

Numerical Lecture #10: Kinetic Simulation: Vlasov-Poisson Plasmas

I. 1D-1V Vlasov-Poisson System

A. Equations

$$1. \quad \frac{\partial f_s}{\partial t} + v \frac{\partial f_s}{\partial x} - \frac{q_s}{m_s} \frac{\partial \phi}{\partial x} \frac{\partial f_s}{\partial v} = 0$$

Vlasov Equation for each species s

$$2. \quad \frac{\partial^2 \phi}{\partial x^2} = -4\pi \sum_s \int dv q_s f_s$$

Poisson Equation (cgs units)

B. Normalization:

$$1. \quad \hat{\phi} = \frac{q_e \phi}{T_e}$$

$$5. \quad v_{te}^2 = \frac{T_e}{m_e} \quad \begin{array}{l} \text{Temperature in units} \\ \text{of energy} \\ \text{(Boltzmann constant} \\ \text{absorbed)} \end{array}$$

$$2. \quad \hat{x} = x / \lambda_{de}$$

$$6. \quad \omega_{pe} = \frac{4\pi n_0 q_e^2}{m_e}$$

$$3. \quad \hat{t} = t \omega_{pe}$$

$$7. \quad \lambda_{de}^2 = \frac{T_e}{4\pi n_0 q_e^2}$$

4. Species dependant:

$$a. \quad \hat{v}_s = \frac{v}{v_{ts}}$$

$$8. \text{Relation: } v_{te} = \lambda_{de} \omega_{pe}$$

$$b. \quad \hat{f}_s = \frac{f_s}{f_{s0}} \quad \left(\frac{n_0}{v_{ts}} \right)$$

$$9. \quad q_e = -q_i \quad \left. \begin{array}{l} \\ \\ \end{array} \right\} \text{Quasi-neutral}$$

Maxwellian equilibrium

$$c. \quad f_{s0} = \frac{n_0}{(2\pi)^{1/2} v_{ts}} e^{-\frac{v^2}{2v_{ts}^2}}$$

$$10. \quad n_{oe} = n_{oi} = n_0$$

II. Normalized Vlasov Equations:

$$a. \text{ Electrons: } \frac{\partial \hat{f}_e}{\partial \hat{t}} + \hat{v}_e \frac{\partial \hat{f}_e}{\partial \hat{x}} - \frac{\partial \hat{\phi}}{\partial \hat{x}} \frac{\partial \hat{f}_e}{\partial \hat{v}_e} = 0$$

$$b. \text{ Ions: } \frac{\partial \hat{f}_i}{\partial \hat{t}} + \left(\frac{T_i m_e}{T_e m_i} \right)^{1/2} \hat{v}_i \frac{\partial \hat{f}_i}{\partial \hat{x}} - \frac{q_i}{q_e} \left(\frac{T_e m_e}{T_i m_i} \right)^{1/2} \frac{\partial \hat{\phi}}{\partial \hat{x}} \frac{\partial \hat{f}_i}{\partial \hat{v}_i} = 0$$

C. Discretization1. Timesstepping: 3rd-Order Adams-Bashforth (AB3)

$$\text{For } \frac{dy}{dt} = g, \quad y^{n+1} = y^n + \frac{\Delta t}{12} (23g^n - 16g^{n-1} + 5g^{n-2})$$

2. Spatial Differencing

a. Centered Finite Difference $\frac{dy}{dx} = \frac{y_{i+1} - y_{i-1}}{2\Delta x}$

b. Boundary Conditions: Periodic boundaries in x , $-L \leq x \leq L$ 3. Velocity Differencing

a. Centered Finite Difference $\frac{\partial f}{\partial v} = \frac{f_{j+1} - f_{j-1}}{2\Delta v}$

b. Boundary Conditions:

First-order difference at $\pm v_{\max}$: $\frac{\partial f}{\partial v} = \frac{f - f_{-1}}{\Delta v}$

D. Poisson Equation Solver: Green's Function Solution1. For $\frac{\partial^2 \phi}{\partial x^2} = f(x)$ with periodic BCs $\phi(-L) = \phi(L)$

a. $G(x, x') = \begin{cases} -\frac{1}{2L} (L+x')(L-x) & -L \leq x' \leq x \\ -\frac{1}{2L} (L+x)(L-x') & x < x' \leq L \end{cases}$

b. $\phi(x) = \int_{-L}^L G(x', x) f(x') dx'$

2. a. For inhomogeneous source $f(x) = -4\pi \rho(x) = -4\pi \int dV \rho_s \delta_s$

b. $\phi(x) = \frac{2\pi}{L} \left\{ (L-x) \int_{-L}^x (L+x') \rho(x') dx' + (L+x) \int_x^L (L-x') \rho(x') dx' \right\}$

E. Separating Linear and Nonlinear Terms

$$1. f_s(x, v, t) = f_{s0}(v) + \delta f_s(x, v, t) \geq 0$$

↖ equilibrium uniform in space
and constant in time

2. This decomposition yields

$$a. \frac{\partial \delta f_s}{\partial t} = -v \frac{\partial \delta f_s}{\partial x} + \frac{q_s}{m_s} \frac{\partial \phi}{\partial x} \frac{\partial f_{s0}}{\partial v} + \frac{q_s}{m_s} \frac{\partial \phi}{\partial x} \frac{\partial \delta f_s}{\partial v}$$

Linear Ballistic Term	Linear Wave- Particle term	Nonlinear Wave- Particle term
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b. Each term is advanced separately

F. Initial Conditions

1. Zero net charges $\sum_s \int dv q_s f_s(x, v, 0) = 0$ necessary

2. Options:
- ic=1: Sinusoidal Electron density perturbation
 - ic=2: Linear Wave Eigenfunction Initialization
 - eig-opt=1 Langmuir Wave
 - eig-opt=2 Ion Acoustic Wave

II. General Flow of Code VP (version 3)

A. VP.F90

1. Initialize Variables
 - a. Read in parameters from input file
 - b. Allocate arrays
2. Set Initial Conditions
3. (Debug) Check Initialization comparing ρ and ϕ
4. Set timestep $\Delta t = CFL \frac{\Delta x}{V_{max}}$ where $0 < CFL < 1$
is safety factor ($CFL = 0.05$)
5. Open Output Files: (runname.*)
6. Initialize AB3 Timestepping:
 - a. 1 Eulerian step
 - b. 6 geometric Leapfrog Steps
7. Main Timestep Loop
 - a. Get x & v derivatives
 - b. Compute $\frac{d}{dt}$ and update with AB3
 - c. Update to new timestep & compute ρ and ϕ
 - d. Write to diagnostic output files
8. Close output files and deallocate arrays