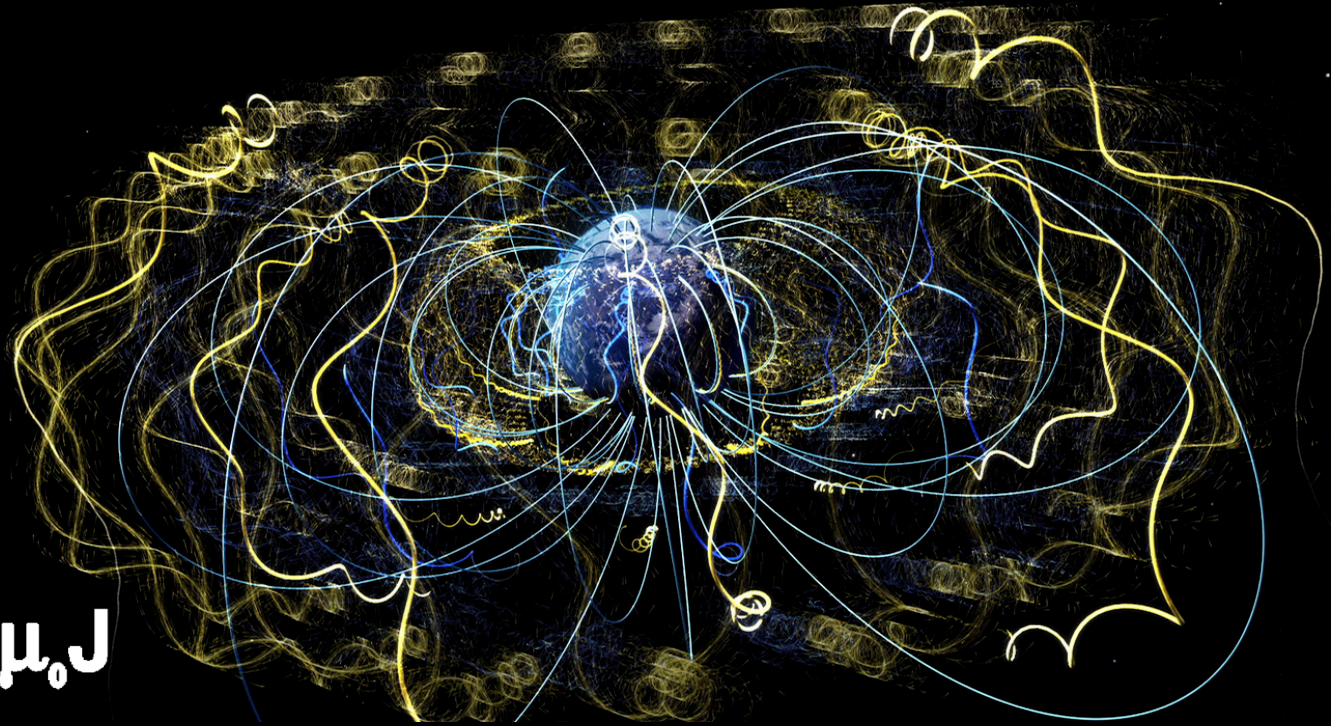


$$\nabla \cdot \mathbf{E} = \frac{\rho}{\epsilon_0}$$

$$\nabla \cdot \mathbf{B} = 0$$

$$\nabla \times \mathbf{E} = -\frac{\partial \mathbf{B}}{\partial t}$$

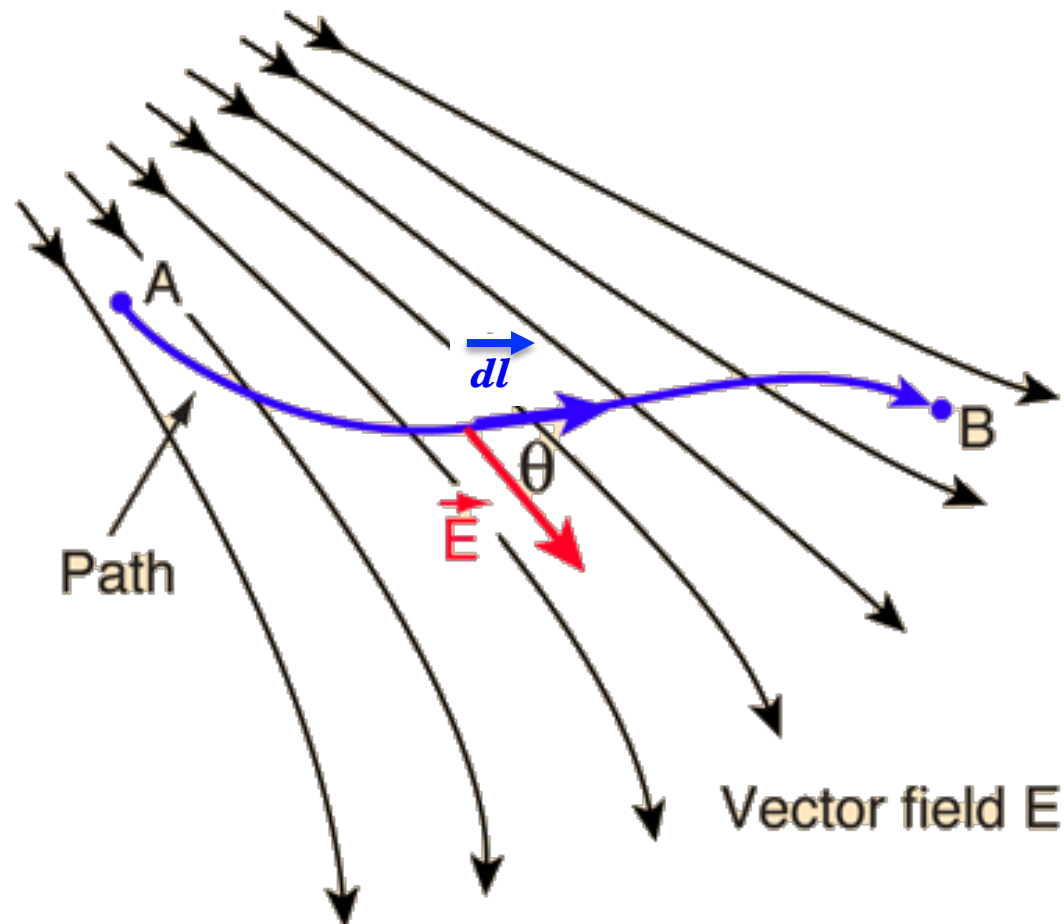
$$\nabla \times \mathbf{B} = \mu_0 \epsilon_0 \frac{\partial \mathbf{E}}{\partial t} + \mu_0 \mathbf{J}$$



Electricity and Magnetism I: 3811

Professor Jasper Halekas
Van Allen 301
MWF 9:30-10:20 Lecture

Line Integrals



Line Integrals

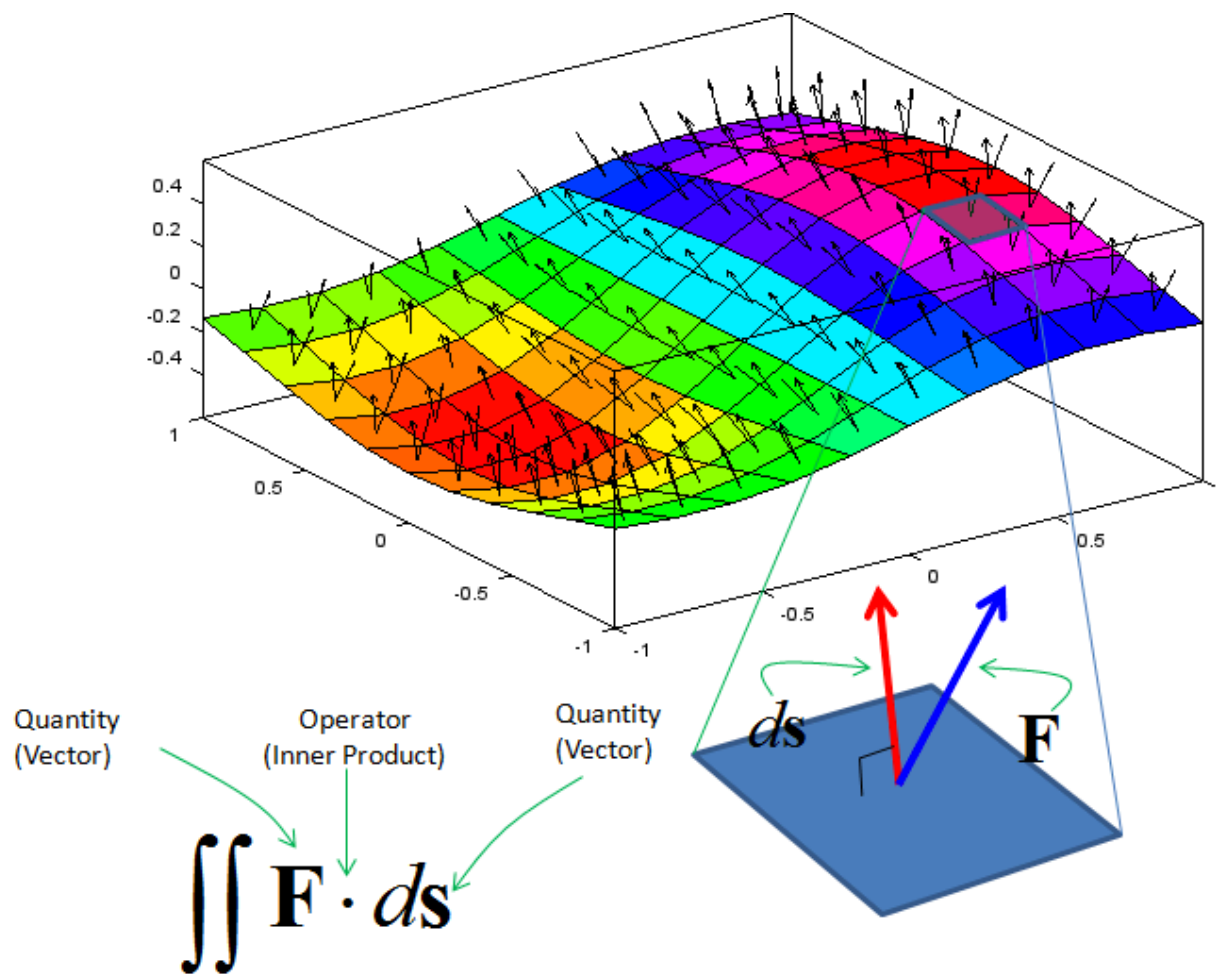
$$\int_{\vec{a}}^{\vec{b}} \vec{A} \cdot d\vec{x}$$

$$d\vec{x} = [dx, dy, dz]$$

$$\Rightarrow \int_{\vec{a}}^{\vec{b}} (A_x dx + A_y dy + A_z dz)$$

- Looks like a simple scalar integral
- But \vec{A} and $d\vec{x}$ depend on the path
- So $\int_{\vec{a}}^{\vec{b}} \vec{A} \cdot d\vec{x}$ in general depends on the path between \vec{a} and \vec{b}

Surface Integrals



Surface Integrals

$$\int_S \vec{A} \cdot d\vec{a} = \int_S \vec{A} \cdot \hat{n} da$$

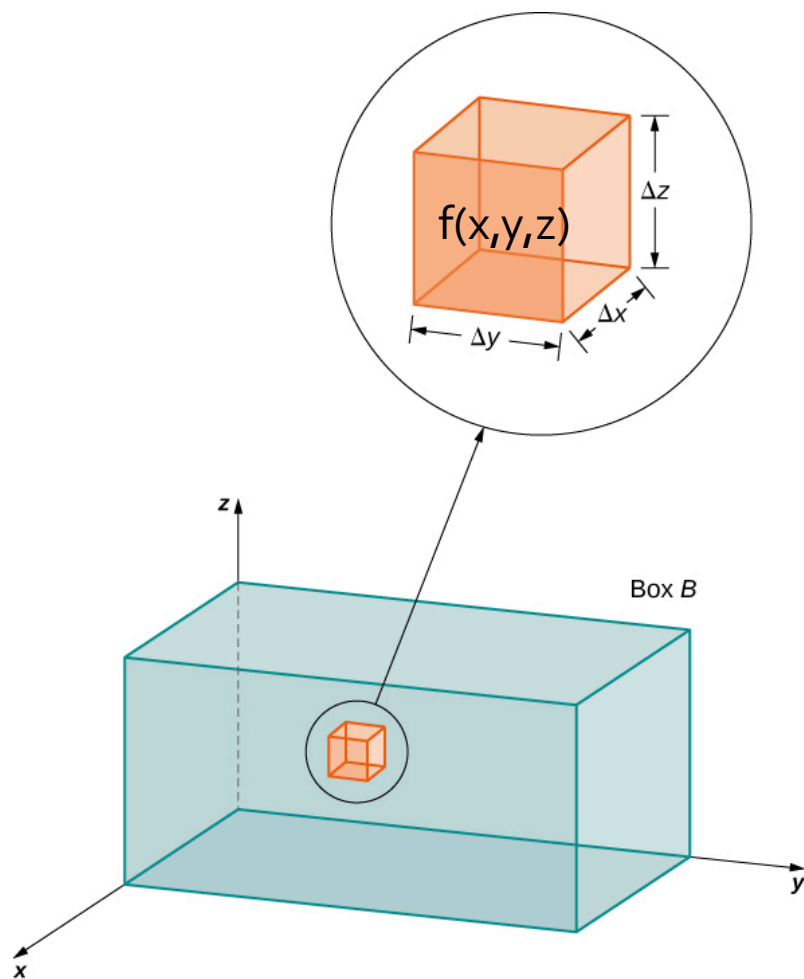
w/ \hat{n} = normal
to surface $d\vec{a}$

- often explicitly written

$$\iint \vec{A} \cdot d\vec{a}$$

- $\vec{A}, d\vec{a}$ both depend on surface orientation
- In general $\int \vec{A} \cdot d\vec{a}$ depends on shape of surface S

Volume Integrals



Volume Integrals

$$\int_V f \, d\tau \quad \text{or} \quad \int_V f \, dV$$

$$\text{w/ } d\tau = dx \, dy \, dz$$

— Can also explicitly write
 $\iiint f \, d\tau$

— Easier than line or surface integrals since no dot products

— Still tricky for complex shapes

Fundamental Theorem of Calculus

$$\int_a^b \left(\frac{df}{dx} \right) dx = \int_a^b df = f(b) - f(a)$$

Fundamental Theorem: Gradients

$$\int_{\vec{a}}^{\vec{b}} \nabla f \cdot d\vec{x} = \int_{\vec{a}}^{\vec{b}} df = f(\vec{b}) - f(\vec{a})$$

- Independent of path $\vec{a} \rightarrow \vec{b}$
- Total elevation gain independent of path

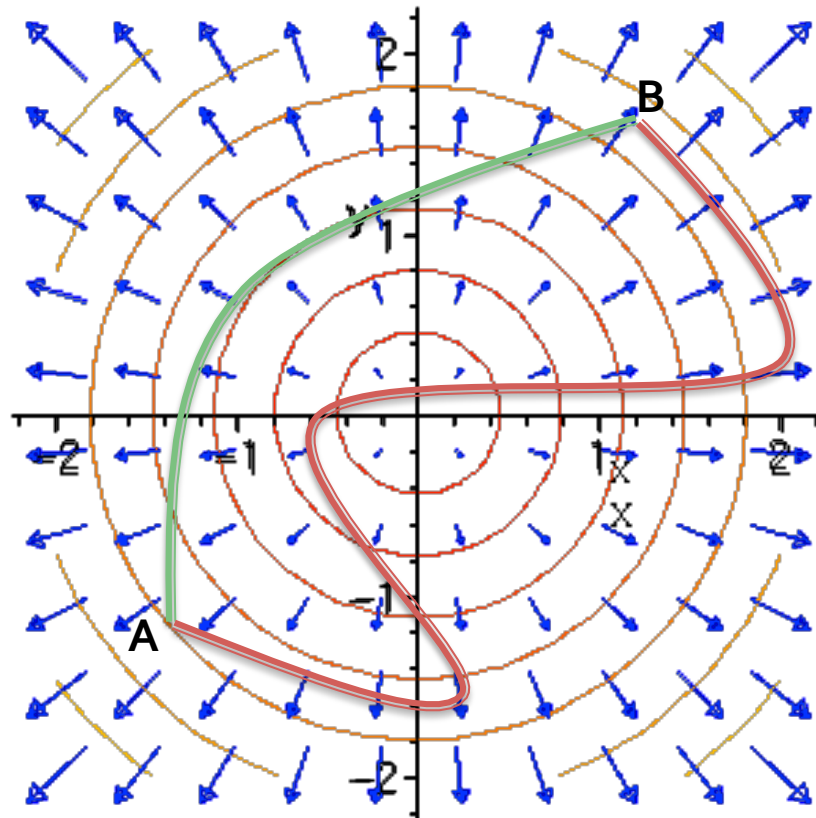
Divergence Theorem

$$\int_V (\nabla \cdot \vec{A}) d\tau = \oint_S \vec{A} \cdot d\vec{a}$$

w/ S = closed surface
that bounds volume V

- Total divergence in volume equal to flux through surface

Gradient Theorem

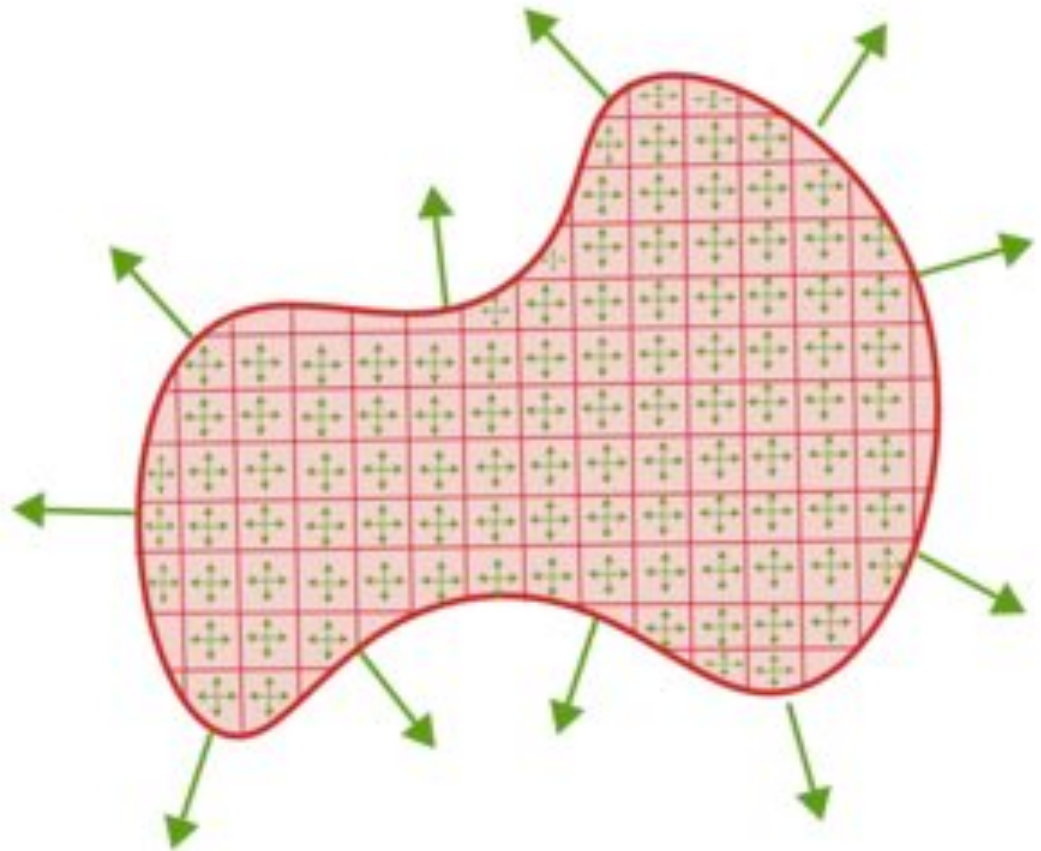
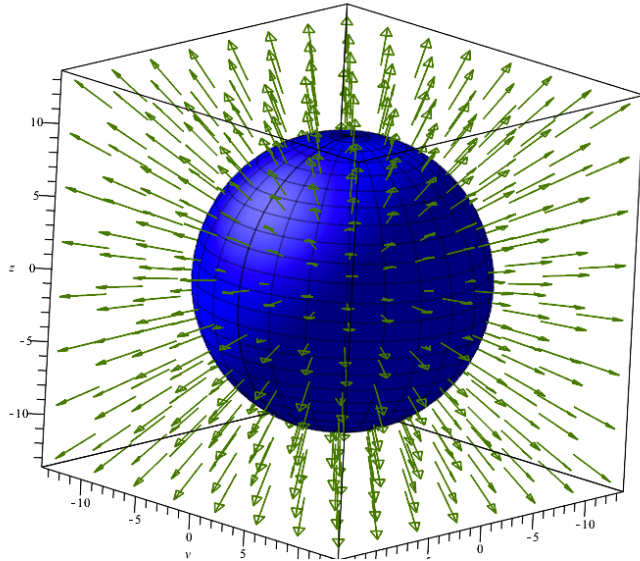


Total of
slope*distance =
total elevation
change

Net elevation
gain does not
depend on path!

$$\int_C \nabla f \cdot ds = f(B) - f(A)$$

Divergence Theorem



$$\iint \nabla \cdot \mathbf{F} dA$$
$$= \int_C \mathbf{F} \cdot \hat{\mathbf{n}} ds$$

Total divergence in volume = total
outward flux through bounding surface

Stokes' Theorem

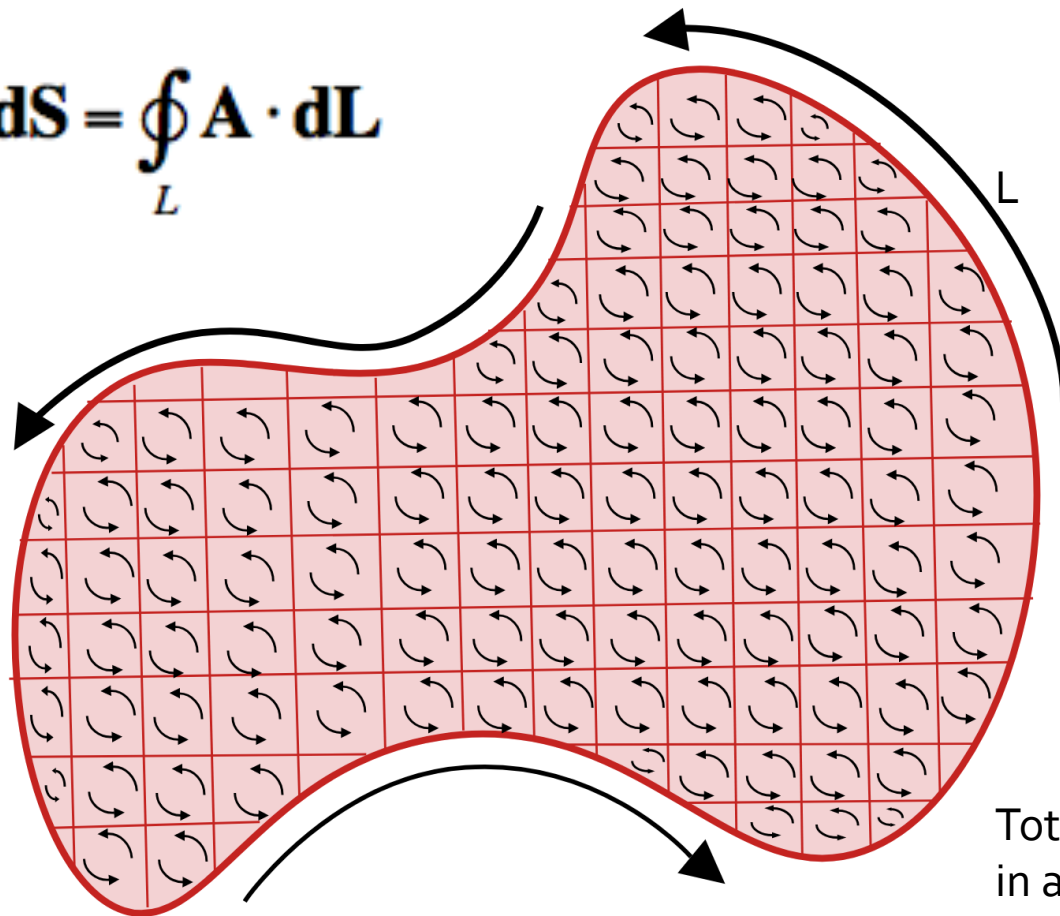
$$\int_S (\nabla \times \vec{A}) \cdot d\vec{a} = \oint_P \vec{A} \cdot d\vec{\ell}$$

w/ P the closed loop
around surface S

- Total circulation
in area equal to
flow around boundary
- Independent of shape
of S

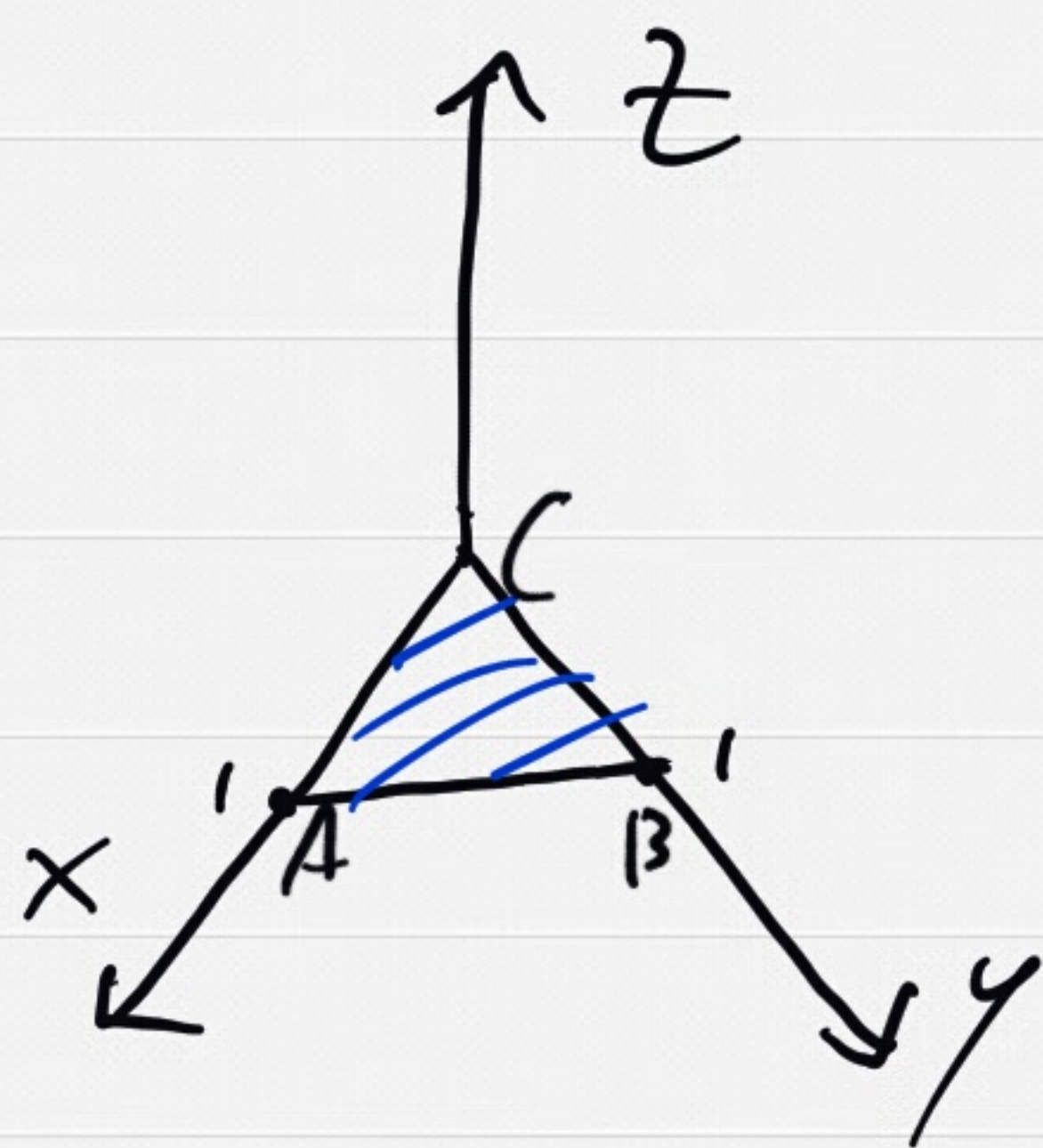
Stokes' Theorem

$$\int (\nabla \times \mathbf{A}) \cdot d\mathbf{S} = \oint_L \mathbf{A} \cdot d\mathbf{L}$$



Total circulation
in area =
total circulation
around perimeter

Example



Check Stokes' Theorem for path ABC

$$w/ \vec{A}(x, y, z) = xy \hat{x}$$

$$1. \quad \nabla \times \vec{A} = \begin{vmatrix} \hat{x} & \hat{y} & \hat{z} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ xy & 0 & 0 \end{vmatrix}$$

$$= 0 \hat{x} + 0 \hat{y} - \frac{\partial}{\partial y}(xy) \hat{z}$$

$$= -x \hat{z}$$

$$\int_S (\nabla \times \vec{A}) \cdot d\vec{a}$$

$$= \int_S (-x \hat{z}) \cdot d\vec{a}$$

$$= \int_S (-x) da \quad \text{since } d\vec{a} = da \hat{z} \text{ for path ABC by right hand rule}$$

$$= \int_S (-x) dx dy$$

$$= \int_0^1 \left(\int_0^{1-x} (-x) dy \right) dx$$

$$= \int_0^1 (-xy \big|_0^{1-x}) dx$$

$$= \int_0^1 -x(1-x) dx$$

$$= \left(-x^2/2 + x^3/3 \right) \big|_0^1$$

$$= \boxed{-1/6} \quad \hookrightarrow$$

$$\int \vec{A} \cdot d\vec{r} = \int_{AB} \vec{A} \cdot d\vec{r} + \int_{BC} \vec{A} \cdot d\vec{r} + \int_{CA} \vec{A} \cdot d\vec{r}$$

$$\begin{aligned} \int_{AB} \vec{A} \cdot d\vec{r} &= \int_{AB} (xy\hat{x}) \cdot (\hat{x}dx + \hat{y}dy + \hat{z}dz) \\ &= \int_{AB} xy dx \end{aligned}$$

Use dummy variable t

$$\begin{aligned} \text{on path } AB, \quad x &= 1-t, \quad y = t \\ \Rightarrow dx &= -dt \end{aligned}$$

$$\begin{aligned} \text{So } \int_{AB} \vec{A} \cdot d\vec{r} &= \int_0^1 (1-t) \cdot t \cdot -dt \\ &= \int_0^1 (t^2 - t) dt \\ &= \left(\frac{t^3}{3} - \frac{t^2}{2} \right) \Big|_0^1 \\ &= -\frac{1}{6} \end{aligned}$$

$$\int_{BC} \vec{A} \cdot d\vec{r} = 0 \quad \text{since } \vec{A} = 0 \quad \text{on path } BC$$

$$\int_{CA} \vec{A} \cdot d\vec{r} = 0 \quad \text{since } \vec{A} = 0 \quad \text{on path } CA$$

$$\Rightarrow \int_{ABC} \vec{A} \cdot d\vec{r} = \boxed{-\frac{1}{6}} //$$