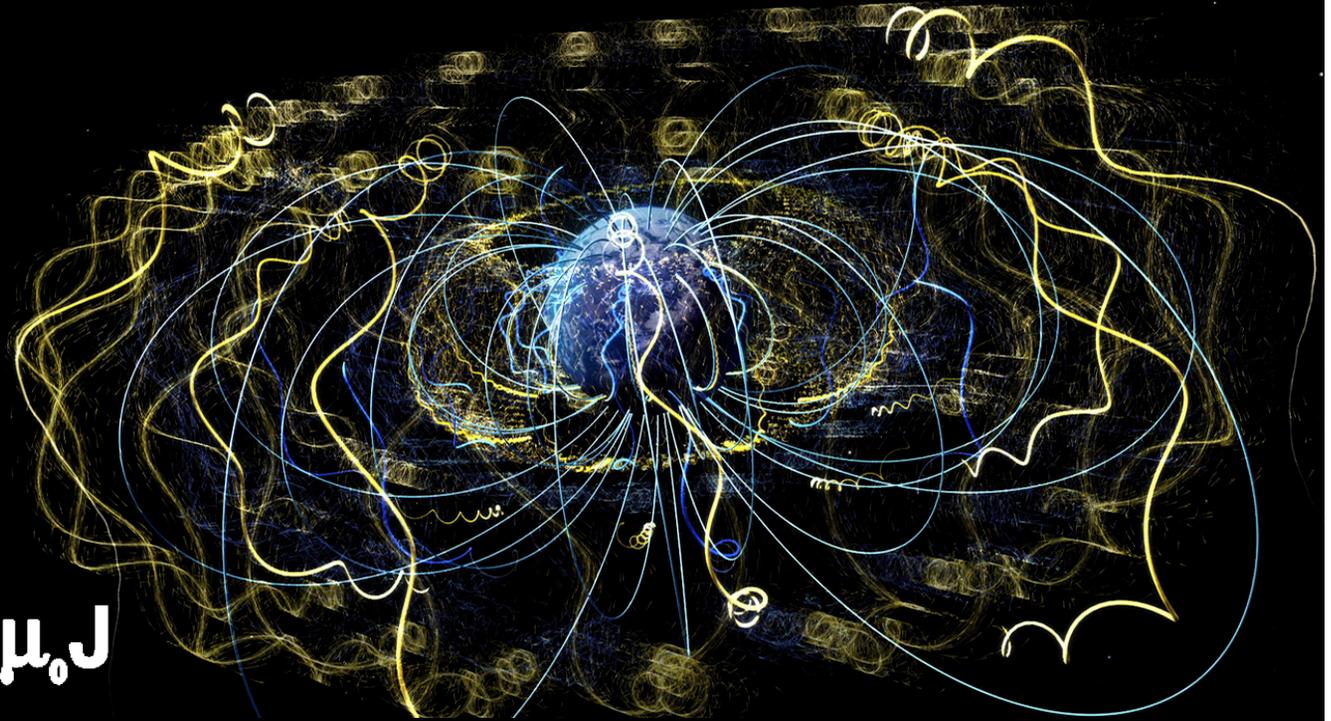


$$\nabla \cdot \mathbf{E} = \frac{\rho}{\epsilon_0}$$

$$\nabla \cdot \mathbf{B} = 0$$

$$\nabla \times \mathbf{E} = -\frac{\partial \mathbf{B}}{\partial t}$$

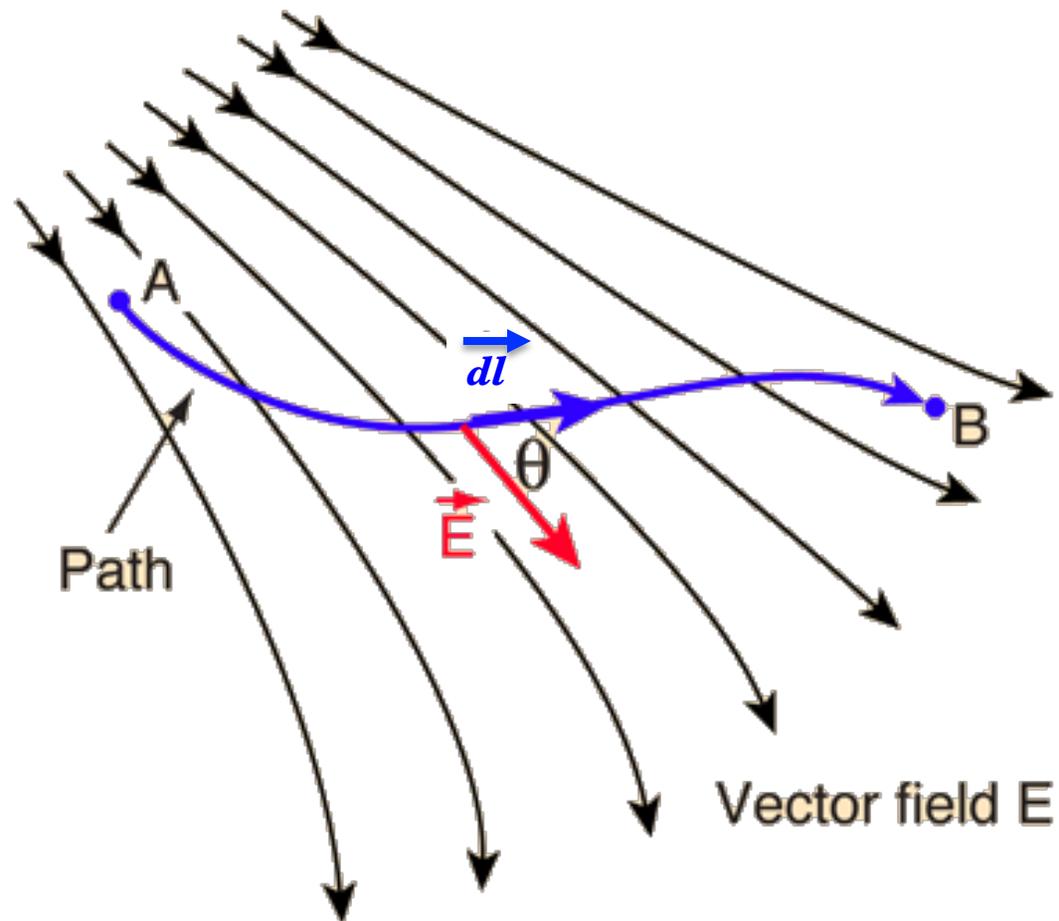
$$\nabla \times \mathbf{B} = \mu_0 \epsilon_0 \frac{\partial \mathbf{E}}{\partial t} + \mu_0 \mathbf{J}$$



# Electricity and Magnetism I: 3811

Professor Jasper Halekas  
Van Allen 301  
MWF 9:30-10:20 Lecture

# Line Integrals



# Line Integrals

$$\int_{\vec{a}}^{\vec{b}} \vec{A} \cdot d\vec{l}$$

$$d\vec{l} = [dx, dy, dz]$$

$$\Rightarrow \int_{\vec{a}}^{\vec{b}} (A_x dx + A_y dy + A_z dz)$$

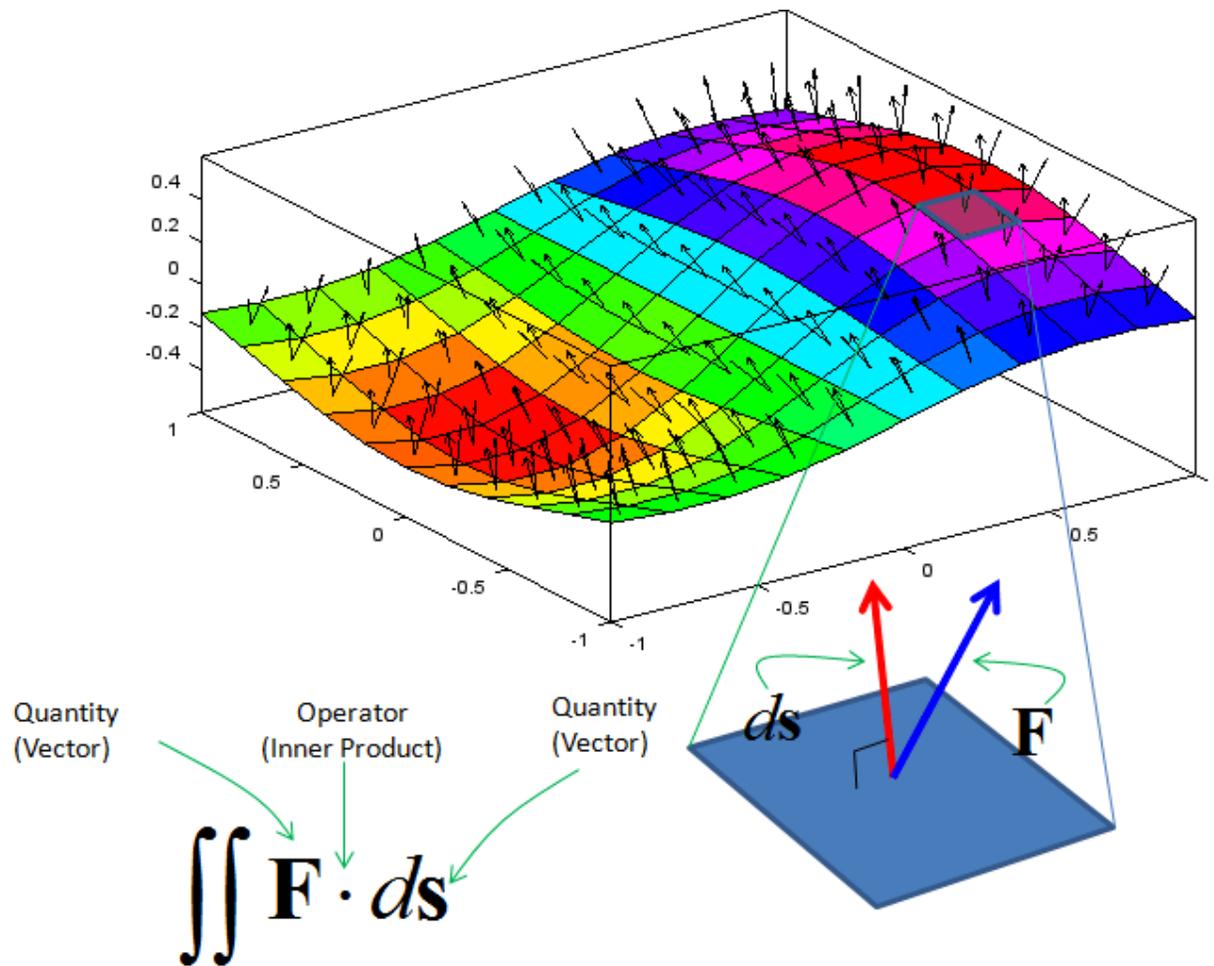
- Looks like a simple scalar integral

- But  $\vec{A}$  and  $d\vec{l}$  depend on the path

- So  $\int_{\vec{a}}^{\vec{b}} \vec{A} \cdot d\vec{l}$  in general

depends on the path between  $\vec{a}$  and  $\vec{b}$

# Surface Integrals



# Surface Integrals

$$\int_S \vec{A} \cdot d\vec{a} = \int_S \vec{A} \cdot \hat{n} da$$

w/  $\hat{n}$  = normal  
to surface  $d\vec{a}$

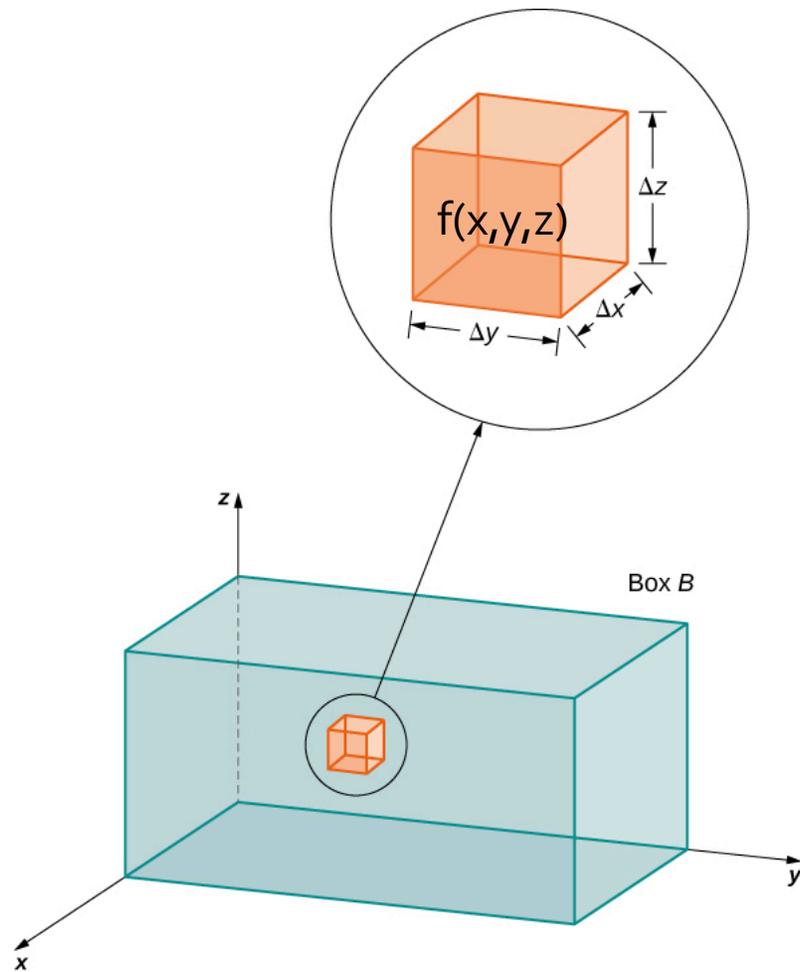
- often explicitly written

$$\iint \vec{A} \cdot d\vec{a}$$

-  $\vec{A}$ ,  $d\vec{a}$  both depend on  
surface orientation

- In general  $\int \vec{A} \cdot d\vec{a}$  depends  
on shape of surface  $S$

# Volume Integrals



## Volume Integrals

$$\int_V f \, d\tau \quad \text{or} \quad \int_V f \, dV$$

$$\text{w/ } d\tau = dx \, dy \, dz$$

- Can also explicitly write  
 $\iiint f \, d\tau$

- Easier than line or surface integrals since no dot products

- Still tricky for complex shapes

## Fundamental Theorem of Calculus

$$\int_a^b \left(\frac{df}{dx}\right) dx = \int_a^b df = f(b) - f(a)$$

## Fundamental Theorem: Gradients

$$\int_{\vec{a}}^{\vec{b}} \nabla f \cdot d\vec{x} = \int_{\vec{a}}^{\vec{b}} df = f(\vec{b}) - f(\vec{a})$$

- Independent of path  $\vec{a} \rightarrow \vec{b}$
- Total elevation gain independent of path

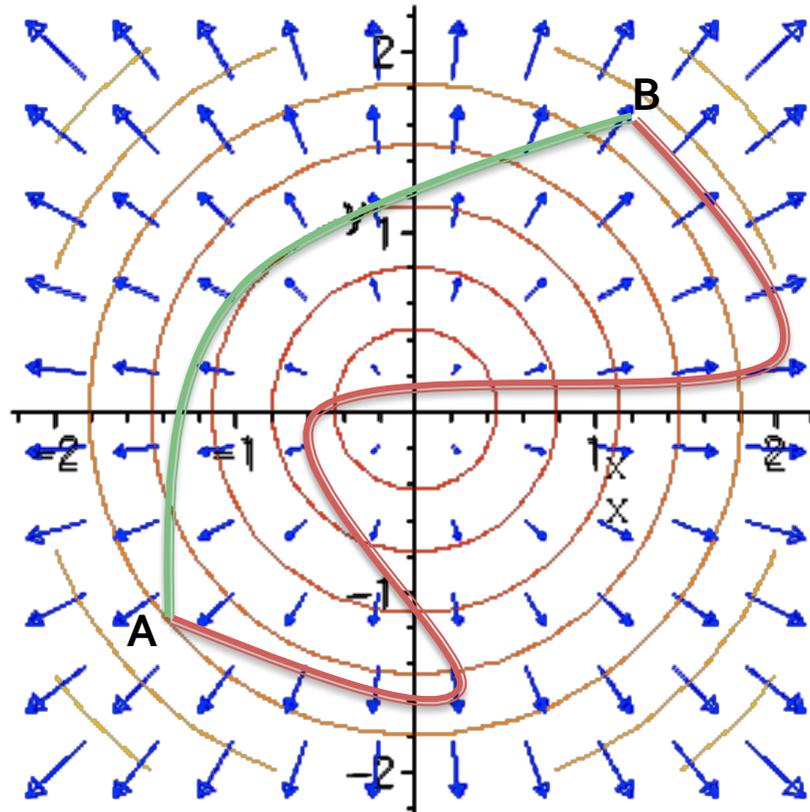
## Divergence Theorem

$$\int_V (\nabla \cdot \vec{A}) d\tau = \oint_S \vec{A} \cdot d\vec{a}$$

w/  $S$  = closed surface that bounds volume  $V$

- Total divergence in volume equal to flux through surface

# Gradient Theorem

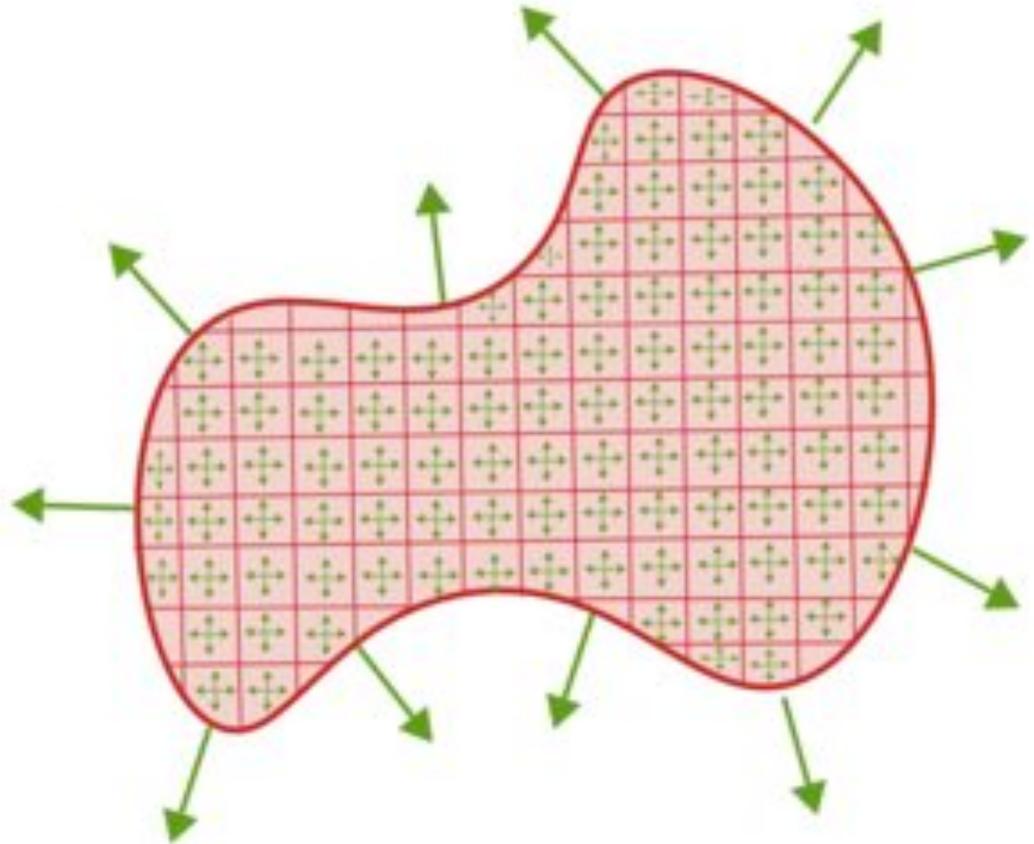
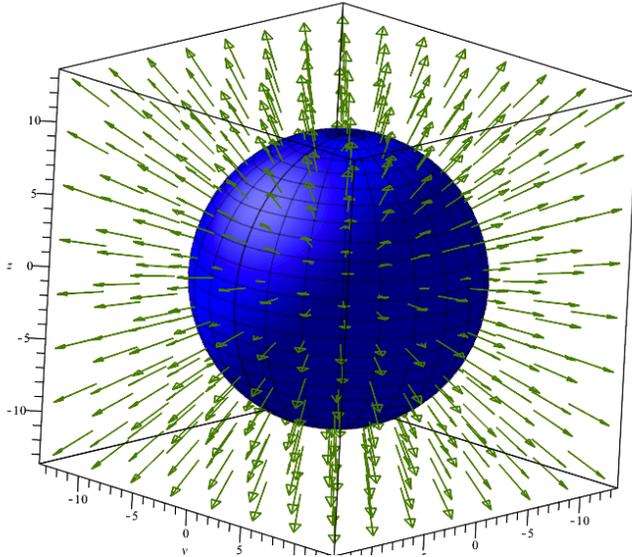


Total of  
slope\*distance =  
total elevation  
change

Net elevation  
gain does not  
depend on path!

$$\int_C \nabla f \cdot ds = f(B) - f(A)$$

# Divergence Theorem



$$\iint \nabla \cdot \mathbf{F} dA$$
$$= \int_C \mathbf{F} \cdot \hat{\mathbf{n}} ds$$

Total divergence in volume = total outward flux through bounding surface

## Stokes' Theorem

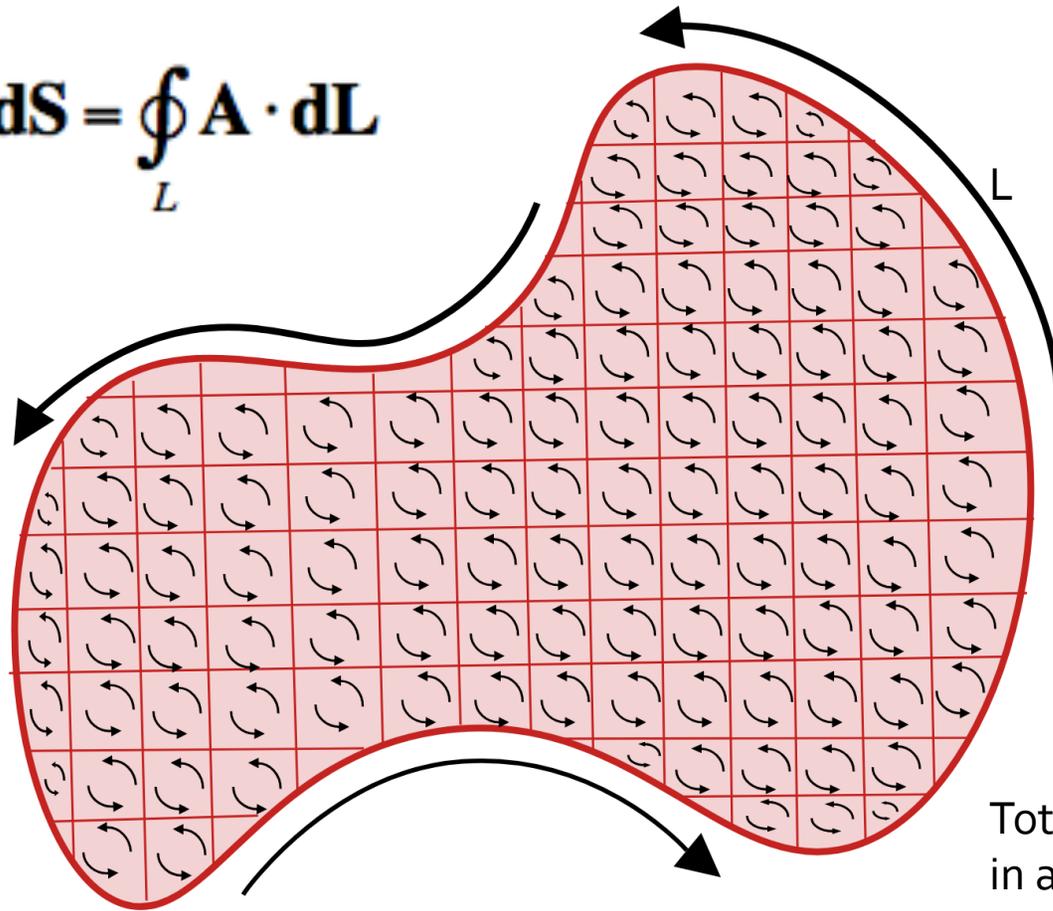
$$\int_S (\nabla \times \vec{A}) \cdot d\vec{a} = \oint_P \vec{A} \cdot d\vec{l}$$

w/  $P$  the closed loop  
around surface  $S$

- Total circulation  
in area equal to  
flow around boundary
- Independent of shape  
of  $S$

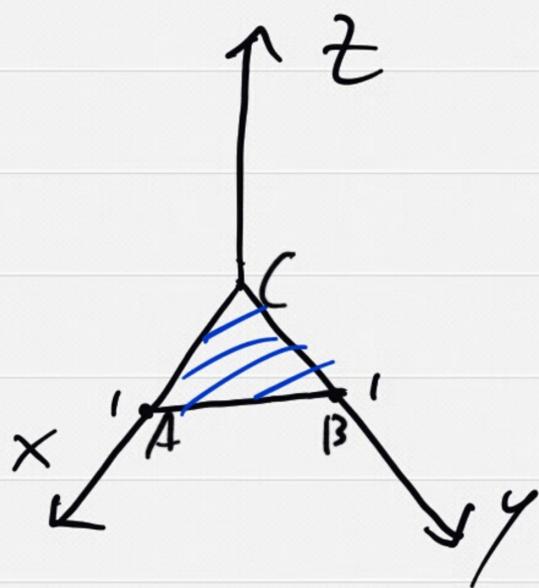
# Stokes' Theorem

$$\int (\nabla \times \mathbf{A}) \cdot d\mathbf{S} = \oint_L \mathbf{A} \cdot d\mathbf{L}$$



Total circulation  
in area =  
total circulation  
around perimeter

# Example



Check Stokes' Theorem for path ABC

$$w/ \vec{A}(x, y, z) = xy \hat{x}$$

$$1. \quad \nabla \times \vec{A} = \begin{vmatrix} \hat{x} & \hat{y} & \hat{z} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ xy & 0 & 0 \end{vmatrix}$$

$$= 0 \hat{x} + 0 \hat{y} - \frac{\partial}{\partial y}(xy) \hat{z}$$

$$= -x \hat{z}$$

$$\int_S (\nabla \times \vec{A}) \cdot d\vec{a}$$

$$= \int_S (-x \hat{z}) \cdot d\vec{a}$$

$$= \int_S (-x) da \quad \text{since } d\vec{a} = da \hat{z} \text{ for path ABC by right hand rule}$$

$$= \int_S (-x) dx dy$$

$$= \int_0^1 \left( \int_0^{1-x} (-x) dy \right) dx$$

$$= \int_0^1 (-xy \Big|_0^{1-x}) dx$$

$$= \int_0^1 -x(1-x) dx$$

$$= \left( -\frac{x^2}{2} + \frac{x^3}{3} \right) \Big|_0^1$$

$$= \frac{-1}{6} \curvearrowright$$

$$\int \vec{A} \cdot d\vec{l} = \int_{AB} \vec{A} \cdot d\vec{l} + \int_{BC} \vec{A} \cdot d\vec{l} + \int_{CA} \vec{A} \cdot d\vec{l}$$

$$\int_{AB} \vec{A} \cdot d\vec{l} = \int_{AB} (xy\hat{x}) \cdot (\hat{x}dx + \hat{y}dy + \hat{z}dz)$$
$$= \int_{AB} xy dx$$

Use dummy variable  $t$

on path  $AB$ ,  $x = 1-t$ ,  $y = t$   
 $\Rightarrow dx = -dt$

$$\begin{aligned} \text{So } \int_{AB} \vec{A} \cdot d\vec{l} &= \int_0^1 (1-t) \cdot t \cdot -dt \\ &= \int_0^1 (t^2 - t) dt \\ &= \left( \frac{t^3}{3} - \frac{t^2}{2} \right) \Big|_0^1 \\ &= -\frac{1}{6} \end{aligned}$$

$$\int_{BC} \vec{A} \cdot d\vec{l} = 0 \quad \text{since } \vec{A} = 0 \quad \text{on path } BC$$

$$\int_{CA} \vec{A} \cdot d\vec{l} = 0 \quad \text{since } \vec{A} = 0 \quad \text{on path } CA$$

$$\Rightarrow \int_{ABC} \vec{A} \cdot d\vec{l} = \boxed{-\frac{1}{6}}$$