

Lecture 19

Magnetic force on current carrying wire

$$* \vec{F} = q \vec{v} \times \vec{B}$$

q = charge

\vec{v} = particle velocity

\vec{B} = magnetic field

Field units

$$1 \text{ Tesla} = (\text{N} \cdot \text{sec}) / (\text{coulomb} \cdot \text{meter})$$

A length dl of wire contains many charge carriers. The superposition principle gives

$$\vec{F} = \sum_i q_i \vec{v}_i \times \vec{B}(\vec{r}_i, t)$$

this is the sum of the forces on every charge in the wire

Let \vec{dl} be a vector of length dl pointing in the direction of the current

This is the same direction as

$$\vec{v}_D \cdot \vec{q}$$

For Δl small enough, $\vec{B}(\vec{r}_i)$ is approximately constant

$$d\vec{F} = \sum q_i \vec{v}_i \times \vec{B}$$

We replace

volume

$$\sum q_i \vec{v}_i = n e \vec{v}_D A \cdot d\vec{l}$$

since $d\vec{l} \propto e \vec{v}_D$

$$d\vec{F} = n e \vec{v}_D A \cdot d\vec{l} \times \vec{B}$$

$$= I d\vec{l} \times \vec{B}$$

This means that the total force on the wire is

$$\vec{F}_T = \sum I d\vec{l}_i \times \vec{B}(\vec{r}_i)$$

which in the limit of small $d\vec{l}_i$,

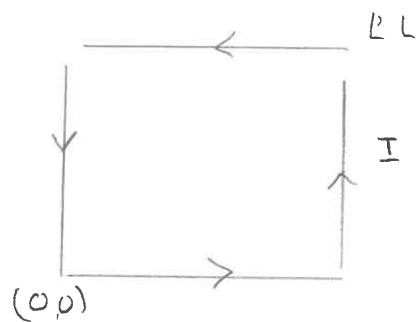
gives

$$\vec{F} = \int I d\vec{l} \times \vec{B}$$

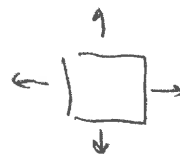
where the integral is along the path of the wire

example 1

consider a square loop of wire with current I and side L in the xy plane. Let \vec{B} be a constant magnetic field



for $B = \hat{z} B$

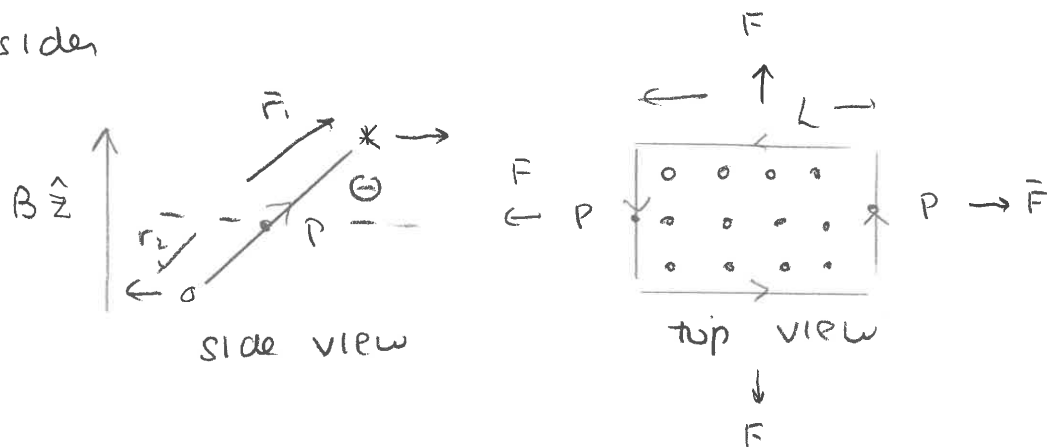


$$\begin{aligned} \oint I d\vec{r} \times \vec{B} &= \int_0^L dx I \hat{x} \times \vec{B} + \\ &\int_0^L dy I \hat{y} \times \vec{B} + \\ &\int_L^0 dx I \hat{x} \times \vec{B} \\ &\int_0^L dy I \hat{y} \times \vec{B} \\ &= IL (\hat{x} + \hat{y} - \hat{x} - \hat{y}) \times \vec{B} \\ &= 0 \end{aligned}$$

this shows that the field does no work on this current loop. while there is a net force on each side, the forces all cancel

The forces can exert a torque on the current loop

Consider



Looking at the picture it is clear that the magnetic forces on this loop are producing a torque

The relevant forces are the ones in and out of the plane of the paper in the plane on the right

$$ILB (\hat{x} \times \hat{z}) = ILB \hat{y} \quad *$$

$$ILB (\hat{y} \times \hat{z}) = -ILB \hat{x} \quad \ominus$$

The torque about P is

$$\vec{r}_1 = \frac{L}{2} (\hat{y} \cos \theta + \hat{z} \sin \theta)$$

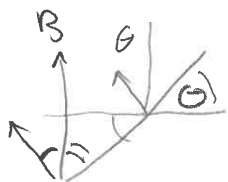
$$\vec{r}_1 \times \vec{F}_1 + \vec{r}_2 \times \vec{F}_2 =$$

$$\vec{r}_2 = -\frac{L}{2} (\hat{y} \cos \theta + \hat{z} \sin \theta)$$

$$-\frac{L}{2} \sin \theta (ILB) \hat{x} + (-\frac{L}{2} \sin \theta) (-ILB) \hat{x}$$

$$-IL^2 B \sin \theta \hat{x}$$

In this case $L^2 = A = \text{area of current loop}$



$$\boxed{T = IA \hat{n} \times \vec{B}}$$

recall for an electric dipole the torque is

$$\boxed{T = \vec{p} \times \vec{E}}$$

where \vec{p} is the dipole moment

We see that for a square loop $IA\hat{n}$ behaves like a dipole with respect to the magnetic field

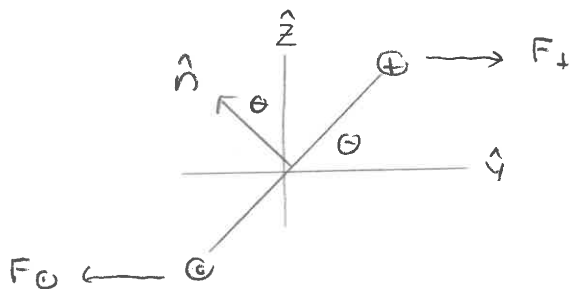
The work needed to rotate the dipole against the torque

We define the magnetic dipole moment of this current loop

$$\vec{\mu} = IA\hat{n}$$

$$T = \vec{\mu} \times \vec{B}$$

We can also compute the potential energy of this dipole in the magnetic field \vec{B}



$$F_+ = IBL\hat{y}$$

$$F_- = -IBL\hat{y}$$

$$\text{Let } \vec{r}_+ = \frac{L}{2} (\hat{y} \cos\theta + \hat{z} \sin\theta)$$

$$\vec{r}_- = \frac{L}{2} (-\hat{y} \cos\theta - \hat{z} \sin\theta)$$

$$d\vec{r}_+ = \frac{L}{2} (-\hat{y} \sin\theta + \hat{z} \cos\theta) d\theta$$

$$d\vec{r}_- = \frac{L}{2} (\hat{y} \sin\theta - \hat{z} \cos\theta) d\theta$$

work done against the field by increasing θ is

$$dW = -\vec{F} \cdot d\vec{r} = -\vec{F}_+ \cdot d\vec{r}_+ - \vec{F}_- \cdot d\vec{r}_-$$

$$= -(IBL\hat{y}) \cdot \left(-\frac{L}{2}\hat{y} \sin\theta + \frac{L}{2}\hat{z} \cos\theta\right) d\theta +$$

$$-(-IBL\hat{y}) \cdot \left(\frac{L}{2}\hat{y} \sin\theta - \frac{L}{2}\hat{z} \cos\theta\right) d\theta$$

$$= \frac{L^2 IB}{2} (\sin\theta + \sin\theta) d\theta$$

$$= L^2 IB \sin\theta = IAB \sin\theta$$

Integrating gives

$$\int (-\mathbf{F} \cdot d\mathbf{r}) = \int_{\theta_0}^0 IAB \sin\theta d\theta$$
$$= IAB \cos\theta + IAB \cos\theta_0$$

The constant is irrelevant

$$U = -IAB \cos\theta$$

but $\mu = IA \hat{n}$ $B = B \hat{z}$ $\hat{n} \cdot \hat{z} = \cos\theta$

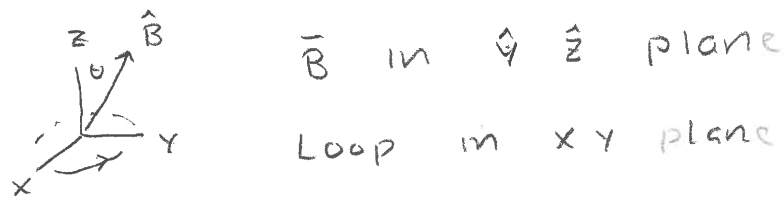
$$U = -\vec{\mu} \cdot \vec{B}$$

which looks similar to $-\vec{p} \cdot \vec{E} = U$

In this sense we can understand current loops as magnetic dipoles

It turns out that this result is the same for any shape.

Case of a circular current loop



$$\begin{aligned} d\vec{\ell} &= d(R \cos\phi \hat{x} + R \sin\phi \hat{y}) \\ &= (-R \sin\phi \hat{x} + R \cos\phi \hat{y}) d\phi \end{aligned}$$

consider torque about x axis

$$\vec{B} = B \hat{y} \sin\theta + B \hat{z} \cos\theta$$

the force on a section of wire

$$\begin{aligned} d\vec{F} &= I d\vec{\ell} \times \vec{B} \\ &= I (-R \sin\phi \hat{x} + R \cos\phi \hat{y}) d\phi \times (B \hat{y} \sin\theta + B \hat{z} \cos\theta) \\ &= IRB (-\hat{z} \sin\theta \sin\phi + \hat{x} \cos\phi \cos\theta + \hat{y} \sin\phi \cos\theta) \end{aligned}$$

If we integrate around the circle
all 3 terms vanish

If we want the torque about the \hat{x} axis

$$\begin{aligned} \vec{\tau} &= \int \vec{r} \times d\vec{F} = \\ &= (R \cos\phi \hat{x} + R \sin\phi \hat{y}) \times IRB (-\hat{z} \sin\phi \sin\theta + \hat{x} \cos\phi \cos\theta + \hat{y} \sin\phi \cos\theta) \\ &= \hat{y} R^2 IB \cos\phi \sin\phi \sin\theta + \hat{z} R^2 IB \cos\phi \sin\phi \cos\theta \\ &\quad - \hat{x} R^2 IB \sin^2\phi \sin\theta - \hat{z} R^2 IB \sin\phi \cos\phi \cos\theta \end{aligned}$$

$$\sin\phi \cos\phi = \frac{1}{2} \sin 2\phi \quad u = 2\phi \quad du = 2d\phi$$

$$\int_0^{2\pi} \frac{1}{2} \sin 2\phi d\phi = \frac{1}{4} \int_0^{4\pi} \sin u du = -\frac{1}{4} (\cos 4\pi - \cos 0) = 0$$

the only term that contributes is

$$-\hat{x} R^2 I B \int_0^{2\pi} \sin^2\phi \sin\theta$$

$$\text{The integral } \int_0^{2\pi} \sin^2\phi = \frac{1}{2} \int_0^{2\pi} (\sin^2\phi + \cos^2\phi) = \pi$$

$$\vec{\tau} = -\pi R^2 I B \sin\theta \hat{x}$$

$$\text{Note: } \hat{n} \times \vec{B} = \hat{z} \times (B \hat{y} \sin\theta + B \hat{z} \cos\theta) = -B \hat{x} \sin\theta$$

this gives the torque

$$\vec{\tau} = \underbrace{(\pi R^2) I}_{A} \hat{n} \times \vec{B}$$

$$= I A \hat{n} \times \vec{B}$$

$$= \vec{\mu} \times \vec{B}$$

$$\text{where } \vec{\mu} = I A \hat{n}$$

Consider a "hydrogen atom" with an electron in a circular orbit around a proton

$$\vec{\mu} = I A = \frac{q}{T} \cdot \pi r^2 \quad r = 5.29 \times 10^{-11}$$

$$\frac{1}{2} m v^2 = \frac{k q^2}{r^2} \quad v = r\omega \quad \omega = 2\pi f$$

so far what we have done is the analog of $\vec{F} = q\vec{E}$ for magnetic fields. The thing that is missing is the analog of Coulomb's law or Gauss law for magnets.

The relevant law is called the Biot-Savart Law

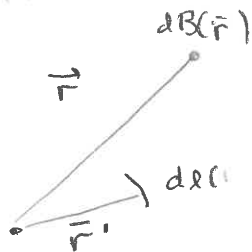
It has the form

$$d\vec{B} = \frac{\mu_0}{4\pi} \frac{I d\vec{\ell} \times (\vec{r} - \vec{r}')}{|\vec{r} - \vec{r}'|^3}$$

which is the contribution to the field \vec{B} at \vec{r} due to a current at \vec{r}'

$$\mu_0 = 4\pi \times 10^{-7} \frac{\text{T}\cdot\text{m}}{\text{A}}$$

Like Coulomb's law the field strength falls off like $1/r^2$



We can use the superposition principle to find the full field at \vec{r} by adding up all of the contributions in a wire

$$\vec{B} = \int_{\text{wire}} d\vec{B} = \frac{\mu_0 I}{4\pi} \int \frac{d\vec{\ell}' \times (\vec{r} - \vec{r}')}{|\vec{r} - \vec{r}'|^3}$$

This is considerably more complicated than Coulomb's law. Some special cases are not too difficult

Case 1

\vec{B} due to a long straight wire along the z axis with current I

$$I d\vec{\ell} = I dz \hat{z} \quad \vec{r}' = z' \hat{z} = (00z')$$

$$d\vec{\ell}' \times (\vec{r} - \vec{r}') = dz' \hat{z} \times (x\hat{x} + y\hat{y} + (z-z')\hat{z}) =$$

$$dz' (x\hat{y} - y\hat{x})$$

$$|\vec{r} - \vec{r}'|^2 = x^2 + y^2 + (z-z')^2$$

$$\vec{B} = \frac{\mu_0 I}{4\pi} \int_{-\infty}^{\infty} dz' \frac{x\hat{y} - y\hat{x}}{(x^2 + y^2 + (z-z')^2)^{3/2}}$$

let $z'' = z' - z$ $dz'' = dz'$ $z'': -\infty \rightarrow \infty$

$$\vec{B}(x,y,z) = \frac{\mu_0 I}{4\pi} \int_{-\infty}^{\infty} dz'' \frac{x\hat{y} - y\hat{x}}{(x^2 + y^2 + z''^2)^{3/2}} dz''$$

$$= \frac{\mu_0 I}{4\pi} (x\hat{y} - y\hat{x}) \int_{-\infty}^{\infty} \frac{dz''}{(r^2 + z''^2)^{3/2}}$$

$$r^2 = x^2 + y^2$$

To do the integral note

$$\frac{d}{dz} \left(z(z^2 + r^2)^{-1/2} \right) = (z^2 + r^2)^{-1/2} + z \left(-\frac{1}{2} \right) (z^2 + r^2)^{-3/2} \cdot (2z)$$

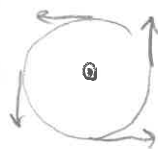
$$= \frac{z^2 + r^2}{(z^2 + r^2)^{3/2}} - \frac{z^2}{(z^2 + r^2)^{3/2}} = \frac{r^2}{(z^2 + r^2)^{3/2}}$$

$$\therefore \frac{1}{(z^2 + r^2)^{3/2}} = \frac{1}{r^2} \frac{d}{dz} \left(\frac{z}{(z^2 + r^2)^{1/2}} \right)$$

using this in the above gives

$$\vec{B}(x,y,z) = \frac{\mu_0 I}{4\pi} (x\hat{y} - y\hat{x}) \frac{1}{r^2} \underbrace{\frac{z}{(z^2 + r^2)^{1/2}}}_{2} \Big|_{-\infty}^{\infty}$$

$$\boxed{\vec{B}(x,y,z) = \frac{\mu_0 I}{2\pi} \frac{x\hat{y} - y\hat{x}}{r^2}}$$



This satisfies the right hand rule
in the sense that following the field
lines with the right hand rule
gives the direction of the current