $U_z \neq 0$,

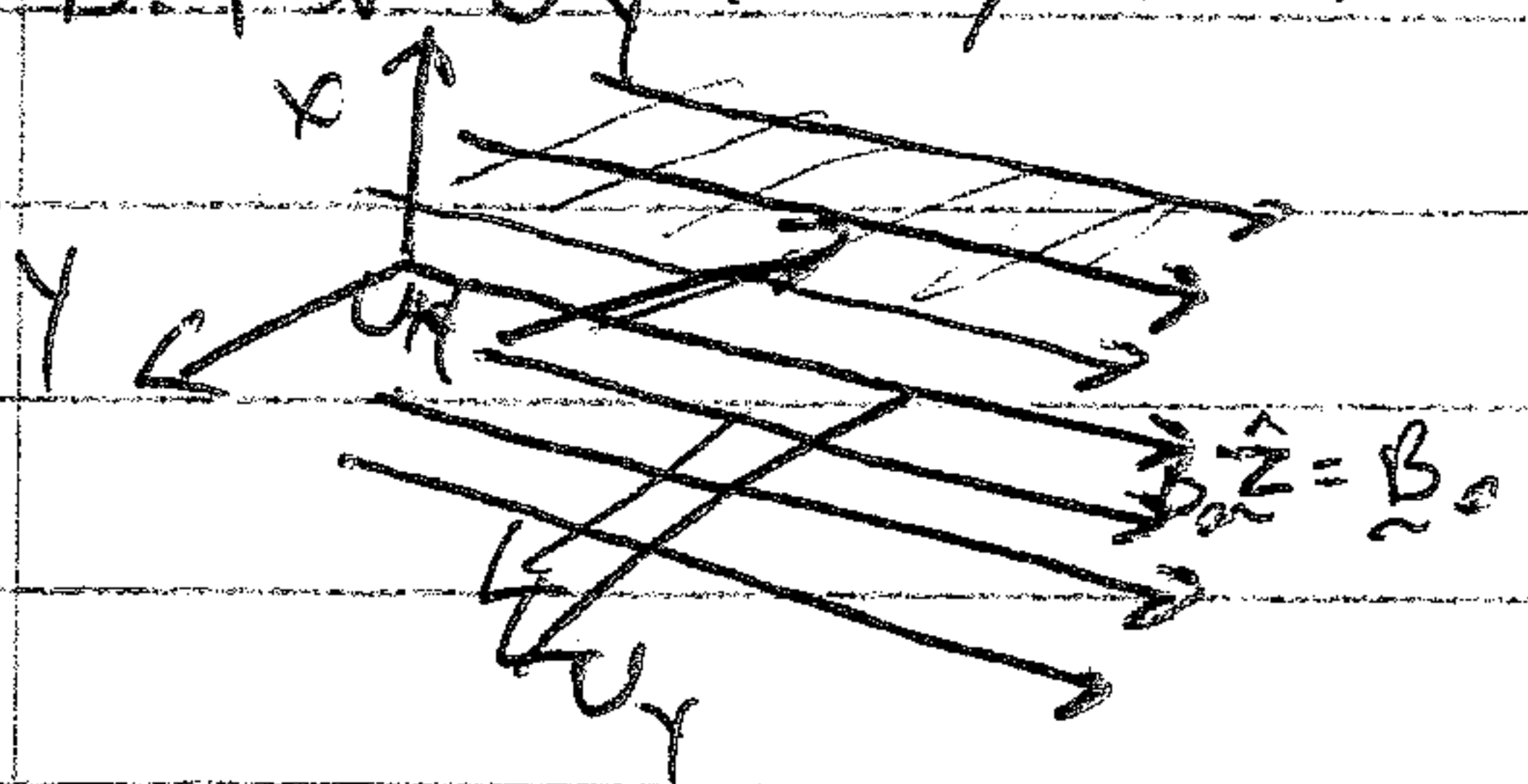


i. These are like sound waves (motion along field)

ii. BUT, $\tilde{k} \cdot \tilde{U} = 0$, so

no compression, and thus no restoring force.

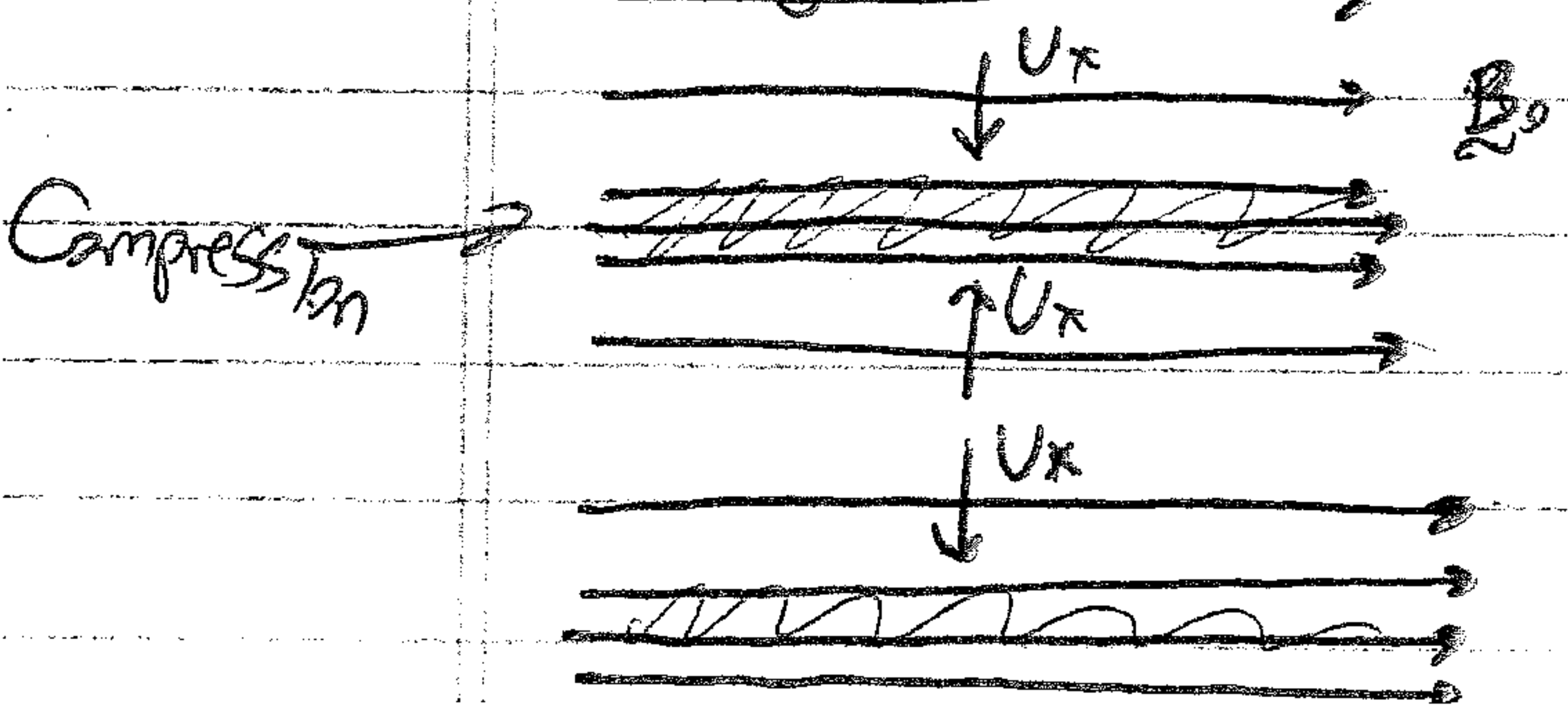
b. For $U_y \neq 0$, Motion is in $\hat{y} = \tilde{B}_0 \times \tilde{k}_L$ direction.



ii) Magnetic field lines may slide past one another. Again, no restoring force, so $\omega = 0$.

ii) This is called an interchange motion: It moves straight magnetic field lines with bending them.

7. Magneto-Acoustic (or Fast) Wave | $U_x \neq 0 \Rightarrow \omega = \pm k_L (c_s^2 + v_A^2)^{1/2}$



a. Motions are similar to compressional sound waves, but include a contribution from the magnetic pressure as well, propagating at ^{speed} $(c_s^2 + v_A^2)^{1/2}$.

Lecture #18 (Continued)
 II.C (Continued)

Hawes 6

b. Relevant Equations:

\hat{x} -component of Momentum Eq.

$$\rho_0 \frac{\partial U_x}{\partial t} = - \frac{\partial}{\partial x} \left(P_1 + \frac{B_z}{\mu_0} B_z \right)$$

Thermal Pressure
↓
Magnetic Pressure
↓

\hat{z} -component of Induction Eq.

$$\frac{\partial B_z}{\partial t} = -B_0 \frac{\partial U_x}{\partial x}$$

Pressure Equation

$$\frac{\partial P_1}{\partial t} = -\gamma p_0 \frac{\partial U_x}{\partial x}$$

c. $\underline{k} \cdot \underline{U}_1 = k_{\perp} U_x \neq 0$, so these waves are compressional.

d. Perpendicular motion U_x compresses both plasma and magnetic field
 Restoring force includes both thermal pressure P_1
 and magnetic pressure due to B_z .

e. NOTE! A fluctuation with only $B_z \neq 0$ has $\underline{B} = (B_0 + B_z) \hat{z}$.
 Magnetic field does not change direction
 but does increase magnitude.

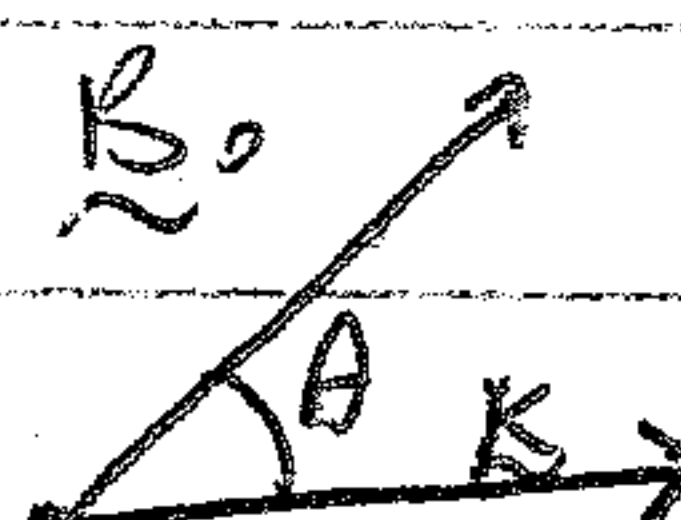
D. The General Case of MHD Dispersion Relation

1. We can solve the MHD Dispersion Relation for any wavevector \underline{k} .

a. With out loss of generality, we take

$$\underline{k} = k_{\perp} \hat{x} + k_{\parallel} \hat{z} = k \sin \theta \hat{x} + k \cos \theta \hat{z}$$

where $\underline{k} \cdot \hat{b} = k \cos \theta$



b. In general, then, $\underline{k} \cdot \underline{U}_1 = k \sin \theta U_x + k \cos \theta U_z$

$$\hat{b} \cdot \underline{k} = k \cos \theta$$

$$\underline{U}_1 \cdot \hat{b} = U_z$$

II.2 (Continued)

2. ~~The~~ After some algebra, the dispersion relation is found to be:

$$\left(\omega^2 - k^2 \cos^2 \theta V_A^2 \right) \left[\omega^4 - \omega^2 k^2 (c_s^2 + V_A^2) + k^4 \cos^2 \theta c_s^2 V_A^2 \right] = 0$$

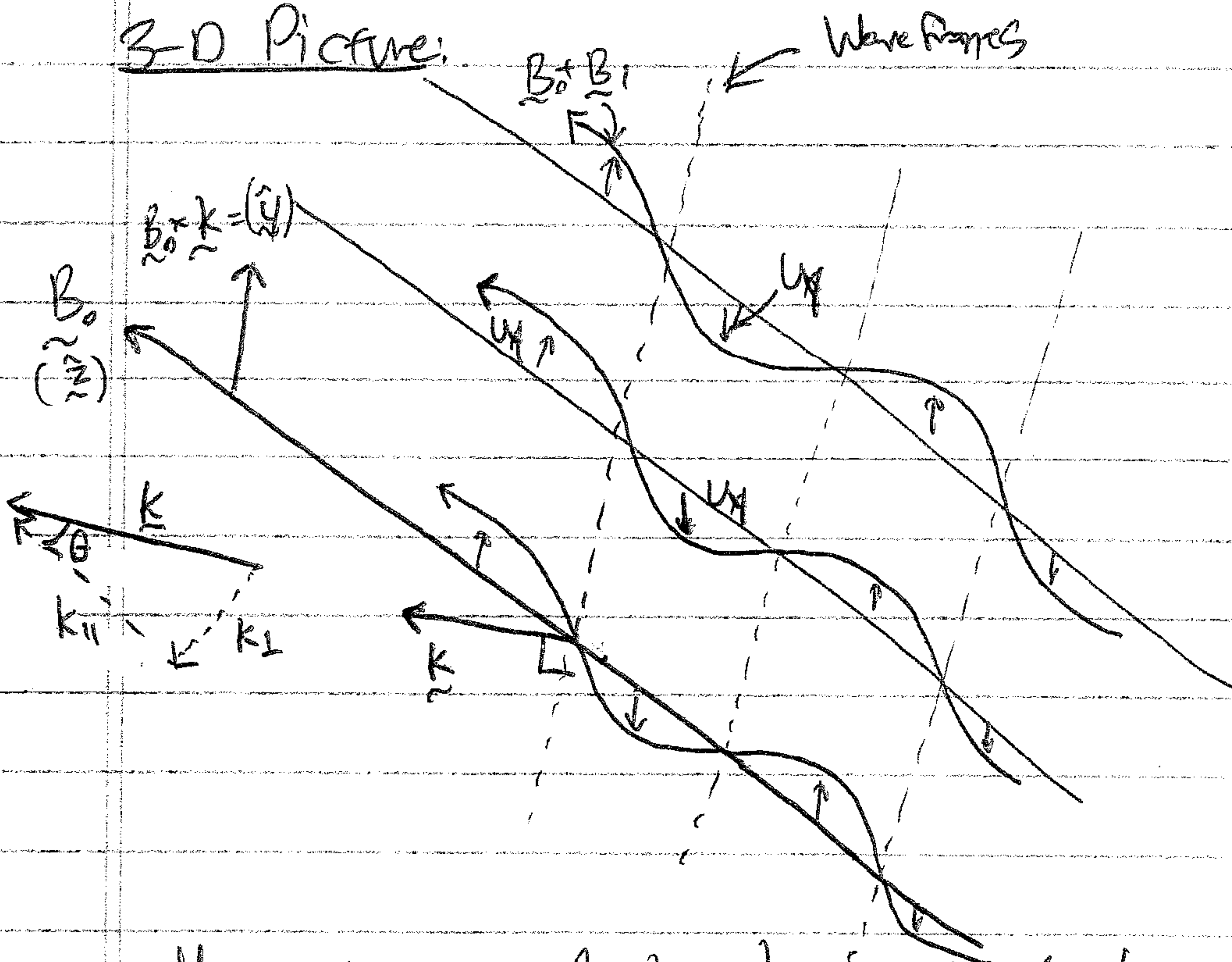
General MHD Dispersion Relation

3. Six Solutions: Three Waves, each with \oplus & \ominus .

4. Alfven Waves $\omega^2 = k^2 \cos^2 \theta V_A^2 \Rightarrow \omega^2 = k_{\parallel}^2 V_A^2$

a. Motion is in the $\hat{b} \times \hat{k}_{\perp}$ direction (\hat{y} direction)

3-D Picture:



Polarization b. Motion is out of the plane defined by \underline{B}_0 and \underline{k} .

c. Restoring force is only magnetic tension

d. $\underline{k} \cdot \underline{v}_1 = 0 \Rightarrow$ Alfvén wave is incompressible

Sometimes called the "Shear Alfvén Wave"

Lecture #18 (Continued)

III D. (Continued)

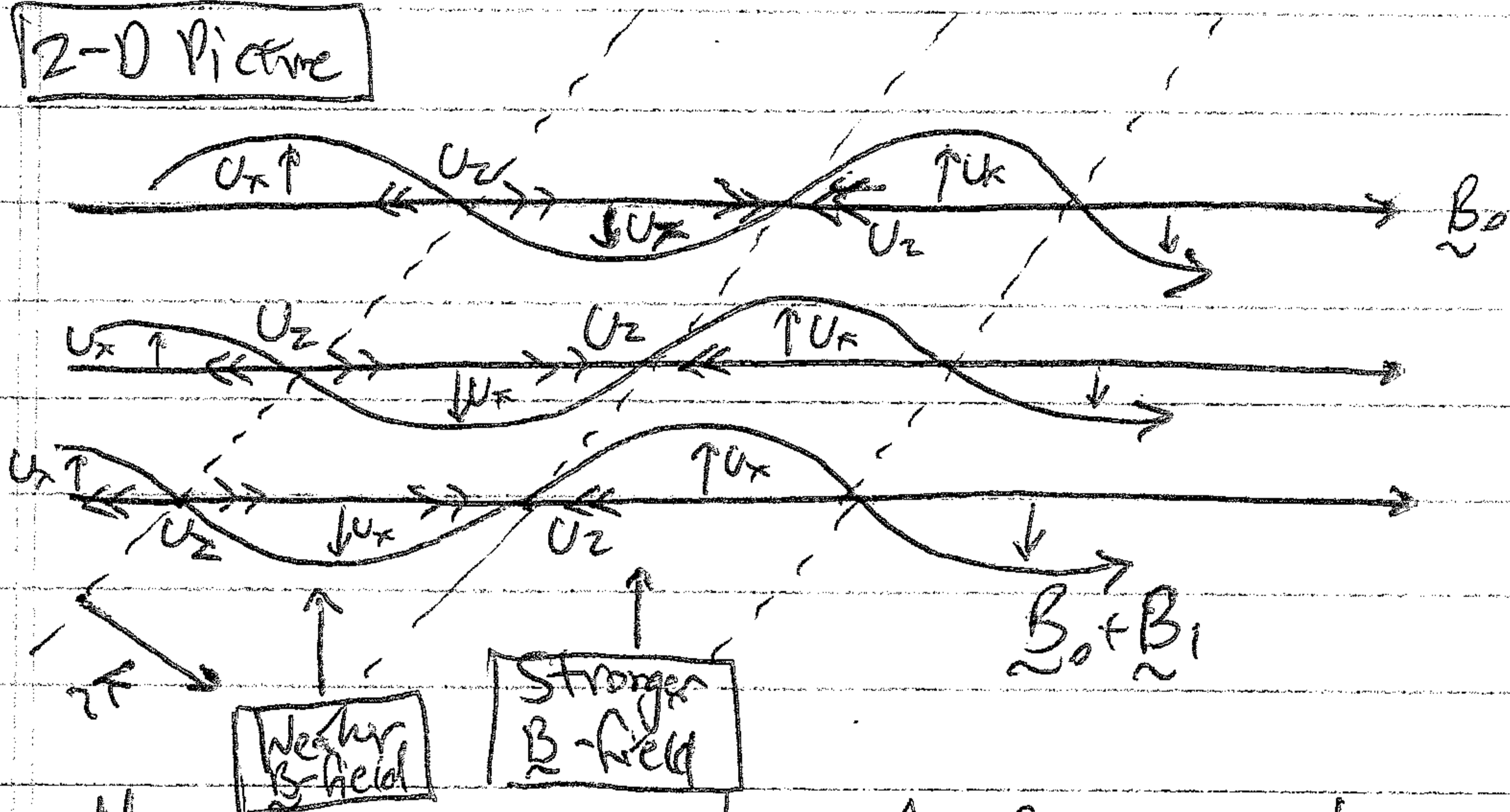
5. **Fast Waves**

phase speed $v_p = \frac{\omega}{k}$

Hoves 8

$$\frac{\omega^2}{k^2} = \frac{1}{2}(c_s^2 + v_A^2) + \frac{1}{2}\sqrt{(c_s^2 + v_A^2)^2 - 4c_s^2 v_A^2 \cos^2 \theta}$$

2-D Picture



Polarization a. Motion is in the plane of \underline{B}_0 and \underline{k}
 Has both $\hat{b} (= \hat{z})$ and $\underline{k}_\perp (= \hat{x})$ components U_z & U_x

b. This wave is a mixture of ^(parallel) Compressional wave and ^(perpendicular) transverse wave
 - Restoring forces: 1) Thermal and Magnetic pressure add together
 2) Bending of field lines - magnetic tension

c. Restoring force is strong because thermal & magnetic pressures add
 \Rightarrow Wave is fast.

d. For $\theta = 0$, $\omega^2 = \begin{cases} k^2 c_s^2 & c_s \gg v_A \text{ Sound Wave} \\ k^2 v_A^2 & v_A \gg c_s \text{ Alven Wave} \end{cases}$

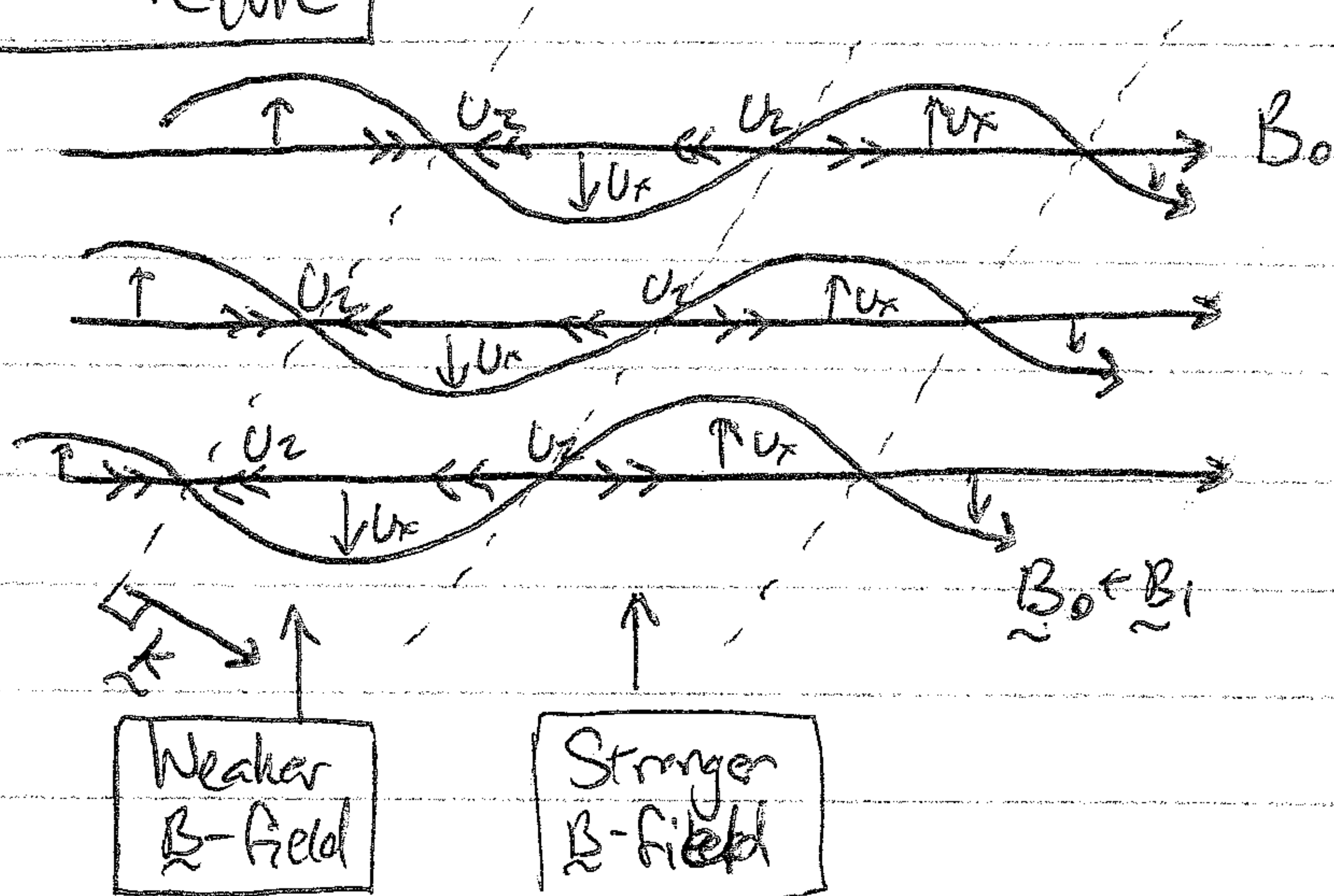
2. For $\theta = \frac{\pi}{2}$, $\omega^2 = k^2 (c_s^2 + v_A^2)$ Magneto-acoustic wave

III, D, (Continued)

G. Slow Waves

$$\frac{\omega^2}{k^2} = \frac{1}{2}(c_s^2 + v_A^2) - \frac{1}{2}\sqrt{(c_s^2 + v_A^2)^2 - 4c_s^2 v_A^2 \cos^2 \theta}$$

2-D Picture



Polarization a. Motion is in the plane of \underline{B}_0 & \underline{k}
 Has both $\underline{b}_{\parallel} (= \hat{z})$ and $\underline{k}_{\perp} (= \hat{x})$ components U_z & U_x

b. Wave is a mixture of compressional and transverse motions
 - Restoring force: 1) Thermal pressure and Magnetic pressure oppose (parallel)
 2) Magnetic tension due to bending of field lines (perpendicular)

c. Restoring force is weak because thermal and magnetic pressures subtract
 \Rightarrow Wave is slow

d. For $\theta=0$, $\omega^2 = \begin{cases} k^2 c_s^2 & c_s^2 < v_A^2 \text{ Sound wave} \\ k^2 v_A^2 & c_s^2 > v_A^2 \text{ Alfvén wave} \end{cases}$

e. For $\theta \rightarrow 0$ $\omega^2 \rightarrow 0$

Magnetic and thermal pressures subtract completely.