# College Physics I: 1511 Mechanics & Thermodynamics

Professor Jasper Halekas Van Allen Lecture Room 1 MWF 8:30-9:20 Lecture

### Announcements

- Office hours schedule this week
  - Today 9:30-11:00 am
  - Tuesday none (out of office)
  - Wednesday 9:30-11:00 am
  - Thursday 12:00-1:00 pm
  - Thursday 3:30-5:00 pm
- No labs or homework this week
- Midterm #2 is in class Friday

### **Midterm Details**

- Will Cover Chs. 7-11
  - Not cumulative, but many concepts rely on previous material (F = ma!)
  - No questions on the following material:
    - 8.7 (vector nature of angular variables)
    - 10.5-10.8 (driven/damped oscillators, stress, strain)
    - 11.9-11.11 (Bernoulli's equation, viscous flow)
  - Fifteen questions: Four on Ch. 7, five on Chs. 8-9, three on Ch. 10, three on Ch. 11

# **Equation Sheet: Top**

### Trigonometry (For right triangle with sides Adjacent, Opposite, and Hypoteneuse):

 $Sin(\theta) = O/H$ 

 $Cos(\theta) = A/H$ 

 $Tan(\theta) = O/A$   $H^2 = O^2 + A^2$ 

 $Sin(30^{\circ}) = Cos(60^{\circ}) = \frac{1}{2}$ 

 $Sin(60^{\circ}) = Cos(30^{\circ}) = \sqrt{3}/2 \sim 0.866$   $Sin(45^{\circ}) = Cos(45^{\circ}) = \sqrt{2}/2 \sim 0.707$ 

 $Sin(0^{\circ}) = Cos(90^{\circ}) = 0$   $Sin(90^{\circ}) = Cos(0^{\circ}) = 1$ 

#### Moment of Inertia

*Point mass or thin-walled wheel:* 

 $I = mr^2$ 

Solid cylinder:

 $I = \frac{1}{2} mr^2$ 

Thin rod pivoting around end:

 $I = 1/3 \text{ mr}^2$ 

Solid sphere:

 $I = 2/5 \text{ mr}^2$ 

### **Kinematics:**

$$\langle \vec{v} \rangle = \frac{\Delta \vec{r}}{\Delta t}$$

$$\langle \vec{a} \rangle = \frac{\Delta \vec{v}}{\Delta t}$$

$$\langle \vec{v} \rangle = \frac{\Delta \vec{r}}{\Delta t}$$
  $\langle \vec{a} \rangle = \frac{\Delta \vec{v}}{\Delta t}$   $\vec{r}(t) = \vec{r_0} + \vec{v_0}t + \frac{1}{2}\vec{a}t^2$   $v(t)^2 = v_0^2 + 2\vec{a} \cdot \Delta \vec{r}(t)$ 

$$v(t)^2 = v_o^2 + 2\vec{a} \cdot \Delta \vec{r}(t)$$

#### **Newton's Laws:**

$$\sum \vec{F} = m\vec{a}$$

$$\overline{F_{AB}} = -\overline{F_{BA}}$$

#### **Forces:**

$$F_G = mg$$
 (@ surface)

$$f_s^{MAX} = \mu_s F_N \qquad f_k = \mu_k F_N$$

$$f_k = \mu_k F_N$$

$$F_C = ma_C = \frac{mv^2}{r}$$

$$F_{spring} = -kx$$

$$F_{spring} = -kx$$
  $F_{Buoyant} = m_{fluid\_displaced} g$ 

### Work & Energy:

$$KE_{trans} = \frac{1}{2}mv^2$$

$$\Delta KE = W_{net}$$

$$PE_G = mgh$$

$$\Delta KE = W_{net}$$
  $PE_G = mgh$   $PE_{spring} = \frac{1}{2}kx^2$ 

$$E = KE + PE$$

$$\Delta E = W_{no}$$

$$\Delta E = W_{nc}$$
  $W = \overrightarrow{F} \cdot \Delta \overrightarrow{r} = |\overrightarrow{F}| |\Delta \overrightarrow{r}| \cos \theta_{Fdr}$ 

# **Equation Sheet: Bottom**

### **Impulse & Momentum:**

$$\vec{J} = \vec{F} \Delta t \qquad \vec{p} = m\vec{v} \qquad \sum \vec{J} = \Delta \vec{p} \qquad \sum \vec{p_f} = \sum \vec{p_l} \quad (if F_{ext} = 0)$$

$$\vec{v_{cm}} = \frac{\sum m_l \vec{v_l}}{\sum m_l} = \sum \vec{p} / M$$

#### **Rotational Motion:**

$$\begin{array}{ll} \theta = s/r & \langle \omega \rangle = \frac{\langle v_t \rangle}{r} = \frac{\Delta \theta}{\Delta t} & \langle \alpha \rangle = \frac{\langle a_t \rangle}{r} = \frac{\Delta \omega}{\Delta t} \\ \theta(t) = \theta_o + \omega_o t + \frac{1}{2} \alpha t^2 & \omega(t)^2 = \omega_o^2 + 2\alpha \Delta \theta(t) \\ \tau = rF \sin \theta_{rF} = F * lever \ arm & \sum \tau = I\alpha & L = mvr = I\omega \\ W_{rot} = \tau \Delta \theta & KE_{rot} = \frac{1}{2} I\omega^2 & r_{CM} = \frac{\sum m_i r_i}{\sum m_i} \end{array}$$

#### **Harmonic Motion:**

$$\omega_{h} = 2\pi f_{h} = \frac{2\pi}{T} = \sqrt{\frac{k}{m}} \qquad x_{max} = A \qquad v_{max} = A\omega_{h} \qquad a_{max} = A\omega_{h}^{2}$$

$$\omega_{h\_pendulum} = \sqrt{\frac{mgr_{CM}}{I}} = \sqrt{\frac{g}{L}} \text{ for simple pendulum of length } L$$

#### Fluids:

$$\rho = mass/Volume \qquad P = F/A \qquad P_2 = P_1 + \rho g d \qquad F_B = W_{fluid\_displaced}$$
 
$$\rho_1 A_1 v_1 = \rho_2 A_2 v_2 \qquad A_1 v_1 = A_2 v_2 \ (if \ \rho_1 = \rho_2) \qquad P_1 + \frac{1}{2} \rho v_1^2 + \rho g y_1 = P_2 + \frac{1}{2} \rho v_2^2 + \rho g y_2$$

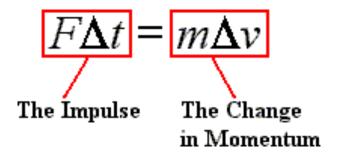
# Impulse and Momentum

### Impulse & Momentum:

$$\vec{J} = \vec{F} \Delta t$$
  $\vec{p} = m\vec{t}$ 
 $\overrightarrow{v_{cm}} = \frac{\sum m_i \overrightarrow{v_i}}{\sum m_i} = \sum \vec{p} / M$ 

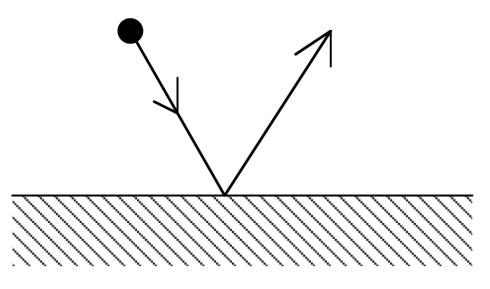
$$\vec{J} = \vec{F} \Delta t$$
  $\vec{p} = m\vec{v}$   $\sum \vec{J} = \Delta \vec{p}$   $\sum \vec{p_f} = \sum \vec{p_l}$  (if  $F_{ext} = 0$ )

# Impulse-Momentum Theorem



Remember: Impulse-Momentum Theorem is just a restatement of F = ma.

A ball bounces off the floor as shown. The direction



of the impulse on the

ball,  $\Delta \mathbf{p}$ , is ...

A: straight up ↑

B: straight down ↓

C: to the right  $\rightarrow$ 

D: to the left  $\leftarrow$ 

A ball bounces off the floor as shown. The direction

of the impulse on the

ball,  $\Delta \mathbf{p}$ , is ...

A: straight up \

B: straight down \

C: to the right  $\rightarrow$ 

D: to the left  $\leftarrow$ 

### **Conservation of Momentum**

- If no external impulse:
  - Total momentum of an isolated system is conserved
  - Internal forces between different parts of an isolated system are equal and opposite, so total momentum is conserved
    - This is true even if mechanical energy is not conserved

# Collisions/Explosions

### **Collisions**

In all collisions where  $\Sigma F_{\text{ext}} = 0$ , momentum is conserved

### **Elastic Collisions**

No deformation occurs. Kinetic energy is also **conserved**.

### **Inelastic Collisions:**

Deformation occurs. Kinetic energy is **lost**.

### Perfectly Inelastic

Collisions

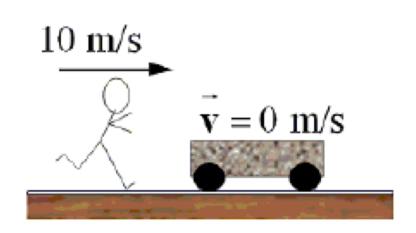
Objects stick together, kinetic energy is **lost**.

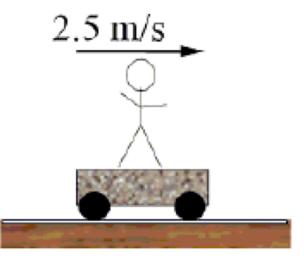
### **Explosions**

Reverse of perfectly inelastic collision, kinetic energy is **gained**.

$$KE = \frac{1}{2}mv^2$$

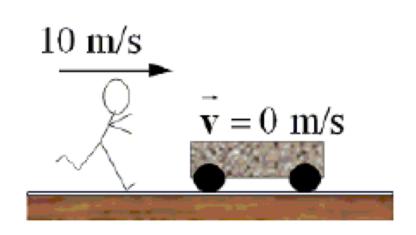
A 50.0-kg boy runs at a speed of 10.0 m/s and jumps onto a cart as shown in the figure. The cart is initially at rest. If the speed of the cart with the boy on it is 2.50 m/s, what is the mass of the cart?

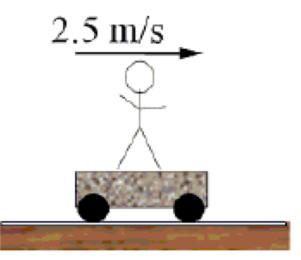




- A. 260 kg
- B. 150 kg
- C. 175 kg
- D. 210 kg
- E. 300 kg

A 50.0-kg boy runs at a speed of 10.0 m/s and jumps onto a cart as shown in the figure. The cart is initially at rest. If the speed of the cart with the boy on it is 2.50 m/s, what is the mass of the cart?





- A. 260 kg
- B. 150 kg
- C. 175 kg
- D. 210 kg
- E. 300 kg

$$\begin{array}{lll}
\rho_0 &=& m_1 V_{10} & + m_2 V_{20} \\
&=& 50 \cdot | 0 & + m_2 - 0 \\
&=& 50 \cdot 0 & + m_3 \cdot 0 \\
&=& 50 \cdot 0 & + m_3 \cdot 0 \\
&=& 50 \cdot 0 & + m_3 \cdot 0 \\
&=& 50 \cdot 0 & + m_3 \cdot 0 \\
&=& 50 \cdot 0 & + m_3 \cdot 0 \\
&=& 125 \cdot 0 & + 2.5 \cdot 0 \\
&=& 125 \cdot 0 \cdot 0 \\
&=& 1$$

- An object of mass 3m, initially at rest, explodes breaking into two fragments of mass m and 2m, respectively. Which one of the following statements concerning the fragments after the explosion is true?
- A. They will fly off in the same direction.
- B. They will fly off at right angles.
- c. The smaller fragment will have twice the speed of the larger fragment.
- D. The larger fragment will have twice the speed of the smaller fragment.
- E. The smaller fragment will have four times the speed of the larger fragment.

- An object of mass 3m, initially at rest, explodes breaking into two fragments of mass m and 2m, respectively. Which one of the following statements concerning the fragments after the explosion is true?
- A. They will fly off in the same direction.
- B. They will fly off at right angles.
- C. The smaller fragment will have twice the speed of the larger fragment.
- The larger fragment will have twice the speed of the smaller fragment.
- E. The smaller fragment will have four times the speed of the larger fragment.

$$2m - V_2 - mV_1 = 0$$

$$2m V_2 = mV_1$$

$$V_2 = V_1/2$$

# **Rotational Motion**

### **Rotational Motion:**

$$\theta = s/r \qquad \langle \omega \rangle = \frac{\langle v_t \rangle}{r} = \frac{\Delta \theta}{\Delta t} \qquad \langle \alpha \rangle = \frac{\langle a_t \rangle}{r} = \frac{\Delta \omega}{\Delta t}$$

$$\theta(t) = \theta_o + \omega_o t + \frac{1}{2} \alpha t^2 \qquad \omega(t)^2 = \omega_o^2 + \tau$$

$$\tau = rF \sin \theta_{rF} = F * lever \ arm \qquad \sum \tau = I\alpha$$

$$W_{rot} = \tau \Delta \theta \qquad KE_{rot} = \frac{1}{2} I\omega^2$$

$$\langle \alpha \rangle = \frac{\langle a_t \rangle}{r} = \frac{\Delta \omega}{\Delta t}$$

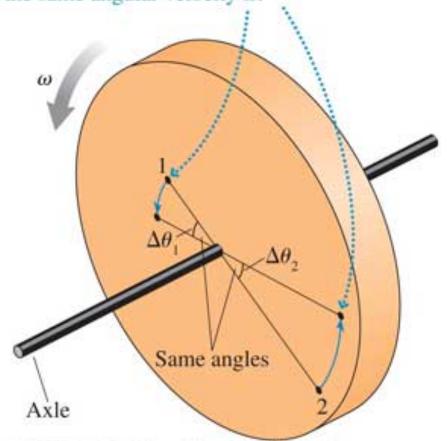
$$\omega(t)^2 = \omega_o^2 + 2\alpha \Delta \theta(t)$$

$$m \qquad \sum \tau = I\alpha \qquad \qquad L = mvr = I\omega$$

$$KE_{rot} = \frac{1}{2}I\omega^2 \qquad \qquad r_{CM} = \frac{\sum m_i r_i}{\sum m_i}$$

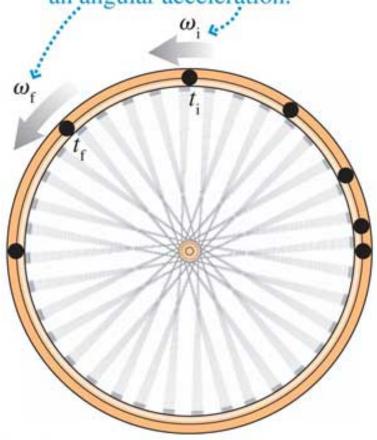
# **Rotational Kinematics**

Every point on the wheel undergoes circular motion with the same angular velocity  $\omega$ .



Copyright © 2007, Pearson Education, Inc., publishing as Pearson Addison-Wesley.

The angular velocity is *changing*, so the wheel has an angular acceleration.



Copyright © 2007, Pearson Education, Inc., publishing as Pearson Addison-Wesley.

During the spin-dry cycle of a washing machine, the motor slows from 5 rad/s to 3 rad/s while turning the drum through an angle of 4 radians. What is the magnitude of the angular acceleration of the motor?

- A.  $3 \text{ rad/s}^2$
- B.  $6 \text{ rad/s}^2$
- C. 1 rad/s²
- D. 2 rad/s<sup>2</sup>
- E. 10 rad/s<sup>2</sup>

During the spin-dry cycle of a washing machine, the motor slows from 5 rad/s to 3 rad/s while turning the drum through an angle of 4 radians. What is the magnitude of the angular acceleration of the motor?

- A.  $3 \text{ rad/s}^2$
- B.  $6 \text{ rad/s}^2$
- C. 1 rad/s<sup>2</sup>
- D.  $2 \text{ rad/s}^2$ 
  - E. 10 rad/s<sup>2</sup>

# Moment of Inertia

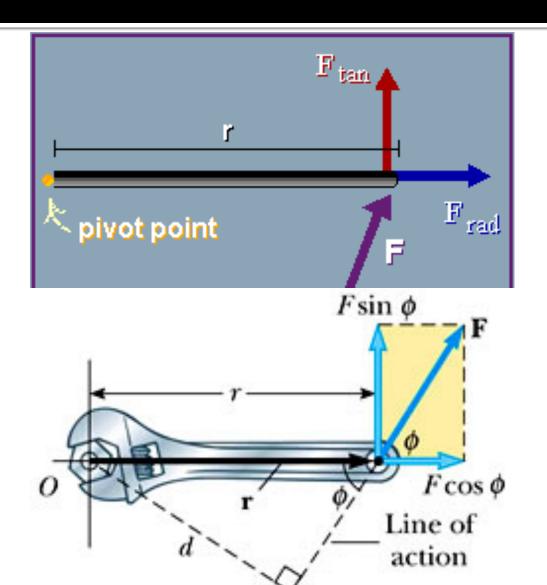
### **Moment of Inertia**

Point mass or thin-walled wheel:  $I = mr^2$  Solid cylinder:  $I = \frac{1}{2} mr^2$ Thin rod pivoting around end:  $I = \frac{1}{3} mr^2$  Solid sphere:  $I = \frac{2}{5} mr^2$ 

- Moment of inertia is a measure of how hard it is to change the angular velocity of an object
- The highest possible moment of inertia is for a point-mass (or hoop or wheel with all mass at rim)
  - Any other object has some mass at smaller radius so has a lower moment of inertia

 $6x^{2} = 6x^{2} + 2x + 2x + 4$   $3^{2} = 5^{2} + 2x + 4$  4 = 25 + 8x -16 = 8x x = -2 x = -2

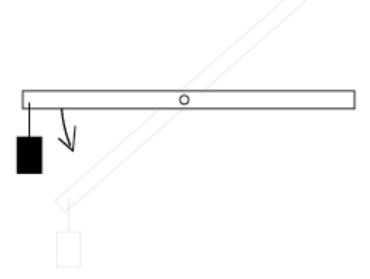
# **Torque**



d = lever arm in this image

A mass is hanging from the end of a horizontal bar which pivots about an axis through it center, but it being held stationary. The bar is released and begins to rotate. As the bar rotates from horizontal to vertical, the magnitude of the torque on the bar..

A) increases B) decreases C) remains constant

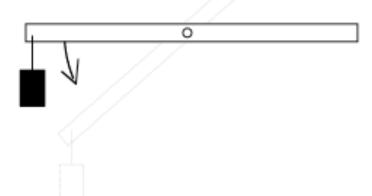


A mass is hanging from the end of a horizontal bar which pivots about an axis through it center, but it being held stationary. The bar is released and begins to rotate. As the bar rotates from horizontal to vertical, the magnitude of the torque on the bar..

A) increases

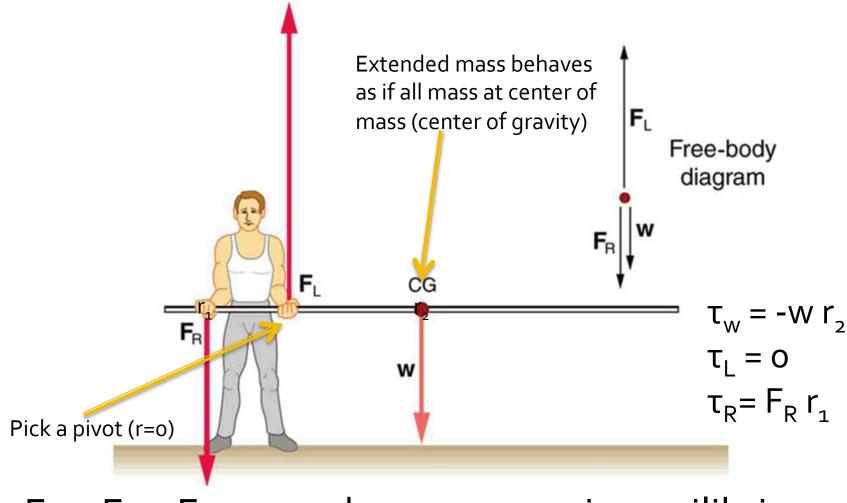
B) decreases

C) remains constant



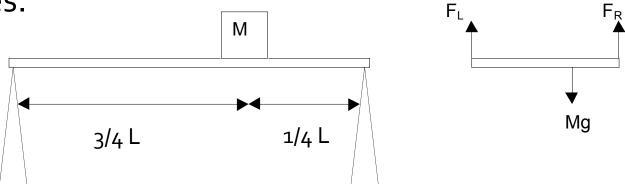
Fle Plant Pl

# **Equilibrium & Statics**



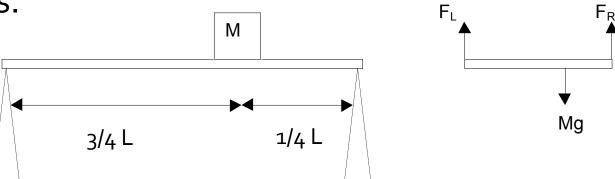
 $F_R + F_L + F_w = o$  and  $\tau_w + \tau_R + \tau_L = o$  in equilibrium

 A mass M is placed on a very light board supported at the ends, as shown. The free-body diagram shows directions of the forces, but not their correct relative sizes.



- What is the ratio  $F_R/F_L$ ?
- **B**: 4 **C**: 1/3 **D**: 3
- E: some other answer

 A mass M is placed on a very light board supported at the ends, as shown. The free-body diagram shows directions of the forces, but not their correct relative sizes.



• What is the ratio  $F_R/F_L$ ?

**A**: 3/4 **B**: 4

E: some other answer

**C**: 1/3

**D**: 3

Pivat @ M M 1 349 FL FR

 $\sum T = 0$   $= |T_L| = |T_R|$   $F_L \cdot 3/4 = F_R - 1/4$   $F_R = 3F_L$ Also  $F_R + F_L = M_g$