

Lecture #21: Magnetic Reconnection in Resistive MHD

I. Resistive Magnetohydrodynamics: Equations & Properties

A. Equations of Resistive MHD

1. Continuity: $\frac{\partial \rho}{\partial t} + \underline{u} \cdot \nabla \rho = -\rho \nabla \cdot \underline{u}$

2. Momentum: $\frac{\partial \underline{u}}{\partial t} + \underline{u} \cdot \nabla \underline{u} = -\frac{1}{\rho} \nabla (p + \frac{B^2}{2\mu_0}) + \frac{\underline{B} \cdot \nabla \underline{B}}{\mu_0 \rho} + \nu \nabla^2 \underline{u}$

3. Magnetic Induction: $\frac{\partial \underline{B}}{\partial t} = \nabla \times (\underline{u} \times \underline{B}) + \frac{c^2}{\mu_0} \nabla^2 \underline{B}$

4. Adiabatic Eq. of State: $\frac{d}{dt} \left(\frac{p}{\rho^\gamma} \right) = 0$

where $\underline{\nu}$ Kinematic viscosity $\nu \equiv \frac{\mu}{\rho}$ ← coefficient of shear viscosity
 η Resistivity $\eta \equiv \frac{m_e v_{ei}}{e^2 n_0}$ ← electron-ion collision rate

5. Additional Equations used to derive Resistive MHD

a. Faraday's Law $\frac{\partial \underline{B}}{\partial t} = -\nabla \times \underline{E}$

b. Ampere's Law $\underline{j} = \frac{1}{\mu_0} \nabla \times \underline{B}$

c. No Magnetic Divergence $\nabla \cdot \underline{B} = 0$

d. Coulomb's Law $\nabla \cdot \underline{E} = 0$ ← zero charge density (q)

6. Ohm's Law:

a. In general, Ohm's Law can be derived from the two-fluid momentum equation for electrons where current density $\underline{j} \equiv en(\underline{u}_i - \underline{u}_e)$

b. Generalized Ohm's Law

$$\underline{E} + \underline{u} \times \underline{B} = \underbrace{\eta \underline{j}}_{\text{Resistivity}} + \underbrace{\frac{1}{en} \underline{j} \times \underline{B}}_{\text{Hall term}} - \underbrace{\frac{1}{en} \nabla \cdot \underline{P}_e}_{\text{Electron Pressure tensor}} + \underbrace{\frac{me}{e^2 n} \left[\frac{d\underline{j}}{dt} + \nabla \cdot (\underline{j} \underline{u} + \underline{u} \underline{j}) \right]}_{\text{Electron inertia}}$$

c. Resistive Ohm's Law

$$\underline{E} + \underline{u} \times \underline{B} = \eta \underline{j}$$

B. Frozen-In Magnetic Field:

1. In the absence of resistivity, the Ideal Ohm's Law

$$\underline{E} + \underline{u} \times \underline{B} = 0$$

implies that the magnetic field is frozen-in to the plasma flow

\Rightarrow The plasma cannot slip relative to the magnetic field.
Magnetic flux is conserved!

2. Note that this implies $E_{\parallel} = 0$.

3a. A necessary condition for magnetic reconnection is some non-ideal term to break the magnetic field.

I. B. (Continued)

HWes ③

3 (Continued)

- b. In resistive MHD, resistivity breaks flux conservation, allowing annihilation of magnetic flux and $E_{\parallel} = \eta j_{\parallel} \neq 0$.

C. Resistive Diffusion vs. Magnetic Reconnection

1. In the presence of $\eta \neq 0$, magnetic flux can be annihilated by either resistive diffusion or through magnetic reconnection.

- a. Must have an appropriate geometry for magnetic reconnection to occur.
b. Timescales of both processes are distinct.

2. Timescales:

a) Def: Alfvén Time, τ_A

$$\tau_A = \frac{L}{v_A}$$

← macroscopic scale length of change in \underline{B}

b) Def: Resistive Diffusion Time, τ_R

$$i) \frac{\partial \underline{B}}{\partial t} \sim \frac{\mu}{\mu_0} \nabla^2 \underline{B} \Rightarrow \tau_R \sim \frac{\mu \underline{B}}{\mu_0 L^2}$$

$$ii) \tau_R = \frac{\mu_0 L^2}{\eta}$$

3. Def: Lundquist Number, S

$$a. S \equiv \frac{\tau_R}{\tau_A} = \frac{\mu_0 L^2}{\eta} = \frac{\mu_0 v_A L}{\eta}$$

$$S = \frac{\mu_0 v_A L}{\eta}$$

b. Ratio of resistive diffusion & Alfvénic timescales

c. Similar to magnetic Reynolds number $Re_M = \frac{\mu_0 U L}{\eta}$,

but with v_A replacing U

d. For fusion or astrophysical plasma $S \gtrsim 10^8$
 \Rightarrow resistive diffusion is very slow.

4. Def: Magnetic Reconnection Timescale, τ_r

a. We will find $\tau_A \ll \tau_r \ll \tau_R$

b. Magnetic reconnection enables magnetic flux annihilation much faster than resistive diffusion.

c. Magnetic reconnection is only possible when the geometry of field lines allows it — change of magnetic field direction.

D. Forced vs. Spontaneous Magnetic Reconnection

i. If magnetic field changes direction, reconnection can occur!

a. Forced magnetic reconnection: When external driving pushes oppositely directed magnetic fields together \Rightarrow Sweet-Parker Model

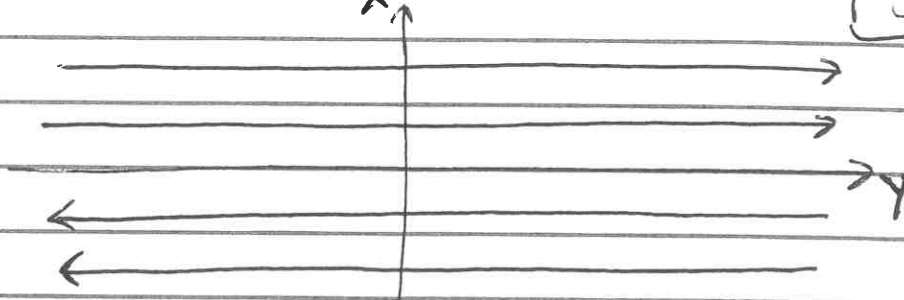
b. Spontaneous magnetic reconnection: Driven by Tearing Instability.

II. Sweet-Parker Model of Magnetic Reconnection

A. Equilibrium Magnetic Field Configuration

1. $\underline{B}_0 = B_{L0} \tanh\left(\frac{x}{a}\right) \hat{y} + B_{R0} \hat{z}$

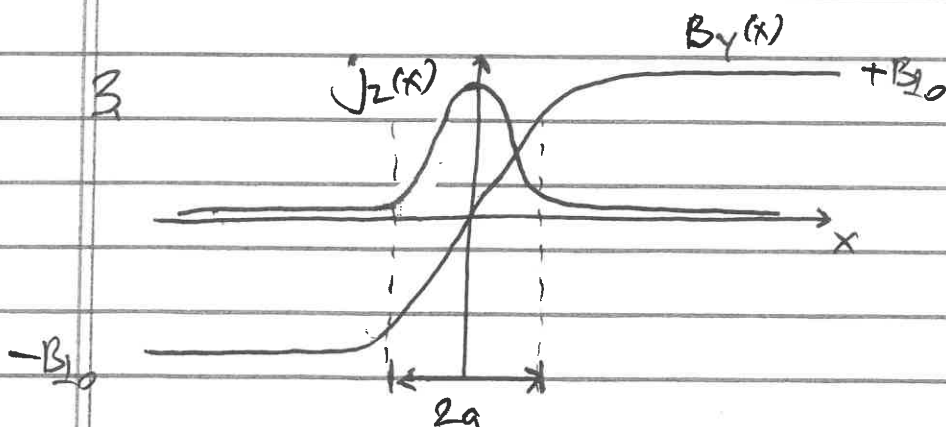
Harris Current Sheet



2. Ampere's Law: $\underline{j} = \frac{1}{\mu_0} \nabla \times \underline{B}$

a. $\frac{1}{\mu_0} \nabla \times \underline{B} = \frac{1}{\mu_0} \begin{vmatrix} \hat{x} & \hat{y} & \hat{z} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ B_x & B_y & B_z \end{vmatrix} = \frac{1}{\mu_0} \frac{\partial B_y}{\partial x} \hat{z} - \frac{\partial B_z}{\partial x} \hat{y}$

b. $j_z = \frac{1}{\mu_0} \frac{\partial B_y}{\partial x} = \frac{B_{L0}}{\mu_0 a} \text{sech}^2\left(\frac{x}{a}\right)$ Using $\frac{d}{dx} \tanh u = \text{sech}^2 u \frac{du}{dx}$



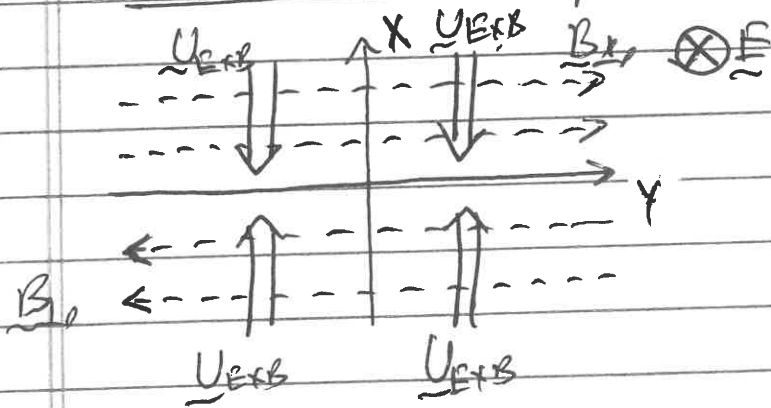
4. Pressure Balance: Note that in equilibrium, the Harris Sheet requires a pressure variation $p_0(x)$ to balance magnetic pressure along x , $\frac{\partial}{\partial x} \left(p_0(x) + \frac{B_0^2}{2\mu_0} \right) = 0$.

B. Sweep-Parker Model

Refs: Sweet, Nuovo Cimento Suppl. Ser X, 8: 188 (1958)
 Parker, J. Geophys. Res., 62: 509 (1957)

1. This has been a fundamental model for resistive magnetic reconnection for six decades, with validation by computer simulations and laboratory experiments.

2. Forced Reconnection Impose $\underline{E} = E_z \hat{z} > 0$,



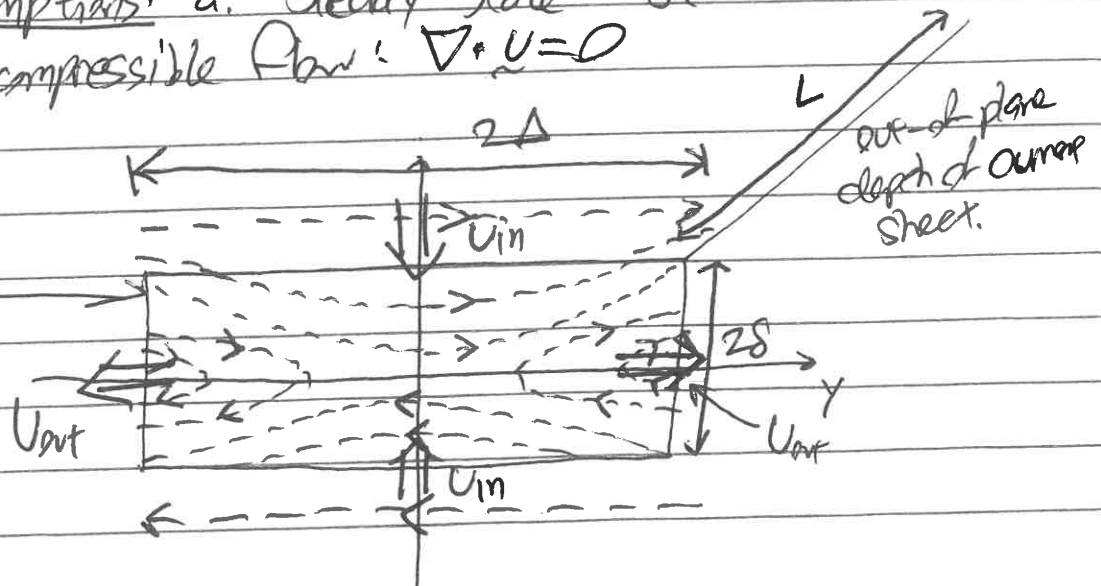
b. What is the in flow speed U_{in} at which oppositely directed (in y) magnetic fields merge and annihilate?

3. Assumptions: a. Steady State $\frac{\partial}{\partial t} = 0$

b. Incompressible Flow: $\nabla \cdot \underline{U} = 0$

4. Geometry:

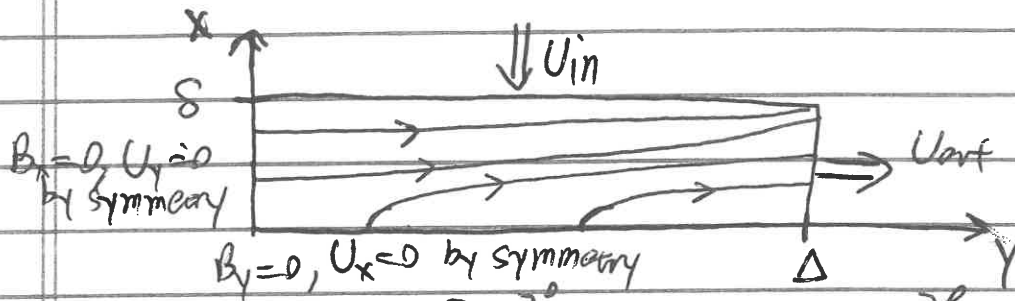
width - Δ
 thickness - δ
 length - L



II. B. (Continued)

Hawes ⑦

5. Consider one quadrant of the curved sheet region:



a. Incompressible: $\frac{\partial \rho}{\partial t} + \underline{u} \cdot \nabla \rho = -\rho \nabla \cdot \underline{u}$

$$\Rightarrow \underline{u} \cdot \nabla \rho = 0 \Rightarrow \rho = \text{constant} = \rho_0$$

b. Mass flux into an end of quadrant:

$$i) \rho_0 U_{in} \Delta S = \rho_0 U_{out} S \Delta$$

$$ii) \boxed{U_{in} = U_{out} \frac{S}{\Delta}} \quad \text{(I)}$$

6. Momentum Equation along $x=0$ from $y=0$ to $y=\Delta$:

a. By symmetry: $U_x = 0$, $B_y = 0$, $\frac{\partial}{\partial x} = 0$

y-component: b. $\frac{\partial \rho}{\partial t} + \underline{u} \cdot \nabla \underline{u} = -\frac{1}{\rho_0} \nabla (p + \frac{B^2}{2\mu_0}) + \frac{B \cdot \nabla B}{\mu_0 \rho_0} + \nu \nabla^2 \underline{u}$ Neglect viscosity

$$U_y \frac{\partial U_y}{\partial y} = -\frac{1}{\rho_0} \frac{\partial}{\partial y} (p + \frac{B^2}{2\mu_0}) + \frac{(B_x \frac{\partial B}{\partial x})}{\mu_0 \rho_0}$$

$$c. \frac{\partial}{\partial y} \left[\frac{\rho_0 U_y^2}{2} + p + \frac{B^2}{2\mu_0} \right] = 0$$

d. Integrate from 0 to Δ in y : $\int_0^\Delta dy \frac{\partial}{\partial y} \left[\frac{\rho_0 U_y^2}{2} + p + \frac{B^2}{2\mu_0} \right] = 0$

II. B.G. (Continued)

e. $\rho_0 \frac{U_y^2(\Delta)}{2} + p(\Delta) + \frac{B_y^2(\Delta) + B_{z0}^2(\Delta)}{2\mu_0} - \rho_0 \frac{U_y^2(0)}{2} - p(0) - \frac{B_y^2(0) + B_{z0}^2(0)}{2\mu_0} = 0$ Haves (8)

i) $B_{z0} = \text{const}$, so cancels.

ii) $U_y(0) = 0$

iii) $B_y(0) = 0$ $B_y(\Delta) = B_L$ ← downstream
magnitude

iv) $p(\Delta) = p_0$ ← where pressure gradient ends

v) $U_y(\Delta) = U_{\text{out}}$

vi) $p(0) = p_{\text{max}}$

f. $\rho_0 \frac{U_{\text{out}}^2}{2} + p_0 + \frac{B_L^2}{2\mu_0} - p_{\text{max}} = 0$

g. $\rho_0 \frac{U_{\text{out}}^2}{2} = (p_{\text{max}} - p_0) - \frac{B_L^2}{2\mu_0}$ (II)

7. Momentum Equation along $y=0$ from $x=0$ to $x=\delta$:

x-component a. By symmetry: $U_y = 0$, $B_x = 0$, $\frac{\partial}{\partial y} = 0$

b. $\frac{\partial U_x}{\partial t} + U_x \frac{\partial U_x}{\partial x} = -\frac{1}{\rho_0} \frac{\partial}{\partial x} \left(p + \frac{B^2}{2\mu_0} \right) + \frac{B_y \frac{\partial B_x}{\partial x}}{\mu_0 \rho_0} + \nabla^2 U_x$

c. $\frac{\partial}{\partial x} \left[\rho_0 \frac{U_x^2}{2} + p + \frac{B^2}{2\mu_0} \right] = 0$

d. Integrate from $x=0$ to $x=\delta$ $\int_0^\delta dx \frac{\partial}{\partial x} [\dots] = 0$

e. $\rho_0 \frac{U_x^2(\delta)}{2} + p(\delta) + \frac{B_y^2(\delta)}{2\mu_0} - \rho_0 \frac{U_x^2(0)}{2} - p(0) - \frac{B_y^2(0)}{2\mu_0} = 0$

i) $U_x(\delta) = U_{\text{in}}$ $U_x(0) = 0$

ii) $B_y(\delta) = B_{z0}$ $B_y(0) = 0$

iii) $p(\delta) = p_0$ $p(0) = p_{\text{max}}$

II. B.7. (Continued)

Hawes 9

$$f. \boxed{\rho_0 \frac{U_{in}^2}{2} = p_{max} - p_0 - \frac{B_{10}^2}{2\mu_0}} \quad \textcircled{II}$$

g. Ansatz 1: $\rho_0 \frac{U_{in}^2}{2} \ll \frac{B_{10}^2}{2\mu_0} \leftarrow \text{Verify a posteriori}$

a. Thus $p_{max} - p_0 = \frac{B_{10}^2}{2\mu_0}$

b. Plug into \textcircled{I} for $p_{max} - p_0$:

$$\rho_0 \frac{U_{out}^2}{2} = \frac{B_{10}^2}{2\mu_0} - \frac{B_{11}^2}{2\mu_0}$$

c. Ansatz 2: $B_{11}^2 \ll B_{10}^2 \leftarrow \text{verify a posteriori}$

d. Thus $\boxed{\rho_0 \frac{U_{out}^2}{2} = \frac{B_{10}^2}{2\mu_0}}$

e. We can show this gives $\boxed{U_{out} = \frac{B_{10}}{\sqrt{\mu_0 \rho_0}} = V_{A1}}$

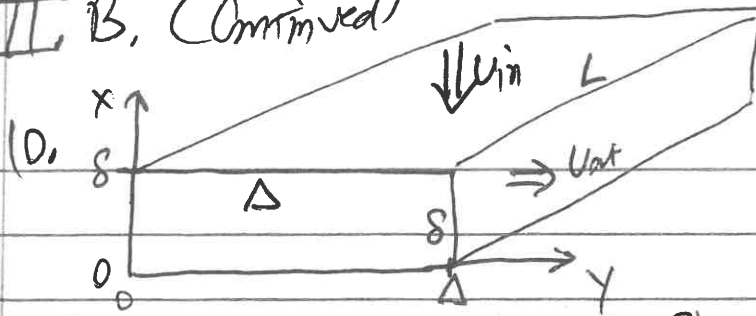
Outflow is a perpendicular Alfvén velocity

9. Revisiting \textcircled{I} , using $U_{out} = V_{A1}$, $\boxed{U_{in} = V_{A1} \frac{S}{\Delta}}$

a. We just need to determine the aspect ratio $\frac{S}{\Delta}$!

II. B. (Continued)

Haves (10)



a) In the quadrant, we demand Ohmic dissipation must balance difference in energy of flow from in flow.

b) In the quadrant volume $\Delta \delta L$,

$$U_{in} \frac{B_{10}^2}{2\mu_0} \Delta \delta L - U_{out} \frac{B_{L1}^2}{2\mu_0} \delta L = \eta j^2 \Delta \delta L$$

c) Ohmic Dissipation: i) $\underline{E} + \underline{v} \times \underline{B} = \eta \underline{j}$

ii) Dot with \underline{j} : $\underbrace{\underline{E} \cdot \underline{j}}_{\text{rate of work done vol}} = \underbrace{(\underline{v} \times \underline{B}) \cdot \underline{j}}_{\text{resistive dissipation vol}} + \eta j^2$

iii) ηj^2 dominates resistive dissipation

d) Using $U_{in} \Delta = U_{out} \delta$, Again, take $B_{L1}^2 \ll B_{10}^2$

$$i) U_{in} \Delta \left[\frac{B_{10}^2}{2\mu_0} - \frac{B_{L1}^2}{2\mu_0} \right] = \eta j^2 \Delta \delta$$

$$ii) \boxed{U_{in} \frac{B_{10}^2}{2\mu_0} = \eta j^2 \delta}$$

e) From Ampere's Law (See Sec. I A. 2b.), $j_z = \frac{1}{\mu_0} \frac{\partial B_y}{\partial x} = \frac{1}{\mu_0} \frac{\Delta B_y}{\Delta x}$

$$\boxed{j_z = \frac{B_{10}}{\mu_0 \delta}}$$

III. B₁₀ (Continued)

Hwvcs ⑪

$$A) U_{in} \frac{B_{10}^2}{2\mu_0} = \eta \frac{B_{10}^2}{\mu_0 \delta^2} \delta \Rightarrow \boxed{U_{in} = \frac{2\eta}{\mu_0 \delta}}$$

ii. Combining $U_{in} = \frac{2\eta}{\mu_0 \delta}$ and $U_{in} = V_{A1} \frac{S}{\Delta}$

a. $V_{A1} \frac{S}{\Delta} = \frac{2\eta}{\mu_0 \delta} \Rightarrow \delta^2 = \left(\frac{2\eta}{\mu_0 V_{A1}} \right) \Delta$

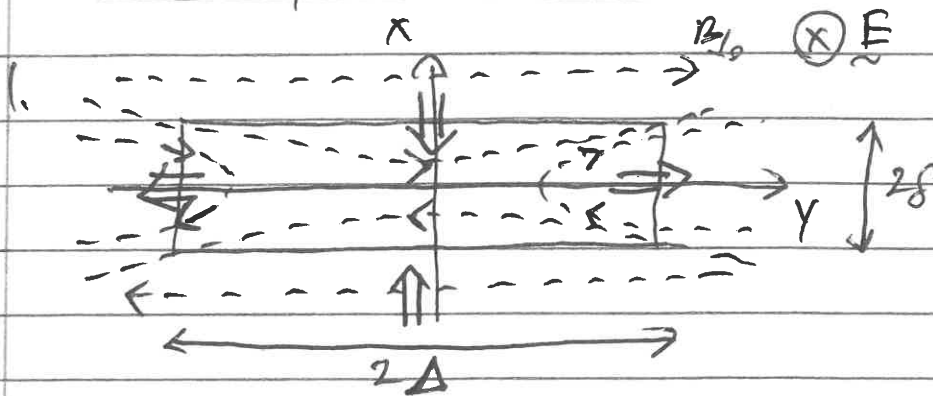
b. $\delta = \frac{\sqrt{2} \Delta^{\frac{1}{2}} \Delta^{\frac{1}{2}}}{\left(\frac{\mu_0 V_{A1} \Delta}{\eta} \right)^{\frac{1}{2}}} \Rightarrow \boxed{\frac{S}{\Delta} = \frac{\sqrt{2}}{S^{\frac{1}{2}}}}$

Aspect ratio of current sheet must have $\frac{S}{\Delta} \ll 1$
to balance energy inflow with energy dissipation for
 $S \gg 1$ plasmas

12. Find inflow velocity U_{in} ?

a. $U_{in} = V_{A1} \frac{S}{\Delta} \Rightarrow \boxed{U_{in} = \frac{\sqrt{2} V_{A1}}{S^{\frac{1}{2}}}} \ll V_{A1} = U_{inf}$

C. Summary of Sweet-Parker Model



2. a. $U_{out} = V_{A1} = \frac{B_{10}^2}{\mu_0 \rho_0}$

b. $U_{in} = \frac{\sqrt{2}}{S^{1/2}} V_{A1}$ where $S \equiv \frac{\mu_0 V_{A1} \Delta}{\eta}$ Lundquist Number

c. $\frac{\delta}{\Delta} = \frac{\sqrt{2}}{S^{1/2}}$

3. Check Ansatz 1: $\rho_0 \frac{U_{in}^2}{2} \ll \frac{B_{10}^2}{2\mu_0}$

a. $\rho_0 \frac{2 V_{A1}^2}{2 S} = \rho_0 \frac{B_{10}^2}{\mu_0 S} = \frac{2}{S} \frac{B_{10}^2}{2\mu_0} \ll \frac{B_{10}^2}{2\mu_0}$

b. This holds if $S \gg 1$ ✓

4. Check Ansatz 2: $B_{11}^2 \ll B_{10}^2$

a. $\rho_0 \frac{U_{out}^2}{2} = \frac{B_{10}^2}{2\mu_0} - \frac{B_{11}^2}{2\mu_0} \Rightarrow \mu_0 \rho_0 U_{out}^2 = B_{10}^2 - B_{11}^2$

b. $B_{11}^2 = B_{10}^2 - \mu_0 \rho_0 U_{out}^2 = B_{10}^2 - \mu_0 \rho_0 \left[\frac{B_{10}^2}{\mu_0 \rho_0} \right] = 0$ ✓

II. Continued)

Hines 13

D. Revisit Timescales

1. For the current sheet of width Δ ,

$$\tau_A = \frac{\Delta}{v_{Al}}$$

$$\tau_R = \frac{\mu_0 \Delta^2}{\eta}$$

2. Reconnection timescale $\tau_r = \frac{\Delta}{v_{in}} = \frac{S^{1/2} \Delta}{\sqrt{2} v_{Al}} = \tau_r$

3. Relative to τ_A : $\frac{\tau_A}{\tau_A} \sim 1, \frac{\tau_r}{\tau_A} \sim S^{1/2}, \frac{\tau_R}{\tau_A} \sim S$

a. Thus $\tau_A \ll \tau_r \ll \tau_R$ Reconnection occurs on an intermediate timescale

4. Hybrid timescale:

$$a. (\tau_A \tau_R)^{1/2} = \left[\tau_A^2 \frac{\tau_R}{\tau_A} \right]^{1/2} = \tau_A S^{1/2} = \sqrt{2} \left(\frac{S^{1/2} \Delta}{\sqrt{2} v_{Al}} \right) = \sqrt{2} \tau_r$$

b. Thus $\tau_r \propto (\tau_A \tau_R)^{1/2}$

5. For laboratory & astrophysical plasmas, $10^4 \leq S \leq 10^{12}$

a. Ex: Solar flares in solar corona: $S \sim 10^{10}$

i) Observed flare magnetic energy release time ~ 20 min.

ii) Predicted Sweet-Parker $\tau_r \sim 2-3$ years.

b. \Rightarrow Some other mechanism enables fast reconnection!