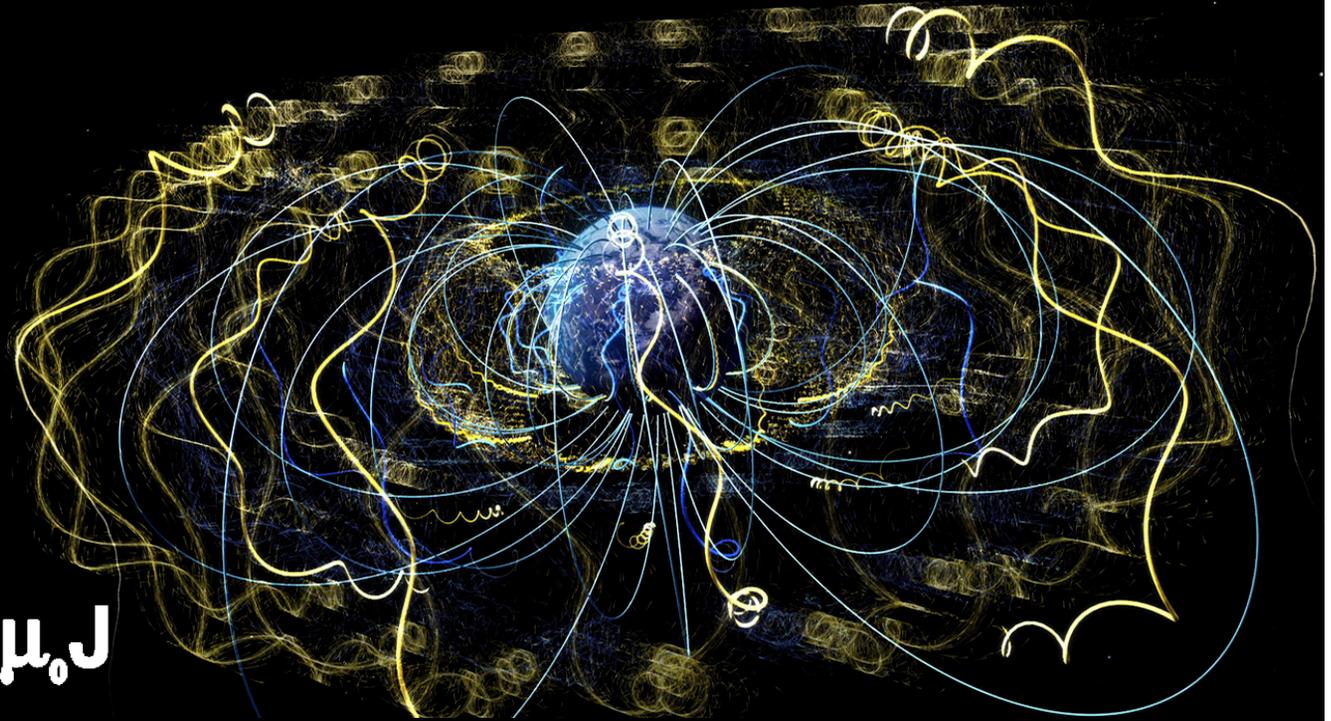


$$\nabla \cdot \mathbf{E} = \frac{\rho}{\epsilon_0}$$

$$\nabla \cdot \mathbf{B} = 0$$

$$\nabla \times \mathbf{E} = -\frac{\partial \mathbf{B}}{\partial t}$$

$$\nabla \times \mathbf{B} = \mu_0 \epsilon_0 \frac{\partial \mathbf{E}}{\partial t} + \mu_0 \mathbf{J}$$



Electricity and Magnetism I: 3811

Professor Jasper Halekas
Van Allen 301
MWF 9:30-10:20 Lecture

Announcements

- Last year's final exam posted on course website
 - Solutions will follow next week
- Next Week
 - Monday: Guest lecture w/ Prof. Craig Kletzing
 - Wednesday: Problem session w/ Mr. Gian Andreone
 - Friday: Final Review (w/ me)
- Finals week
 - Additional office hours to be announced

Announcements II

- Course Evaluations are now open
 - Please take a few minutes to fill these out
 - The course evaluations are very valuable for me – and potentially for you as well
 - I read all evaluations carefully, and use them to improve my teaching

Boundary Conditions

$$\Delta B_{\perp} = 0$$

$$\Delta \vec{B}_{\parallel} = \mu_0 \vec{K} \times \hat{n}$$

$$\Delta H_{\perp} = -\Delta M_{\perp}$$

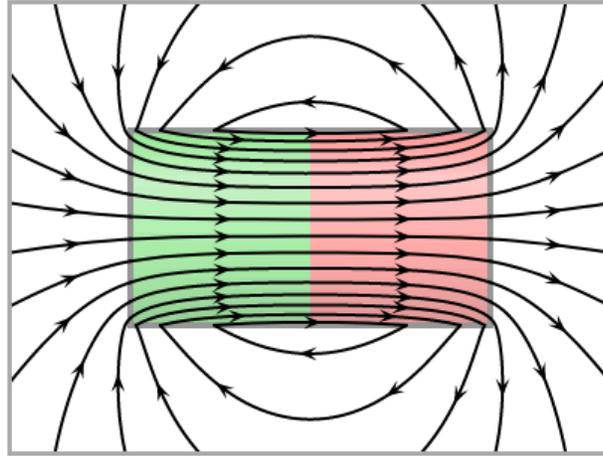
$$\Delta \vec{H}_{\parallel} = \vec{K}_f \times \hat{n}$$

- B continuous
- H can have discontinuities at boundaries at \vec{M}
- B can change its tangential component at currents
- H can only change its tangential component at free currents

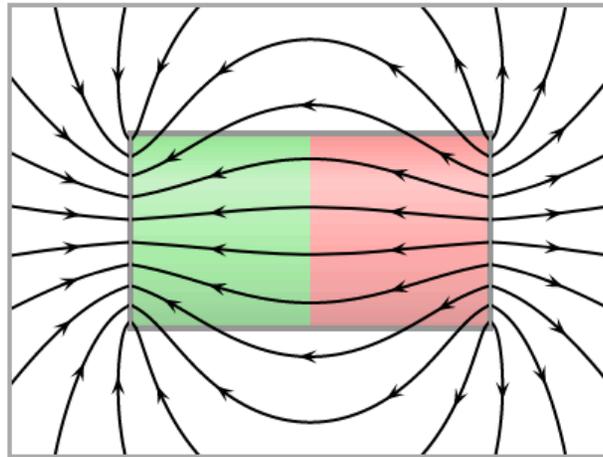
B, H, M



\vec{M}



\vec{B}



\vec{H}

Linear Media

$$\vec{M} = \chi_m \vec{H}$$

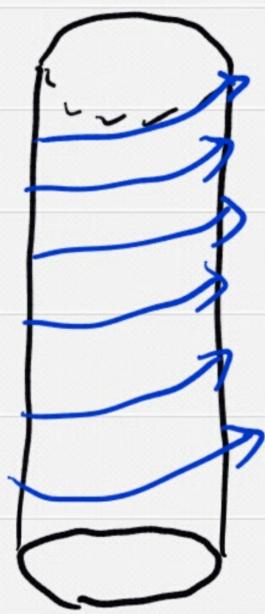
χ_m = "magnetic susceptibility"
positive = paramagnetic
negative = diamagnetic

$$\begin{aligned}\vec{B} &= \mu_0 (\vec{H} + \vec{M}) \\ &= \mu_0 (1 + \chi_m) \vec{H} \\ &= \mu \vec{H}\end{aligned}$$

w/ $\mu = \mu_0 (1 + \chi_m)$ = "permeability"

Example

Solenoid w/ linear core



$$\vec{H} = n I \hat{z}$$

from Ampere's law

$$\vec{B} = \mu \vec{H}$$

$$= \mu \cdot (1 + \chi_m) n I \hat{z}$$

$\chi_m > 0$ increases \vec{B}

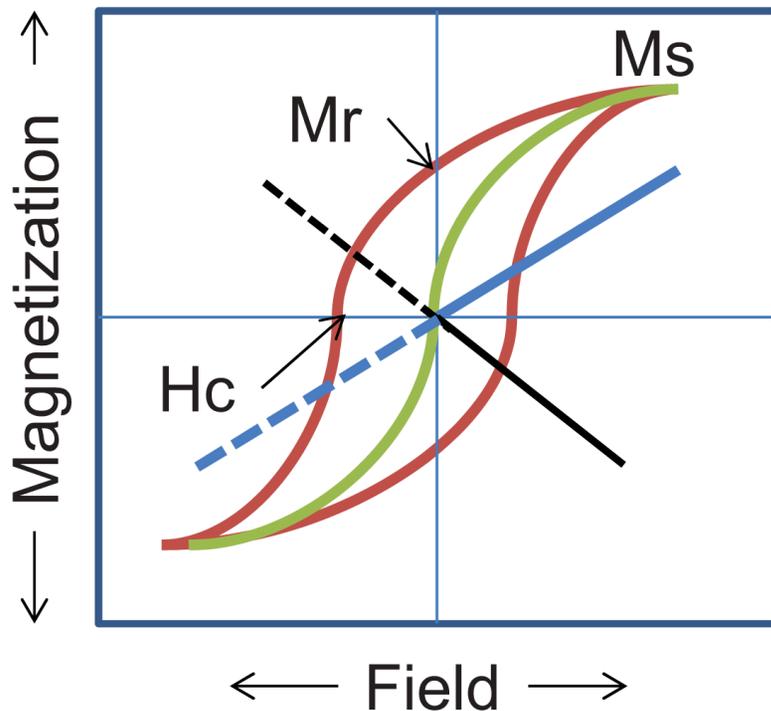
$\chi_m < 0$ decreases \vec{B}

$$\begin{aligned} \vec{K}_b &= \vec{M} \times \hat{n} = \chi_m \vec{H} \times \hat{n} \\ &= \chi_m n I \hat{\phi} \\ &= \chi_m \frac{NI}{L} \hat{\phi} \\ &= \chi_m \vec{K}_f \end{aligned}$$

parallel to \vec{K}_f for $\chi_m > 0$
anti-parallel for $\chi_m < 0$

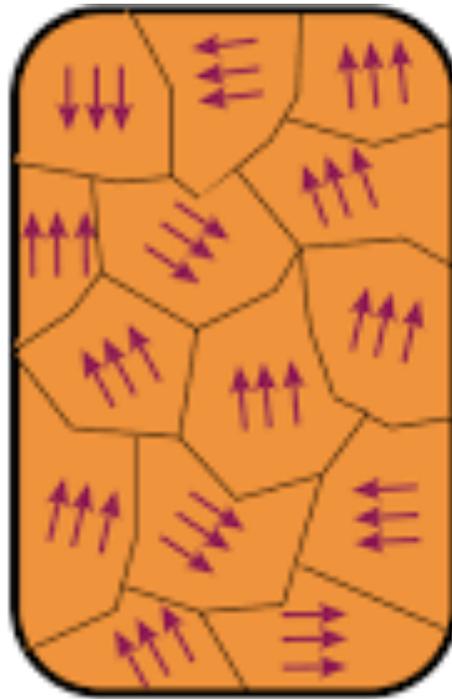
- paramagnetic (or ferromagnetic) core very useful for transformers, inductors, etc.

Magnetic Classification

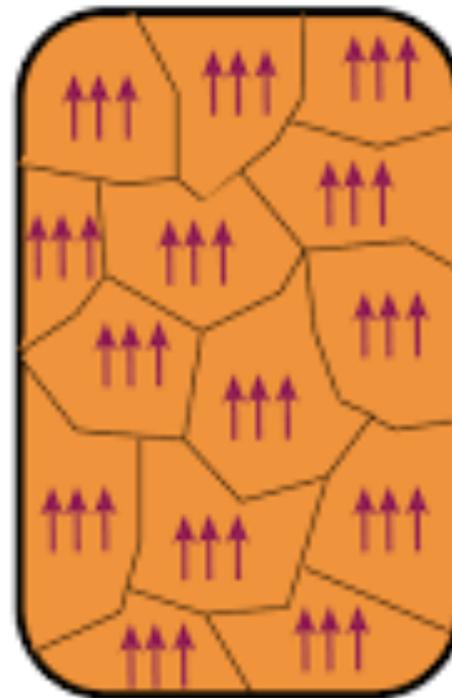


- Ferromagnetic
- Superparamagnetic
- Paramagnetic
- Diamagnetic

Ferromagnetism



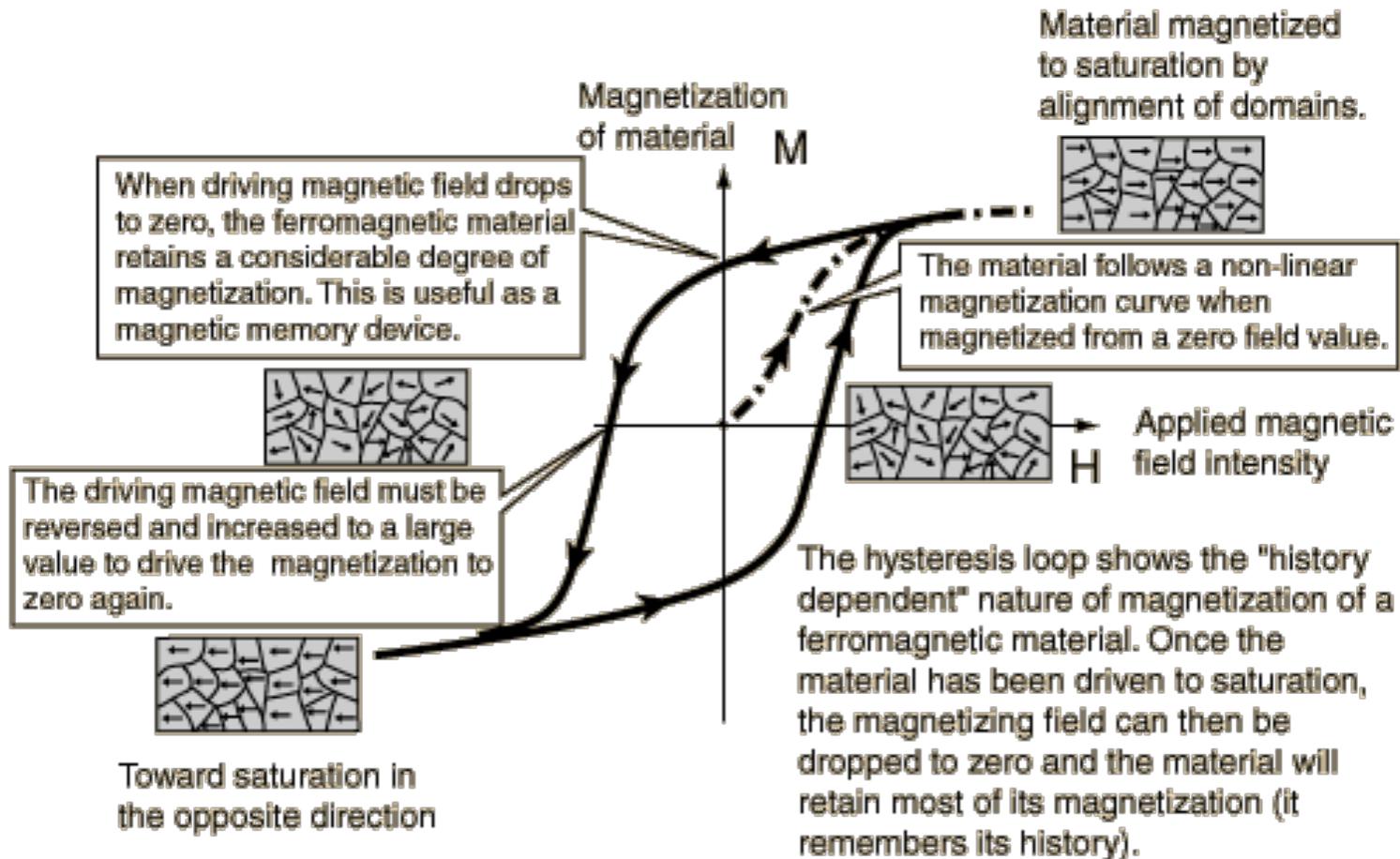
Domains
randomly
aligned



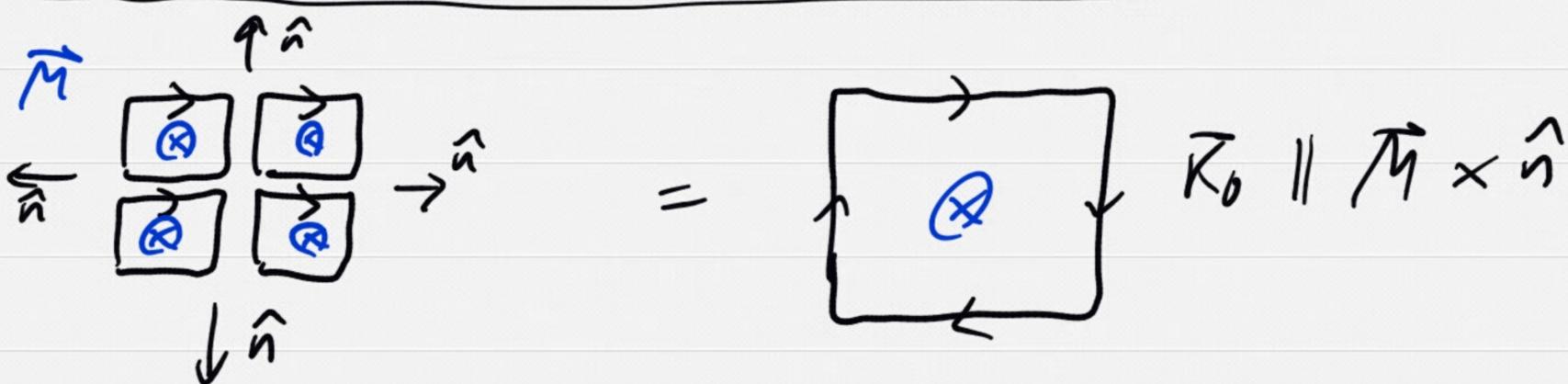
Domains
aligned with
external field



Magnetic Hysteresis

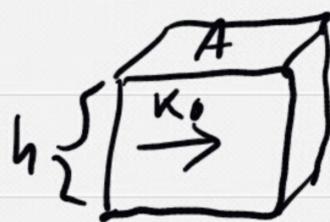


Surface Bound Current



Total current:

$$I = K_0 h$$

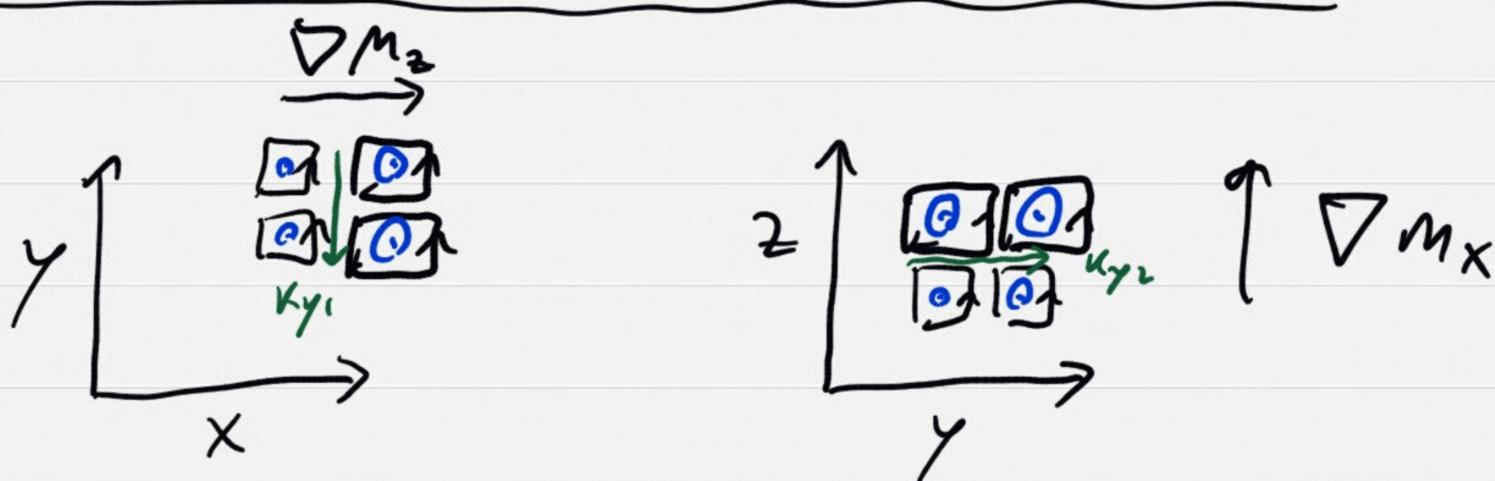


But $I = \frac{m}{A}$

$$= \frac{M \cdot \text{Vol.}}{A} = \frac{M \cdot A \cdot h}{A} = M h$$

$$\Rightarrow |\vec{M}| = |\vec{K}_0| //$$

Volume Bound Current



$$k_{y1} = \frac{F_{y1}}{\Delta z} = M_z(x) - M_z(x + \Delta x) \\ = -\frac{\partial M_z}{\partial x} \cdot \Delta x$$

$$k_{y2} = \frac{F_{y2}}{\Delta x} = M_x(z + \Delta z) - M_x(z) \\ = \frac{\partial M_x}{\partial z} \cdot \Delta z$$

$$k_y = \frac{F_{y1}}{\Delta z} + \frac{F_{y2}}{\Delta x}$$

$$\bar{J}_y = \frac{I_{y1} + I_{y2}}{\Delta x \Delta z}$$

$$= \left(\frac{\partial M_x}{\partial z} - \frac{\partial M_z}{\partial x} \right)$$

$$= (\nabla \times \vec{M})_y$$

$$\Rightarrow \vec{J}_b = \nabla \times \vec{M} //$$