

Lecture #17: Magnetoic Diffusion and Inertial MHD Waves Hawes(1)

I. Magnetic Diffusion

A. Large time we studied the case of $\text{Rem} \gg 1$, when resistivity can be neglected, giving

$$\frac{\partial \vec{B}}{\partial t} = \nabla \times (\vec{U} \times \vec{B}).$$

From this equation, we proved the Frozen-in Flux Theorem:

The magnetic field lines are frozen to the fluid flow.

B. In the opposite limit, $\text{Rem} \ll 1$, the convection term may be neglected, yielding a diffusion equation

$$\frac{\partial \vec{B}}{\partial t} = \frac{\eta}{\mu_0} \nabla^2 \vec{B}$$

1. The timescale for the diffusion of the magnetic field T_{diff} over a scale-length L can be estimated as

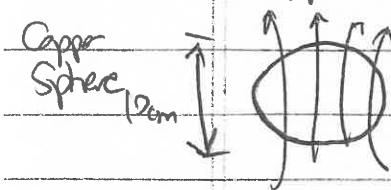
$$\frac{B}{T_{\text{diff}}} \sim \frac{\eta B}{\mu_0 L^2} \Rightarrow T_{\text{diff}} = \frac{\mu_0 L^2}{\eta}$$

2. We can use this equation, along with the expression for resistivity

$$\eta = \frac{m_e \gamma_i}{e^2 n_0} = \frac{e^2 m_e^{1/2} \ln N_D}{2^{5/2} \pi \epsilon_0^2 (k T_e)^{3/2}} \quad (\text{from Lect #11})$$

to find the characteristic diffusion time in typical plasmas.

3. Given the resistivity of copper, $\eta = 1.7 \times 10^{-8} \Omega \cdot \text{m}$, a copper sphere of diameter 10 cm will diffuse a magnetic field



$$\text{in } T_{\text{diff}} = \frac{\mu_0 L^2}{\eta} = \frac{(4\pi \times 10^7 \text{ H/m})(0.1 \text{ m})^2}{1.7 \times 10^{-8} \Omega \cdot \text{m}} = 0.7 \text{ s}$$

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Hawes (3)

I. B₀ (Concluded) NRL p. 40 has many characteristic values.

4.

Plasma	n(cm ⁻³)	T(k)	B(T)	L(m)	$\tau_{ci}(\text{s}^{-1})$	$\tau(\text{cm})$	τ_{diff}
LAPD	10^{18}	10^5	0.06	0.4	3×10^6	10^{-4}	1.7×10^{-3}
Fusion Plasma	10^{21}	10^8	10	2.0	2×10^5	6×10^{-9}	$8 \times 10^2 \text{ s} = 13 \text{ m}$
Solar Wind	10^7	10^5	10^{-8}	$1 \text{ AU} = 1.5 \times 10^{11} \text{ m}$	7×10^{-5}	2.5×10^{-4}	$5 \times 10^{19} \text{ s} = 10^{12} \text{ yr}$
ZSM	10^6	10^4	10^{-10}	$1 \text{ pc} = 3 \times 10^{16} \text{ m}$	2×10^{-4}	7×10^{-3}	$2 \times 10^{21} \text{ s} = 5 \text{ Myr}$

- a. NOTE: Although resistivities are larger than Copper (with the exception of the fusion plasma), diffusion times are because of the scale of the plasma.
- b. Space and astrophysical have very long characteristic diffusion times. This IDEAL MHD is a good approximation.
- 5. The earth's molten iron core has $\tau_{diff} \sim 10^4$ years.
a. Thus, earth's magnetic field must be maintained by some dynamo processes!
- 6. Note also that the diffusion times depend only on plasma temperature T_e and density n. The magnitude of the magnetic field does not enter into the calculation.

I. Characteristic Waves of an MHD Plasma

A. Concept of Linear Wave Modes

1. A very important way of characterizing a plasma is to determine the characteristic linear wave modes, or eigenmodes, of the system.
2. A general perturbation (of small amplitude) can be decomposed into its component linear waves modes. These waves will carry away the disturbance as the plasma response.

3. Linear Dispersion Relation

- a. IMPORTANT: the technique for determining the linear dispersion relation arises again and again in the study of plasma physics.
- b. The dispersion relation tells us a great deal about plasma behavior.

B. General Procedure for finding the Linear Dispersion Relation

(See Ch 4 Sec 4.3 for details of this procedure for plasma oscillations)

i. Linearization of the Equations:

- a. We'll assume small amplitude perturbations so that quadratic terms will be negligible.

Ex: Density: $\rho = \rho_0 + \epsilon \rho_1$ where $\epsilon \ll 1$.

Magnetic field $\mathbf{B} = \mathbf{B}_0 + \epsilon \mathbf{B}_1$, etc.

- b. Plug these expansions into system of equations.

c. Collect terms order by order

i) Zeroth Order: $O(\epsilon^0) = O(1) \Rightarrow$ Plasma Equilibrium

ii) First Order: $O(\epsilon) \Rightarrow$ This gives the linearized equations.

iii) Second Order: $O(\epsilon^2) \Rightarrow$ Discard these non-linear terms.

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T.B. (Continued)

Handout 4

2. Fourier Analysis:

a. Any disturbance can be decomposed into a sum of plane waves.

$$\rho(\underline{x}, t) = \sum_{\underline{k}} \rho(\underline{k}) e^{i(\underline{k} \cdot \underline{x} - \omega(\underline{k})t)}$$

Sum over all possible
wave vectors \underline{k}

This frequency is a function of \underline{k}
to be determined by the dispersion
relation.

b. Because the equations are now linear,

each term has a sum, and each \underline{k} must solve that
set of equations independent of all other

wavevectors \underline{k}'

c. Thus, linear properties of the system of equations (MHD)

may be determined by the response to an arbitrary \underline{k} .

So, we take

$$\rho(\underline{x}, t) = \rho(\underline{k}) e^{i(\underline{k} \cdot \underline{x} - \omega t)}$$

where $\omega = \omega(\underline{k})$.

d. NOTE:

$$\text{i)} \frac{\partial}{\partial t} \rho(\underline{x}, t) = \rho(\underline{k}) \frac{\partial}{\partial t} e^{i(\underline{k} \cdot \underline{x} - \omega t)} = -i\omega \rho(\underline{k}) e^{i(\underline{k} \cdot \underline{x} - \omega t)} \\ = -i\omega \rho(\underline{x}, t)$$

$$\text{ii)} \nabla \rho(\underline{x}, t) = \left(\frac{\partial}{\partial x} \hat{x} + \frac{\partial}{\partial y} \hat{y} + \frac{\partial}{\partial z} \hat{z} \right) \rho(\underline{x}, t)$$

$$\text{So } \hat{x} \text{ component: } \frac{\partial}{\partial x} \rho(\underline{k}) e^{i(k_x x + k_y y + k_z z - \omega t)} = i k_x \rho(\underline{k}) e^{i(\underline{k} \cdot \underline{x} - \omega t)}$$

Thus

$$\nabla \rho(\underline{x}, t) = i(k_x \hat{x} + k_y \hat{y} + k_z \hat{z}) \rho(\underline{k}) e^{i(\underline{k} \cdot \underline{x} - \omega t)} = i \underline{k} \rho(\underline{k}) e^{i(\underline{k} \cdot \underline{x} - \omega t)}$$

iii) Therefore:

$$\boxed{\frac{\partial}{\partial t} \rightarrow -i\omega}$$

$$\boxed{\nabla \rightarrow i \underline{k}}$$

e. After substituting in for the plane wave (i.e. $\rho(\underline{x}, t) = \rho(\underline{k}) e^{i(\underline{k} \cdot \underline{x} - \omega t)}$)
we can cancel $e^{i(\underline{k} \cdot \underline{x} - \omega t)}$ from each term to give a system
of equations for $\rho(\underline{k})$, $B(\underline{k})$, etc.

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II. B.2 (Continued)

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f. Complex Notation: i) The coefficient $\rho(k)$ is taken to be complex.

ii) The observable quantity is $\text{Re}[\rho(k)e^{i(k \cdot x - \omega t)}]$.

iii) If $\rho(k)$ were real, this would be

$$\rho(k) \cos(k \cdot x - \omega t)$$

iv) But, since $\rho(k)$ is complex, the real part allows for arbitrary phase,

$$\rho(k) \cos(k \cdot x - \omega t) - \rho_i(k) \sin(k \cdot x - \omega t)$$

v) This is equivalent to allowing an arbitrary phase δ , such that

$$\underbrace{\rho(k) e^{i(k \cdot x - \omega t + \delta)}}_{\text{Real Constant}} = \underbrace{\rho(k) e^{i\delta}}_{\text{Complex Constant}} e^{i(k \cdot x - \omega t)}$$

3. Collect System of linear equations for Fourier Amplitudes

a. Assemble system of linear equations into Matrix Form.

$$\underbrace{\begin{pmatrix} & \\ & \\ & \\ & \end{pmatrix}}_{N \times N \text{ matrix}} \underbrace{\begin{pmatrix} & \\ & \\ & \\ & \end{pmatrix}}_{\text{Vector of } N\text{-variables}} = 0$$

($N=8$ for MHD)

b. Determinant of $N \times N$ matrix = 0

This yields solubility condition for system of equations

c. This yields the Dispersion Relation of the form

$$\omega = \omega(k)$$

d. There may be other physical system parameters on which ω depends.

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II. (Continued)

C. General properties of MHD Dispersion Relation

1. Basic properties of plane wave Solutions

a. Consider a wavevector $\tilde{k} = k_{||}\hat{z}$ and dispersion relation

$$\omega = k_{||}v_A$$

$$i) e^{i(\tilde{k} \cdot \tilde{x} - \omega t)} = e^{i(k_{||}z - k_{||}v_A t)} = e^{ik_{||}(z - v_A t)}$$

i) This wave has constant phase at $z - v_A t = \text{const}$ or $z = v_A t + \text{const}$

The wave is moving in \hat{z} direction at speed v_A .

ii) If $\omega = -k_{||}v_A$, then wave moves in $-\hat{z}$ direction with speed v_A .

b. Phase velocity:

$$\text{DEF: } \tilde{V}_p = \frac{\omega}{\tilde{k}} = \frac{\omega}{k_x \hat{x} + k_y \hat{y} + k_z \hat{z}}$$

$$\text{Ex: For } \tilde{k} = k_{||}\hat{z} \text{ and } \omega = k_{||}v_A, \quad \tilde{V}_p = \frac{\omega}{\tilde{k}} = \frac{k_{||}v_A}{k_{||}} \hat{z} = v_A \hat{z}$$

c. Group velocity: This is the velocity at which information (and energy) propagates.

$$\text{DEF: } \tilde{V}_g = \frac{d\omega}{dk} = \frac{d\omega}{dk_x} \hat{x} + \frac{d\omega}{dk_y} \hat{y} + \frac{d\omega}{dk_z} \hat{z}$$

Ex: For some example above,

$$\tilde{V}_g = \frac{d\omega}{dk_{||}} = \frac{d}{dk_{||}} (k_{||}v_A) \hat{z} = v_A \hat{z}$$

2. Axisymmetry of MHD Equations.

a. In a plasma with a straight, uniform magnetic field $\tilde{B} = B_0 \hat{z}$, there are three distinct axes for a wave mode with wavevector \tilde{k} :

$$\boxed{\tilde{k}_x, \hat{b}, \tilde{k}_z \hat{b}}$$

where $\tilde{k} = k_{||}\hat{b} + \tilde{k}_\perp$

b. The angle of \tilde{k}_\perp w.r.t. \hat{b} is arbitrary, so there is an axis of symmetry.

III. The MHD Dispersion Relation

A. Begin with the Ideal MHD System of Equations

Continuity $\frac{\partial \rho}{\partial t} + \underline{U} \cdot \nabla \rho = -\rho \nabla \cdot \underline{U}$

Momentum $\rho \frac{\partial \underline{U}}{\partial t} + \rho \underline{U} \cdot \nabla \underline{U} = -\nabla(p + \frac{B^2}{2\mu_0}) + \frac{(\underline{B} \cdot \nabla) \underline{B}}{\mu_0}$

Induction $\frac{\partial \underline{B}}{\partial t} = \nabla \times (\underline{U} \times \underline{B})$

Pressure $\frac{\partial p}{\partial t} + \underline{U} \cdot \nabla p = -\gamma p \nabla \cdot \underline{U}$

B. Linearize Equations: Take Uniform \underline{B} field in homogeneous plasma with

1. Take a. $\rho = \rho_0 + \epsilon p_1$ } no mean flow,

$$\underline{B} = \underline{B}_0 + \epsilon \underline{B}_1$$

$$\underline{U} = \cdot \epsilon \underline{U}_1$$

$$\overline{P} = P_0 + \epsilon \bar{p}_1$$

where $\epsilon \ll 1$

2. b. Let ρ_0 , \underline{B}_0 , and P_0 be uniform in space and constant in time.

2. Substitute into equations:

a. $\frac{\partial \rho^0}{\partial t} + \epsilon \frac{\partial p_1}{\partial t} + \epsilon \underline{U}_1 \cdot \nabla \rho^0 + \epsilon^2 \underline{U}_1 \cdot \nabla p_1 = -\epsilon \rho_0 \nabla \cdot \underline{U}_1 - \epsilon^2 p_1 \nabla \cdot \underline{U}_1$

$$\Theta(\epsilon): \boxed{\frac{\partial p_1}{\partial t} = -\rho_0 \nabla \cdot \underline{U}_1}$$

$$\begin{aligned} b. \rho_0 \frac{\partial \underline{U}_1}{\partial t} + \epsilon^2 p_1 \frac{\partial \underline{U}_1}{\partial t} + \epsilon^2 \rho_0 \underline{U}_1 \cdot \nabla \underline{U}_1 &= -\nabla \rho_0^0 - \nabla p_1^0 - \frac{\nabla B_0 \cdot B_1}{2\mu_0} - \epsilon^2 \frac{\nabla B_0 \cdot B_1}{\mu_0} - \epsilon^2 \frac{\nabla B_1 \cdot B_0}{2\mu_0} \\ &\quad + \frac{B_0 \cdot \nabla B_0}{\mu_0} + \epsilon \frac{B_1 \cdot \nabla B_0}{\mu_0} + \epsilon \frac{B_0 \cdot \nabla B_1}{\mu_0} + \epsilon^2 \frac{B_1 \cdot \nabla B_1}{\mu_0} \end{aligned}$$

$$\Theta(\epsilon): \boxed{\rho_0 \frac{\partial \underline{U}_1}{\partial t} = -\nabla(p_1 + \frac{B_0 \cdot B_1}{\mu_0}) + \frac{B_0 \cdot \nabla B_1}{\mu_0}}$$

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IIIB (Continued)

2) Continued

$$c. \frac{\partial \vec{B}_0}{\partial t} + \epsilon \frac{\partial \vec{B}_1}{\partial x} = -\nabla \times (\vec{U}_1 \times \vec{B}_0) + \epsilon^2 \nabla \times (\vec{U}_1 \times \vec{B}_1)$$

$$\text{O}(e): \frac{\partial \vec{B}_1}{\partial t} = \nabla \times (\vec{U}_1 \times \vec{B}_0) = U_1 \cdot \nabla \vec{B}_0 - \vec{B}_0 \cdot \nabla U_1 + \vec{B}_0 \cdot \nabla U_1 - U_1 \cdot \nabla \vec{B}_0$$

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$$\boxed{\frac{\partial \vec{B}_1}{\partial t} = -\vec{B}_0 \cdot \nabla U_1 + \vec{B}_0 \cdot \nabla U_1}$$

$$d. \frac{\partial \vec{p}}{\partial t} + \epsilon \frac{\partial \vec{p}_1}{\partial x} + \epsilon U_1 \cdot \nabla \vec{p}_0 + \epsilon^2 \vec{p}_1 \cdot \nabla U_1 = -\gamma p_0 \nabla \cdot U_1 - \epsilon^2 \gamma p_1 \nabla \cdot U_1$$

$$\text{O}(e): \boxed{\frac{\partial \vec{p}_1}{\partial t} = -\gamma p_0 \nabla \cdot U_1}$$

C. Fourier Analysis: Take plane wave solutions $\sim e^{i(k \cdot x - \omega t)}$

1.

$$-\omega p_0 \tilde{U}_1 = -\tilde{k} (p_0 + \frac{\vec{B}_0 \cdot \vec{B}_1}{\mu_0}) + \frac{i(\vec{B}_0 \cdot \vec{k}) \vec{B}_1}{\mu_0} \Rightarrow \boxed{\omega \tilde{U}_1 = \tilde{k} \left(p_0 + \frac{\vec{B}_0 \cdot \vec{B}_1}{\mu_0} \right) \frac{(\vec{B}_0 \cdot \vec{k}) \vec{B}_1}{\mu_0 p_0}}$$

2. $-\omega p_0 \tilde{B}_1$

$$= -i \vec{B}_0 (\vec{k} \cdot \vec{U}_1) + i (\vec{B}_0 \cdot \vec{k}) \vec{U}_1 \Rightarrow \boxed{\omega \tilde{B}_1 = \vec{B}_0 (\vec{k} \cdot \vec{U}_1) - (\vec{B}_0 \cdot \vec{k}) \vec{U}_1}$$

3. $-\omega p_1 = -i \gamma p_0 (\vec{k} \cdot \vec{U}_1)$

$$\Rightarrow \boxed{\omega p_1 = \gamma p_0 (\vec{k} \cdot \vec{U}_1)}$$

4. Thus, we have found:

$$\omega p_1 = p_0 (\vec{k} \cdot \vec{U}_1)$$

$$\omega \tilde{U}_1 = \tilde{k} \left(p_0 + \frac{\vec{B}_0 \cdot \vec{B}_1}{\mu_0 p_0} \right) \frac{(\vec{B}_0 \cdot \vec{k}) \vec{B}_1}{\mu_0 p_0}$$

$$\omega \tilde{B}_1 = \vec{B}_0 (\vec{k} \cdot \vec{U}_1) - (\vec{B}_0 \cdot \vec{k}) \vec{U}_1$$

$$\omega p_1 = \gamma p_0 (\vec{k} \cdot \vec{U}_1)$$

Next time we'll finish solving
for the linear MHD dispersion relation