

# Summary - Electromagnetic Radiation

①  $\vec{E} = \vec{E}_0 \cos(\vec{k} \cdot \vec{r} - \omega t)$

$k\lambda = 2\pi$  gives wavelength  $\lambda$

$$\lambda = \frac{2\pi}{k}$$

$k$  = wave number

$$kc = \omega = 2\pi f = \frac{2\pi}{T}$$

$f$  = frequency

$\omega$  = angular frequency

$\hat{k}$  = direction of wave

$$\vec{E}_0 \cdot \hat{k} = 0$$

$$\vec{B}_0 = \frac{1}{c} \hat{k} \times \vec{E}_0$$

$$\vec{B}_0 \cdot \hat{k} = 0$$

$$\vec{B}_0 \cdot \vec{E}_0 = 0$$

$$\vec{B} = \frac{1}{c} \hat{k} \times \vec{E}_0 \cos(\vec{k} \cdot \vec{r} - \omega t)$$

② more complex waves can be constructed using superposition principle

③ energy transport

$$\vec{S} = \frac{1}{\mu_0} \vec{E} \times \vec{B} = c \left( \frac{1}{2} \epsilon_0 \vec{E} \cdot \vec{E} + \frac{1}{2} \mu_0 \vec{B} \cdot \vec{B} \right) \hat{k}$$

$\langle \vec{S} \rangle = I = \text{intensity}$

$$\vec{E}_{rms} = \frac{1}{\sqrt{2}} \vec{E}_{max} \quad \vec{B}_{rms} = \frac{1}{\sqrt{2}} \vec{B}_{max}$$

$$I = \frac{1}{\mu_0} \vec{E}_{rms} \times \vec{B}_{rms} = \frac{1}{2} \cdot \frac{1}{\mu_0} (\vec{E}_{max} \times \vec{B}_{max})$$

$IA = \text{Average power deposited in area } A$

④ radiation pressure

$$P = \frac{I}{c}$$

if radiation absorbed  $P = \frac{I}{c}$

if radiation reflected  $P = 2 \frac{I}{c}$

case 1 field momentum absorbed

case 2 field momentum changes  
direction - absorbed momentum  
is  $2\Delta P$

⑤ polarization



only let polarization  
in an direction

$$I = \epsilon \epsilon_0 E_{rms}^2 \cos^2 \theta$$

$$(\cos 90^\circ)^2 = 0$$

$$(\cos 45^\circ)^2 (\cos 45^\circ)^2 = \frac{1}{2} \cdot \frac{1}{2} = \frac{1}{4}$$

possible to rotate polarization  
without much loss

role of frequency

$$\frac{\text{Energy}}{\text{photon}} = hf = h \frac{\omega}{2\pi} = \hbar\omega$$


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Magnetic Properties of matter

① magnetic dipoles

$$\vec{\mu} = IA \quad \text{current loop}$$

direction right hand rule

magnetic dipole moment

$$\textcircled{1} U = -\vec{\mu} \cdot \vec{B}$$

$$\textcircled{2} \vec{B}_d = \frac{\mu_0}{4\pi} \frac{3(\vec{\mu} \cdot \vec{r})\vec{r} - \vec{\mu}(\vec{r} \cdot \vec{r})}{r^5}$$

analogous to electric case

$$U = -\vec{p} \cdot \vec{E}$$

$$\vec{E}_d = \frac{1}{4\pi\epsilon_0} \left( \frac{3(\vec{p} \cdot \vec{r})\vec{r} - \vec{p}(\vec{r} \cdot \vec{r})}{r^5} \right)$$

② magnetic moments and angular momentum

$$\frac{mv^2}{r} = \frac{q^2}{4\pi\epsilon_0} \frac{1}{r^2} \quad \text{orbiting electron}$$

$$I = \frac{q}{T} = qf = q \frac{\omega}{2\pi}$$

$$IA = \pi r^2 \left( q \frac{\omega}{2\pi} \right) = \frac{q}{2} r^2 \omega = \frac{q}{2} r v = \frac{q}{2m} m r v$$

$$\vec{L} = \vec{r} \times \vec{p} = \vec{r} \times m\vec{v}$$

$$|\vec{L}| = r m v \text{ and } \vec{v} \perp \vec{r}$$

$$\boxed{\vec{\mu} = \frac{q_e}{2m} \vec{L}}$$

In quantum mechanics orbital angular momentum is quantized.  $\vec{L}$  can have integer multiples of  $\hbar$ .

Electrons also have a spin angular momentum.

$$\boxed{\vec{\mu}_{spin} = \frac{q}{m} \vec{S}}$$

$\vec{S}$  has values  $\pm \frac{\hbar}{2}$ .

The absence of  $\frac{1}{2}$  in  $\vec{\mu}_{spin}$  is an experimentally determined number — the big success of the Dirac equation for an electron is that it explains the factor of 2.

In a general atom or molecule the different angular momenta are added, so the total magnetic dipole moment can be more complicated.

In general if there are a lot of magnetic dipoles in a substance, the moments will be randomly oriented.

If a magnetic field is applied they tend to want to rotate until they are parallel to the magnetic field.

Since each dipole behaves like a small bar magnet, the oriented magnetic dipoles will tend to increase the strength of the field.

consider

$$\vec{B}_{\text{dipole}} = \frac{\mu_0}{4\pi} \frac{3(\vec{\mu} \cdot \vec{r})\vec{r} - \mu^2 \vec{r} \cdot \vec{r}}{r^5}$$

$$\approx \mu_0 \frac{\mu}{\text{volume}}$$

$\frac{\vec{B}}{\mu_0}$  has dimension magnetic moment / volume

In a system of magnetic dipoles we define the magnetization  $\vec{M}$  as the dipole moment / volume

the total magnetic field is

$$\bar{B}_{\text{tot}} = \bar{B}_{\text{applied}} + \mu_0 \bar{M}$$

it is useful to define a new field

$$\boxed{\bar{B}_{\text{applied}} = \mu_0 \bar{H}}$$

then

$$\boxed{\bar{B}_{\text{tot}} = \mu_0 (\bar{H} + \bar{M})}$$

In many cases  $\bar{M}$  is proportional to  $\bar{H}$

$$\bar{M} = \chi \bar{H}$$

$\chi$  is called the magnetic susceptibility

$$\boxed{\bar{B}_{\text{tot}} = \mu_0 (1 + \chi) \bar{H} = \mu \bar{H}}$$

where  $\bar{B}$  is the actual field - including magnetization that includes the dipole field.

$\mu$  is called the magnetic permeability

When  $\vec{M} = \chi \vec{H}$

there are 2 cases of interest

①  $\chi > 0$

②  $\chi < 0$

When  $\chi > 0$  the material is called paramagnetic material. This happens when the material has dipoles that align with the field.

When  $\chi < 0$  the material is called diamagnetic. Usually this is a very small effect. It was discovered by Faraday. It tends to weaken the field. The only exception to being small is in superconductors, where it completely eliminates the field in the superconductor.

For paramagnetic substances the magnetization also has a temperature dependence given by Curie's law

$$M = C \frac{B_{\text{ext}}}{T} \quad \bar{B}_{\text{ext}} = \mu_0 \bar{H}$$

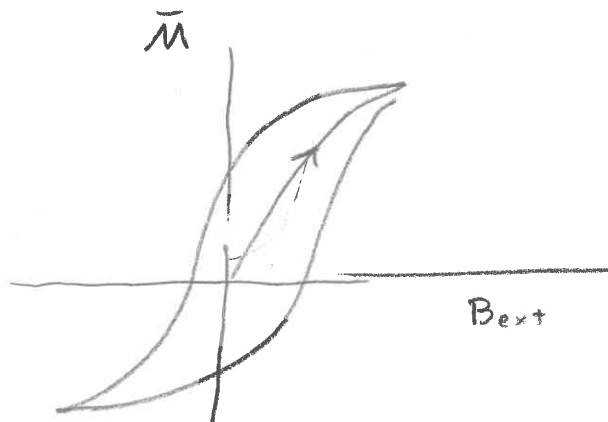
$C$  is called the Curie constant

$T$  is the absolute temperature

There is a third type of magnetic material called Ferromagnetic material

In these materials the magnetic field will persist, even after the external field is removed.

In this case since  $U = -\bar{\mu} \cdot \bar{B}$  hence the dipoles reach a low energy state the fields due to the dipoles keep them aligned.





In this case the magnetization is a multivalued function of the applied field.

The alignment can be destroyed by heating. The Curie temperature is a temperature above which they become paramagnetic.

## Special Relativity

If you throw a ball in a car moving with constant velocity it can be treated using the same laws of physics that apply to the car at rest.

This is not true if the car is accelerating

This suggests that there are preferred coordinate systems where the laws of physics have the same form. These are called inertial coordinate systems

They are coordinate systems where non-interacting particles move with constant velocity

In these systems Newton's second law for free particles must be preserved

$$m \frac{d^2 \vec{x}}{dt^2} = 0 \quad x \rightarrow \vec{y}(\vec{x}) \quad m \frac{d^2 \vec{y}}{dt^2} = 0$$

Transformations that do this are

$$\bar{y}_i(t) = \bar{x}_i(t) + \bar{a} \quad \bar{a} = \text{constant}$$

$$\bar{y}_i(t) = \bar{x}_i(t - t_0) \quad t_0 = \text{constant}$$

$$\bar{y}_i(t) = \bar{x}_i(t) + \bar{b}t \quad \bar{b} = \text{constant}$$

$$y_1(t) = \cos\theta x_1(t) + \sin\theta x_2(t)$$

$$y_2(t) = \cos\theta x_2(t) - \sin\theta x_1(t)$$

$$y_3(t) = x_3(t)$$

These correspond to space translations,  
time translations, velocity shifts,  
and rotations. These all preserve

$$\ddot{m}\bar{y} = 0$$

These elementary transformations  
generate the most general  
transformations relating inertial  
coordinate systems in classical  
mechanics.

Maxwell's equation  $\rightarrow$  wave equation

$$\left( \frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2} + \frac{\partial^2}{\partial z^2} - \frac{1}{c^2} \frac{\partial^2}{\partial t^2} \right) \begin{cases} \vec{E}(r,t) \\ \vec{B}(r,t) \end{cases} = 0$$

leads to waves traveling at the speed of light

The speed of light can't be the same in 2 coordinate systems related by a velocity shift unless the identification of inertial coordinate systems is wrong.

It was known before Einstein that transformations that preserve  $r_1 - r_2$

$$(x_1 - x_2)^2 + (y_1 - y_2)^2 + (z_1 - z_2)^2 - c^2 (t_1 - t_2)^2 = 0$$

$$(x_1' - x_2')^2 + (y_1' - y_2')^2 + (z_1' - z_2')^2 - c^2 (t_1' - t_2')^2 = 0$$

preserves the speed of light)

the wave equation and Maxwell's equations