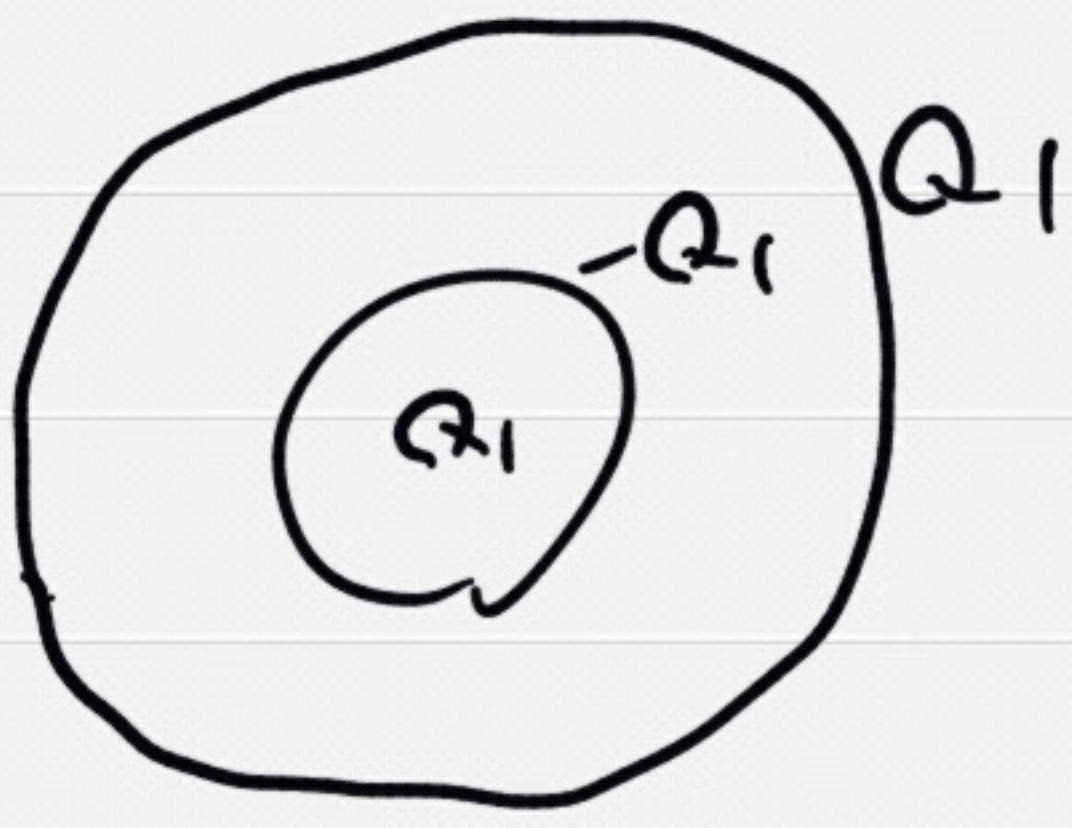


1. a.



$$\sigma_a = -Q_1 / 4\pi a^2$$
$$\sigma_b = +Q_1 / 4\pi b^2$$

b.  $\oint \vec{E} \cdot d\vec{a} = Q_{enc} / \epsilon_0$

$$\Rightarrow \vec{E} = \begin{cases} \frac{Q_1}{4\pi\epsilon_0 r^2} \hat{r} & r < a \\ 0 & a < r < b \\ \frac{Q_1}{4\pi\epsilon_0 r^2} \hat{r} & r > b \end{cases}$$

c.  $\Delta E_{\perp} = \rho / \epsilon_0$

$$\Delta E_a = -\frac{Q_1}{4\pi\epsilon_0 a^2} = \sigma_a / \epsilon_0$$
$$\Delta E_b = +\frac{Q_1}{4\pi\epsilon_0 b^2} = \sigma_b / \epsilon_0$$

d.  $w = Q_2 \Delta V$

$$= Q_2 \left[ -\int_{\infty}^a E dr \right]$$
$$= Q_2 \left[ -\int_{\infty}^b \frac{Q_1}{4\pi\epsilon_0 r^2} dr - \int_b^a 0 dr \right]$$
$$= \frac{Q_2 Q_1}{4\pi\epsilon_0 b}$$

$$\begin{aligned}
 2. a. \quad \vec{E} &= -\nabla V \\
 &= -\frac{\partial V}{\partial r} \hat{r} - \frac{1}{r} \frac{\partial V}{\partial \theta} \hat{\theta} \\
 &= \boxed{-\cos\theta \hat{r} + \sin\theta \hat{\theta}}
 \end{aligned}$$

$$\begin{aligned}
 b. \quad \rho &= \epsilon_0 \nabla \cdot \vec{E} \\
 &= \epsilon_0 \left[ \frac{1}{r^2} \frac{\partial}{\partial r} (r^2 \cdot -\cos\theta) \right. \\
 &\quad \left. + \frac{1}{r \sin\theta} \frac{\partial}{\partial \theta} (\sin^2\theta) \right] \\
 &= \epsilon_0 \left[ -\frac{2\cos\theta}{r} + \frac{2\sin\theta \cos\theta}{r \sin\theta} \right] \\
 &= \boxed{0}
 \end{aligned}$$

$$\begin{aligned}
 3. \quad \oint \vec{E} \cdot d\vec{a} &= Q_{enc} / \epsilon_0 = \int \rho d\tau / \epsilon_0 \\
 E \cdot 2\pi s \cdot L &= \int C/s \cdot s' ds' dz / \epsilon_0 \\
 &= 2\pi C s L / \epsilon_0 \quad s < R \\
 &\quad 2\pi C R L / \epsilon_0 \quad s > R
 \end{aligned}$$

$$\Rightarrow \boxed{\vec{E} = \begin{array}{l} C/\epsilon_0 \hat{s} \quad s < R \\ CR/\epsilon_0 \hat{s} \quad s > R \end{array}}$$

$$\begin{aligned}
 4. \quad \nabla^2 V &= \frac{\partial^2 V}{\partial x^2} + \frac{\partial^2 V}{\partial y^2} + \frac{\partial^2 V}{\partial z^2} \\
 &= -k_x^2 V - k_y^2 V + \frac{\partial^2 V}{\partial z^2} \\
 &= 0
 \end{aligned}$$

$$\Rightarrow \frac{1}{V} \frac{\partial^2 V}{\partial z^2} = k_x^2 + k_y^2$$

$$\Rightarrow V(x, y, z) = V_0 \sin(k_x x) \sin(k_y y) e^{-\sqrt{k_x^2 + k_y^2} \cdot z}$$

Note: No  $e^{+\sqrt{k_x^2 + k_y^2} z}$  since this blows up for  $z > 0$

$$5. a. \quad \nabla \cdot \vec{B} = 0 \Rightarrow \Delta B_{\perp} = 0$$

so this must be  $(H)$

$$b. \quad \Delta \vec{H}_{\parallel} = 0 \Rightarrow \vec{k}_f = 0$$

only  $\vec{k}_0$

$$c. \quad \text{If } \sigma_f = 0 \quad \Delta D_{\perp} = 0$$

so this must be  $(E)$

$$b.a. \oint \vec{D} \cdot d\vec{a} = Q_{fenc}$$

$$D \cdot 2\pi s L = \lambda \cdot L$$

$$\Rightarrow \boxed{\vec{D} = \frac{\lambda}{2\pi s} \hat{s}}$$

$$\vec{D} = (1 + \chi_e) \epsilon_0 \vec{E}$$

$$\Rightarrow \boxed{\vec{E} = \frac{1}{1 + \chi_e} \frac{\lambda}{2\pi \epsilon_0 s} \hat{s}}$$

$$\vec{P} = \epsilon_0 \chi_e \vec{E}$$

$$\Rightarrow \boxed{\vec{P} = \frac{\chi_e}{1 + \chi_e} \frac{\lambda}{2\pi s} \hat{s}}$$

$$b. \sigma_b = \vec{P} \cdot \hat{n}$$

$$\sigma_{ab} = - \frac{\chi_e}{1 + \chi_e} \frac{\lambda}{2\pi a}$$

$$\sigma_{bb} = \frac{\chi_e}{1 + \chi_e} \frac{\lambda}{2\pi b}$$

$$\begin{aligned}
 7.a. \quad I &= \int \vec{J} \cdot d\vec{a} \\
 &= \int C \cdot s \cdot s \, ds \, d\phi \\
 &= 2\pi C \frac{s^3}{3} \Big|_0^R \\
 &= 2\pi C \frac{R^3}{3} \\
 \Rightarrow C &= \frac{3I}{2\pi R^3}
 \end{aligned}$$

$$\Rightarrow \boxed{J(s) = \frac{3Is}{2\pi R^3}}$$

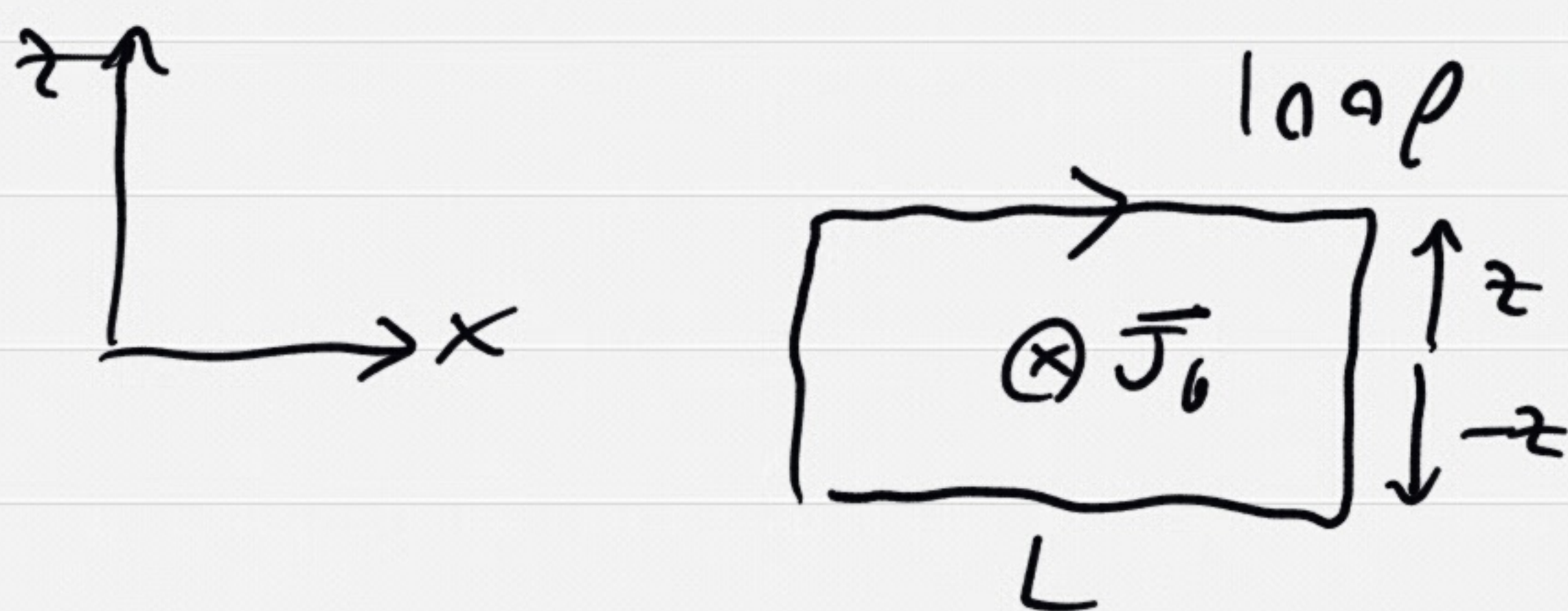
$$\begin{aligned}
 b. \quad \oint \vec{B} \cdot d\vec{\ell} &= \mu_0 \cdot I_{enc} \\
 B \cdot 2\pi s &= \mu_0 \int \vec{J} \cdot d\vec{a} \\
 &= \mu_0 \cdot \frac{3I}{2\pi R^3} \cdot \frac{2\pi s^3}{3} \\
 &= \mu_0 I \frac{s^3}{R^3} \quad s < R \\
 &\quad \mu_0 I \quad s > R
 \end{aligned}$$

$$\Rightarrow \boxed{
 \begin{aligned}
 \vec{B} &= \frac{\mu_0 I s^2}{2\pi R^3} \hat{\phi} \quad s < R \\
 &= \frac{\mu_0 I}{2\pi s} \hat{\phi} \quad s > R
 \end{aligned}
 }$$

$$\begin{aligned}
 \text{8. a. } \vec{J}_0 &= \nabla \times \vec{M} \\
 &= \frac{\partial}{\partial z} (M_0 z) \hat{y} \\
 &= \boxed{M_0 \hat{y}}
 \end{aligned}$$

$$\begin{aligned}
 \vec{K}_0 &= \vec{M} \times \hat{n} = M_0 z \hat{x} \times \pm \hat{z} \\
 &= M_0 \cdot \pm T/2 \cdot \mp \hat{y} \\
 &= \boxed{-\frac{M_0 T}{2} \hat{y}} \quad \text{same top and bottom}
 \end{aligned}$$

$$\text{b. } \oint \vec{B} \cdot d\vec{l} = \mu_0 I_{enc}$$



$$\begin{aligned}
 B \cdot 2L &= \mu_0 M_0 \cdot 2z \cdot L \quad z < T/2 \\
 &= \mu_0 (M_0 \cdot 2T/2 \cdot L - 2 \cdot \frac{M_0 T}{2} \cdot L) \quad z > T/2
 \end{aligned}$$

$$\Rightarrow \boxed{
 \begin{aligned}
 \vec{B} &= \mu_0 M_0 z \hat{x} & |z| < T/2 \\
 &= 0 & |z| > T/2
 \end{aligned}
 }$$

$$\text{c. } \vec{H} = \vec{B} / \mu_0 - \vec{M}$$

$$\boxed{\vec{H} = 0 \text{ everywhere (and continuous)}}$$