

Lecture #6: Particle Motion in Slowly Varying \underline{E} -fields Hamed D

Polarization Drift

I. Polarization Drift

A. Consider an Electric field varying slowly in time $\underline{E}(\tau)$ with a constant Magnetic field $\underline{B} = B_0 \hat{b}$.

B. Multiple Time Scale Analysis

$$1. \frac{d\underline{v}}{dt} = \frac{q}{m} (\underline{E} + \underline{v} \times \underline{B})$$

2. a. Take $\underline{E}(\tau)$ varies only on slow timescale $\tau = \epsilon t$

b. $\underline{v} = \underline{v}_1(t) + \epsilon \underline{v}_2(\tau) + \epsilon^2 \underline{v}_3(\tau) + \dots$

c. Also assume $\underline{E}(\tau) \cdot \underline{B} = 0$

3. As before,

$$\frac{d}{dt} = \frac{\partial}{\partial t} + \frac{\partial \tau}{\partial t} \frac{\partial}{\partial \tau} = \frac{\partial}{\partial t} + \epsilon \frac{\partial}{\partial \tau}$$

4. We'll take a small electric field such that the $\underline{E} \times \underline{B}$ drift velocity $v_E \ll v$, where v is Larmor orbit velocity.

Thus
$$\frac{d\underline{v}}{dt} = \frac{q}{m} (\epsilon \underline{E} + \underline{v} \times \underline{B})$$

5. Substitute expanded solution:

$$\frac{\partial}{\partial t} (\underline{v}_1 + \epsilon \underline{v}_2 + \epsilon^2 \underline{v}_3) + \epsilon \frac{\partial}{\partial \tau} (\underline{v}_1 + \epsilon \underline{v}_2 + \epsilon^2 \underline{v}_3) = \epsilon \frac{q}{m} \underline{E}(\tau) + \frac{q}{m} (\underline{v}_1 + \epsilon \underline{v}_2 + \epsilon^2 \underline{v}_3) \times \underline{B}$$

a. Taking $\underline{B} = B_0 \hat{b}$,

$$\frac{\partial \underline{v}_1}{\partial t} + \epsilon \frac{\partial \underline{v}_2}{\partial \tau} + \epsilon^2 \frac{\partial \underline{v}_3}{\partial \tau} = \epsilon \frac{q \underline{E}(\tau)}{m} + \omega_c \underline{v}_1 \times \hat{b} + \epsilon \omega_c \underline{v}_2 \times \hat{b} + \epsilon^2 \omega_c \underline{v}_3 \times \hat{b}$$

Lecture #16 (Continued)

Pages 2

I. B. (Continued)

6. $\mathcal{O}(1)$: $\frac{\partial \underline{v}_1}{\partial t} = \omega_c \underline{v}_1 \times \hat{b}$

- a. This is just the usual, fast timescale Larmor gyration about the magnetic field.
- b. The general solution for this motion can be written

$$\underline{v}_1 = v_1 \cos(\omega_c t + \phi) \hat{e}_1 - v_1 \sin(\omega_c t + \phi) \hat{e}_2 + v_{1||} \hat{b}$$

For a right-handed coordinate system s.t. $\hat{e}_1 \times \hat{e}_2 = \hat{b}$

7. $\mathcal{O}(\epsilon)$: $0 = \frac{q}{m} \underline{E}(\tau) + \epsilon \frac{q B_0}{m} \underline{v}_2 \times \hat{b}$

- a. This is just the slow timescale $\underline{E} \times \underline{B}$ drift.
- b. Operating $\hat{b} \times$ on equation gives:

$$\hat{b} \times \underline{E}(\tau) = \frac{q B_0}{m} \hat{b} \times (\underline{v}_2 \times \hat{b}) = \frac{q B_0}{m} (v_2 (\hat{b} \cdot \hat{b}) - v_{2||} \hat{b})$$

or

$$\underline{v}_2 = v_{2||} \hat{b} + \frac{\underline{E}(\tau) \times \hat{b}}{B_0}$$

8. $\mathcal{O}(\epsilon^2)$: $\frac{\partial \underline{v}_2}{\partial \tau} = \epsilon^2 \omega_c \underline{v}_3 \times \hat{b}$

- a. At this order, the solution \underline{v}_2 is considered to be known.

Thus, $\frac{\partial \underline{v}_2}{\partial \tau} = \frac{\partial v_{2||}}{\partial \tau} \hat{b} + \frac{1}{B_0^2} \frac{\partial \underline{E}}{\partial \tau} \times \hat{b} = \frac{\partial \underline{E}}{\partial \tau} \times \hat{b} / B_0$

- b. $\frac{1}{B_0} \frac{\partial \underline{E}}{\partial \tau} \times \hat{b} = \epsilon^2 \omega_c \underline{v}_3 \times \hat{b}$

- c. Take $\hat{b} \times$ this equation

$$\frac{1}{B_0} \hat{b} \times \left(\frac{\partial \underline{E}}{\partial \tau} \times \hat{b} \right) = -\frac{1}{B_0} \left[\frac{\partial \underline{E}}{\partial \tau} (\hat{b} \cdot \hat{b}) - \hat{b} \left(\hat{b} \cdot \frac{\partial \underline{E}}{\partial \tau} \right) \right] = \frac{1}{B_0} \frac{\partial \underline{E}}{\partial \tau}$$

$$\omega_c \hat{b} \times (\underline{v}_3 \times \hat{b}) = \omega_c [v_3 (\hat{b} \cdot \hat{b}) - \hat{b} (v_{3||} \hat{b})] = \omega_c (v_3 - v_{3||} \hat{b})$$

d. Thus $\underline{v}_3 = v_{3||} \hat{b} + \frac{1}{\omega_c B_0} \frac{\partial \underline{E}(\tau)}{\partial \tau}$

Lecture #16 (Continued)

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I.B. (Continued)

9. Putting the full solution together: (Taking $\tilde{v}_{21} = \tilde{v}_{31} = 0$)

$$\tilde{\mathbf{v}} = \underbrace{v_L (\cos(\omega_c t + \phi) \hat{e}_1 - \sin(\omega_c t + \phi) \hat{e}_2)}_{\text{Zeroth order Larmor Motion}} + \underbrace{\frac{\mathbf{E}(t) + \mathbf{B}}{B^2}}_{\text{First-order } \mathbf{E} \times \mathbf{B} \text{ drift}} + \underbrace{\frac{1}{\omega_c B_0} \frac{d\mathbf{E}}{dt}}_{\text{Second-order Polarization Drift}}$$

Zeroth order Larmor Motion

First-order $\mathbf{E} \times \mathbf{B}$ drift

Second-order Polarization Drift

C. Polarization Drift:

1. For slowly varying electric field $\mathbf{E}(t)$ (slow with respect to the Larmor motion), we define the

Polarization Drift

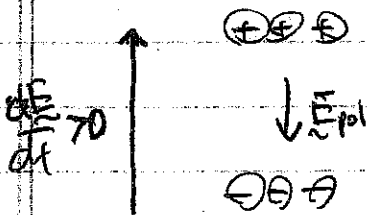
$$\tilde{\mathbf{v}}_p \equiv \frac{1}{\omega_c B} \frac{d\mathbf{E}}{dt}$$

2. Using $\omega_c = \frac{qB}{m}$, we have

$$\tilde{\mathbf{v}}_p = \frac{m}{q B^2} \frac{d\mathbf{E}}{dt}$$

a. Polarization drift is charge dependent.

\Rightarrow ions and electrons drift in opposite directions



b. Resulting polarization of plasma opposes increasing applied Electric field.

c. Because $m_i \gg m_e$, ions dominate the polarization drift.

3. Polarization Current: $\mathbf{j}_p = \sum_s q_s n_s \tilde{\mathbf{v}}_p = \sum_s \frac{q_s n_s m_s}{q_s B^2} \frac{d\mathbf{E}}{dt}$

a. $\tilde{\mathbf{v}}_p = \sum_s \frac{n_s m_s}{B^2} \frac{d\mathbf{E}}{dt}$

b. Mass dependence means ion contribute more to polarization current.

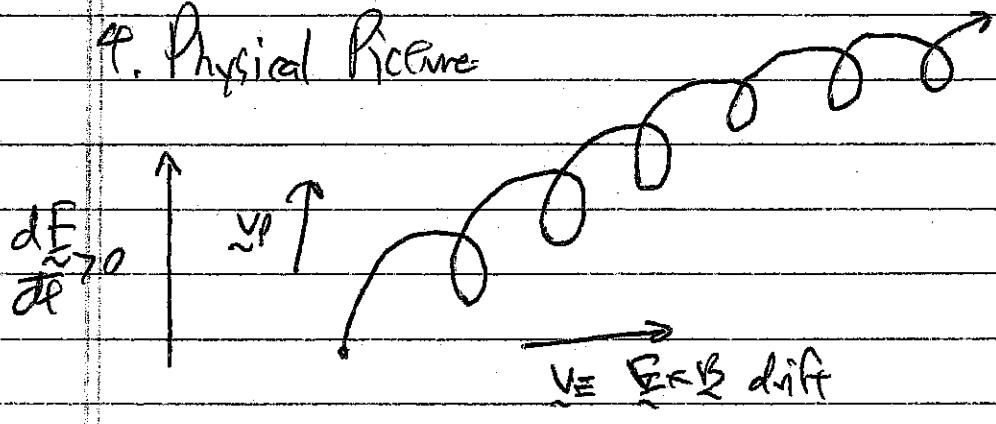
Lecture #16 (Continued)
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b. NOTE: $\underline{E} \times \underline{B}$ velocity is the same for both species, so it cancels, producing no net current.

$$\underline{j}_E = \sum_s q_s n_s \underline{v}_E = \sum_s q_s n_s \frac{\underline{E} \times \underline{B}}{B^2} = \frac{\underline{E} \times \underline{B}}{B^2} \sum_s q_s n_s = 0 \quad \text{by quasineutrality.}$$

4. Physical Picture



5. The Polarization Drift can lead to an increase in energy.

a. $\frac{d\varepsilon}{dt} = \underline{v} \cdot \underline{f} = \underline{v} \cdot q(\underline{E} + \underline{v} \times \underline{B}) = q \underline{v} \cdot \underline{E}$

b. $= q \left[v_{\perp} \cos(\omega_c t + \phi) \underline{E} \cdot \underline{e}_1 + v_{\perp} \sin(\omega_c t + \phi) \underline{E} \cdot \underline{e}_2 + \frac{\underline{E}(\underline{E} \times \underline{B}) \cdot \underline{E}}{B^2} + \frac{1}{\omega_c B} \frac{d\underline{E}}{dt} \cdot \underline{E} \right]$

Average over Larmor orbit $\Rightarrow 0$.

c. Thus $\frac{d\varepsilon}{dt} = \frac{q}{\omega_c B} \frac{d}{dt} \left(\frac{E^2}{2} \right) = \frac{d}{dt} \left[\frac{1}{2} m \left(\frac{E^2}{B^2} \right) \right]$

d. Note: $|\underline{v}_E|^2 = \frac{E^2}{B^2}$, so this can be written $\left[\frac{d}{dt} \left(\frac{1}{2} m v_E^2 \right) = \frac{d\varepsilon}{dt} \right]$

e. The Polarization Drift leads to the acceleration of particles to achieve the $\underline{E} \times \underline{B}$ drift velocity.