

College Physics I: 1511

Mechanics & Thermodynamics

Professor Jasper Halekas
Van Allen Lecture Room 1
MWF 8:30-9:20 Lecture

Public Service Announcement

- Iowa Voter Registration Deadline is October 29 (two weeks away).
- Make sure you are registered
- Make sure your voice is heard!

Equilibrium

$$\Sigma F = ma$$

$$\Sigma \tau = I\alpha$$

- Acceleration = 0
 - Net External Force = 0
 - All external forces balanced

- Angular acceleration = 0
 - Net External Torque = 0
 - All external torques balanced

Concept Check

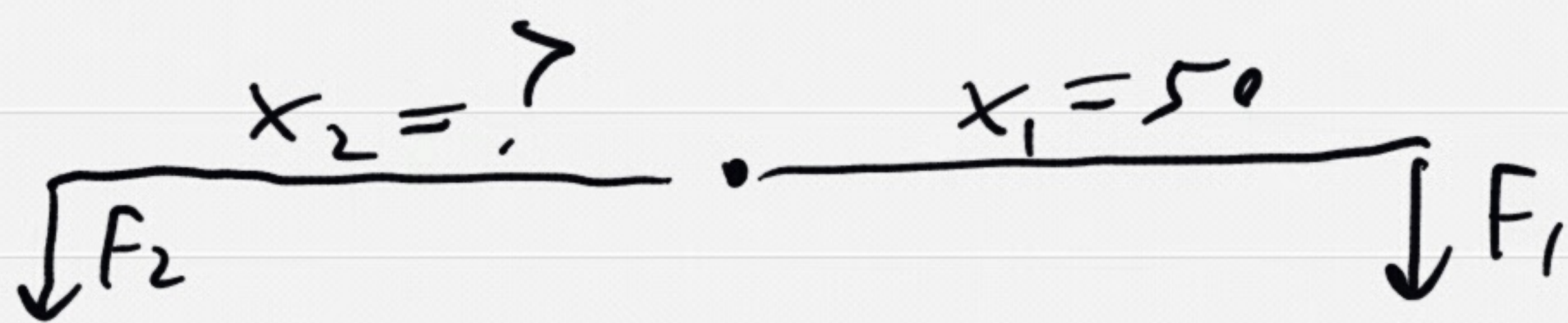
- A meter stick is balanced at its midpoint. I put a 1 kg mass at the end of the stick ($x = 50$ cm). If I also have a 5 kg mass, where should I place it so that the meter stick is balanced?
- A. $x = -50$ cm
 - B. $x = -10$ cm
 - C. $x = 10$ cm
 - D. $x = -20$ cm
 - E. $x = -25$ cm



Concept Check

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$$\begin{aligned}\Sigma \tau &= \Sigma F r \sin \theta_{Fr} \\ &= \Sigma F r\end{aligned}$$

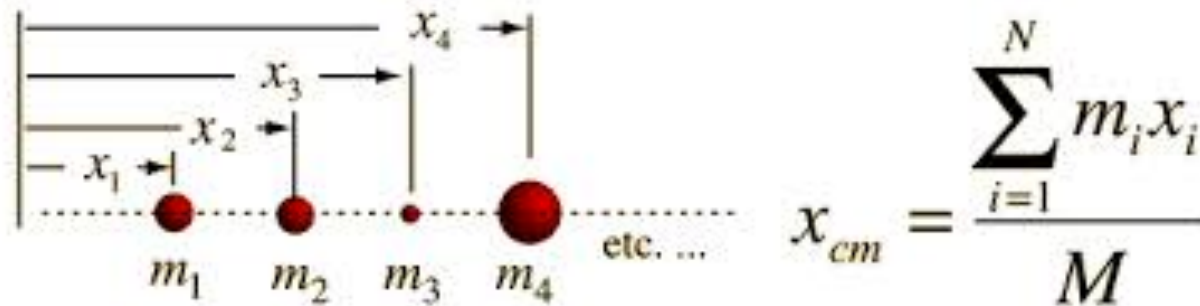
$$\begin{aligned}\tau_1 &= F_1 x_1 \quad \text{CW} \\ &= -m_1 g x_1 \\ &= -g \cdot 0.5\end{aligned}$$

$$\begin{aligned}\tau_2 &= F_2 x_2 \quad \text{CCW} \\ &= -m_2 g \cdot x_2 \\ &= -5 \cdot g \cdot x_2\end{aligned}$$

$$\Sigma \tau = \tau_1 + \tau_2$$

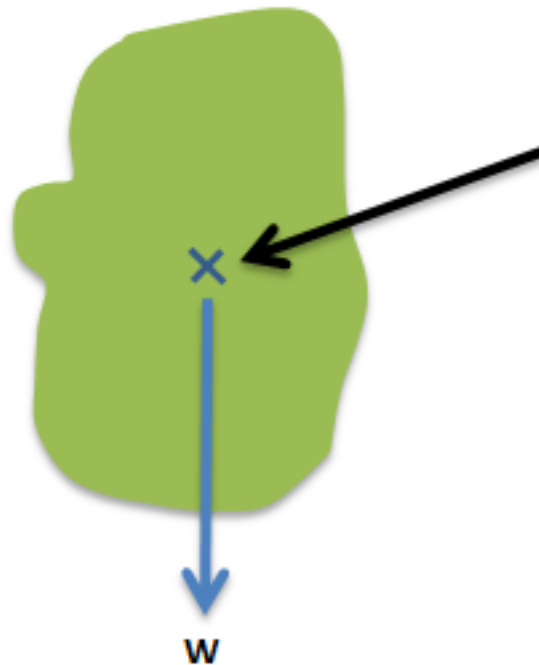
$$\begin{aligned}&= -5g x_2 - 0.5g = 0 \\ \Rightarrow 5g x_2 &= -0.5g \\ \Rightarrow x_2 &= -0.1 \text{ m} \\ &= \boxed{-10 \text{ cm}}\end{aligned}$$

Center of Mass / Center of Gravity



A diagram showing four red spheres of different sizes on a horizontal dashed line. The spheres are labeled m_1 , m_2 , m_3 , and m_4 from left to right. Above each sphere, a horizontal arrow indicates its position relative to a common vertical reference line on the left, labeled x_1 , x_2 , x_3 , and x_4 respectively. To the right of the spheres, the formula for the center of mass is given as $x_{cm} = \frac{\sum_{i=1}^N m_i x_i}{M}$.

$$x_{cm} = \frac{\sum_{i=1}^N m_i x_i}{M}$$



Center of Mass

(This would also be center of Gravity since the object is in uniform gravitational field)

$$\tau = F \cdot x$$

$$\tau_i = F_i \cdot x_i \quad \text{for } i = 1, 2, \dots$$

$$\tau_{\text{total}} = \sum \tau_i$$

$$= \sum F_i x_i$$

$$\text{if } F_i = m_i g$$

$$\tau_{\text{total}} = \sum m_i g x_i$$

$$\text{but } \sum m_i x_i = M x_{\text{cm}}$$

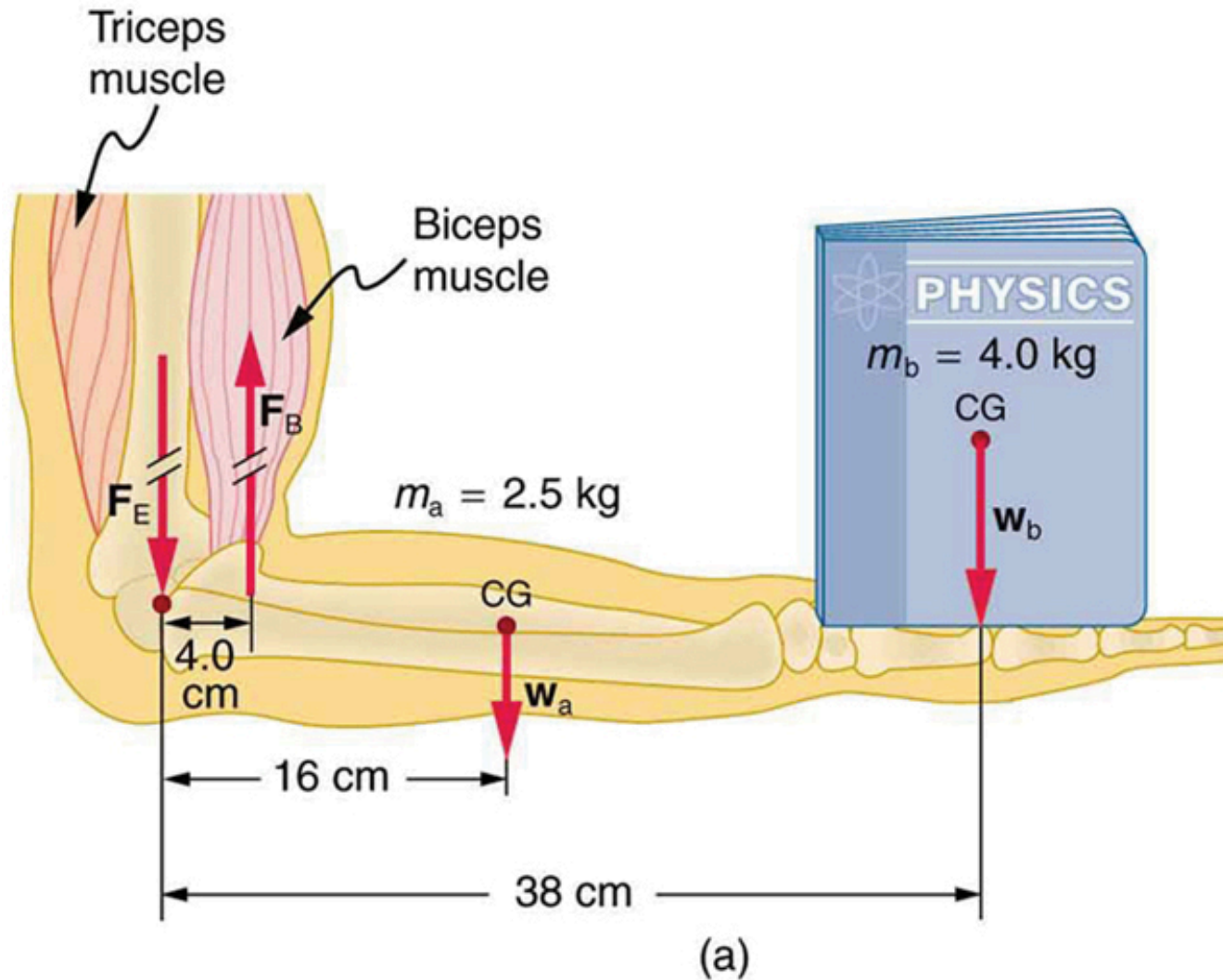
$$\Rightarrow \tau_{\text{total}} = M g x_{\text{cm}}$$

Acts as if all mass
⊙ center of mass

Gravitational Torque on a Solid Object

- Torque = Force F * Lever Arm L
 - Torque on a portion of an object m_i at position x_i
 - $\tau_i = F_i * x_i$
 - Total torque
 - $\tau = \sum F_i x_i = \sum m_i a_i x_i = M * (\sum m_i a_i x_i / M) = M * g * L_c$
 - Since gravitational acceleration g is the same for every portion of the object:
 - Can treat object as if total mass M at center of mass L_c
- Use CM/CG with translational force/acceleration

Torque and Center of Mass



Pick elbow as pivot.

$$\tau_E = F_E r_E = 0$$

$$\tau_B = F_B \cdot r_B = F_B \cdot 0.04$$

$$\tau_a = -m_a g \cdot r_a = -2.5 \cdot 9 \cdot 0.16$$

$$\tau_b = -m_b g \cdot r_b = -4 \cdot 9 \cdot 0.38$$

$$\Sigma \tau = 0$$

$$= F_B \cdot 0.04 - 2.5 \cdot 9 \cdot 0.16 - 4 \cdot 9 \cdot 0.38$$

$$= F_B \cdot 0.04 - 3.92 - 14.9$$

$$= F_B \cdot 0.04 - 18.82 \text{ Nm}$$

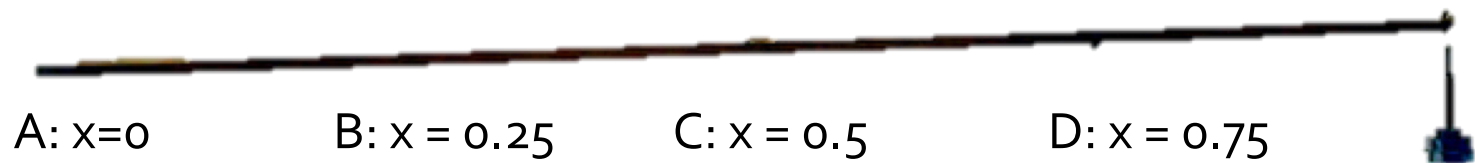
$$\Rightarrow F_B \cdot 0.04 = 18.82$$

$$\text{or } \boxed{F_B = 470 \text{ N}}$$

- Much bigger than weight since lever arm so small

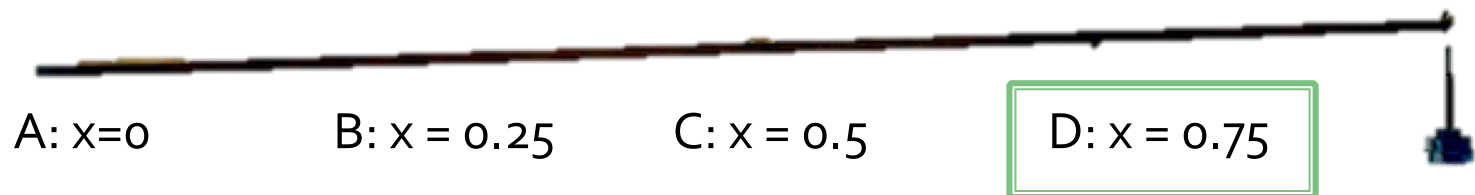
Concept Check

- Imagine that we balance a meter stick weighing 160 g with a suspended weight on one end that also weighs 160 g. Where should the balance point be located?



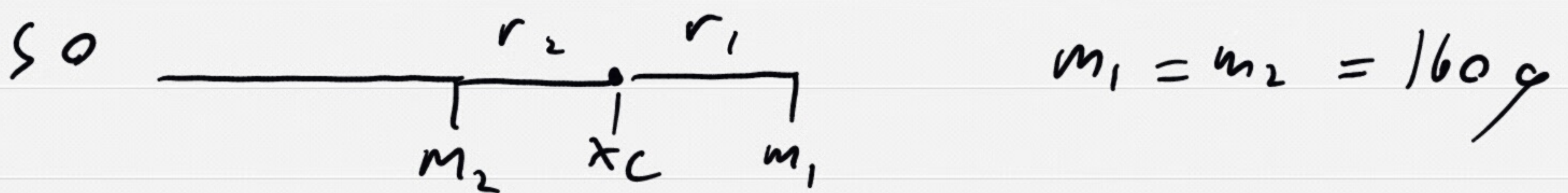
Concept Check

- Imagine that we balance a meter stick weighing 160 g with a suspended weight on one end that also weighs 160 g. Where should the balance point be located?



Treat meter stick as if all mass @ CM.

- CM is at $x = 0.5$
- Put pivot @ $x = x_c$



$$r_1 = 1 - x_c$$

$$r_2 = x_c - 0.5$$

$$|\tau_1| = |\tau_2|$$

$$m_1 (1 - x_c) = m_2 (x_c - 0.5)$$

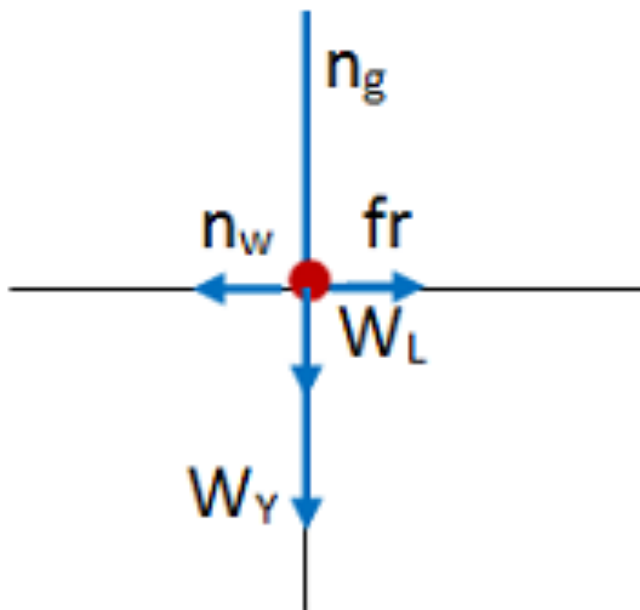
$$1 - x_c = x_c - 0.5$$

$$1 = 2x_c - 0.5$$

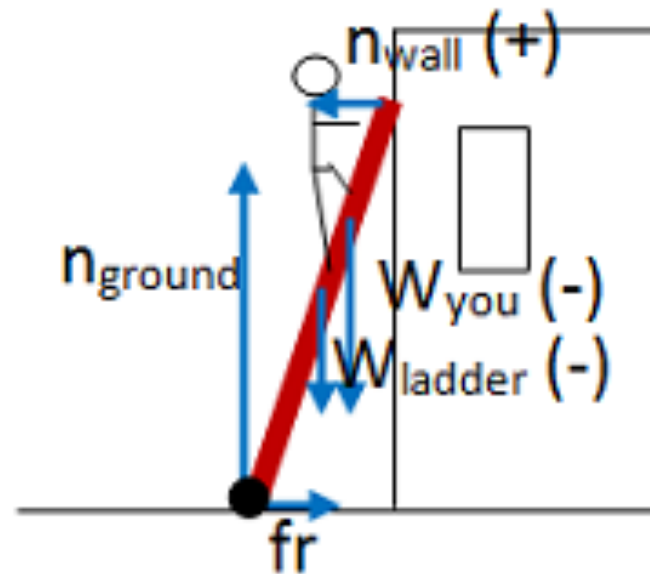
$$1.5 = 2x_c$$

$$x_c = 0.75$$

Non-Equilibrium

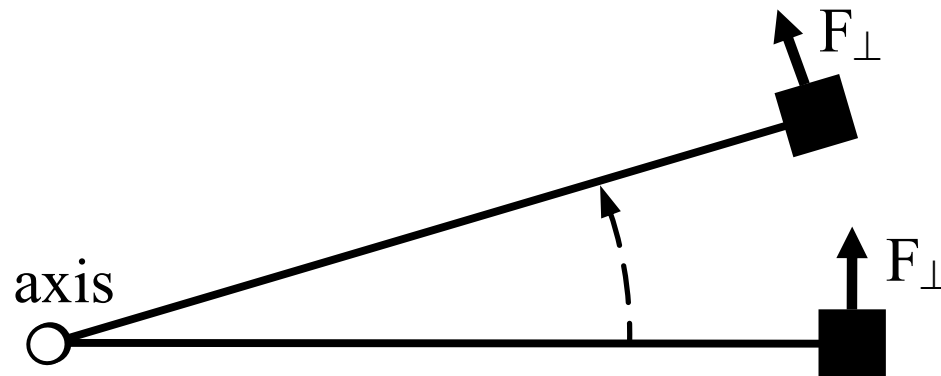


$$\Sigma F = ma$$



$$\Sigma \tau = I\alpha$$

Moment of Inertia



$$I = mr^2 = \text{"Moment of Inertia"}$$

Moment of Inertia

$$I = \sum_{i=1}^N m_i r_i^2$$

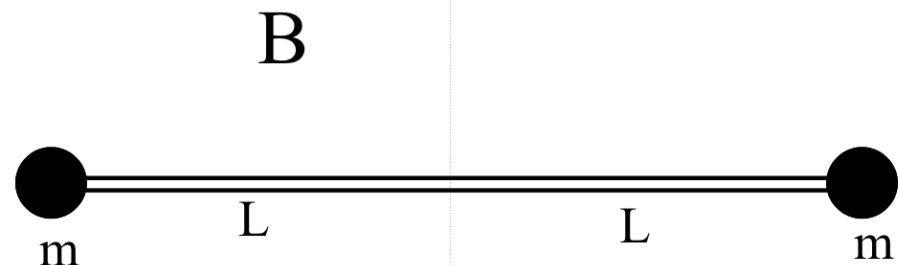
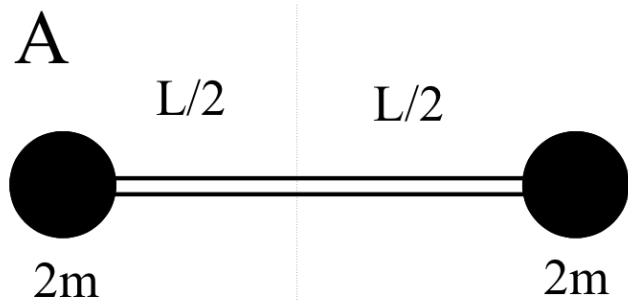
N point particles

$$= \int_0^M r^2 dm$$

Solid of mass M

Concept Check

Consider two masses, each of size $2m$ at the ends of a light rod of length L with the axis of rotation through the center of the rod. The rod is doubled in length and the masses are halved. What happens to I ?



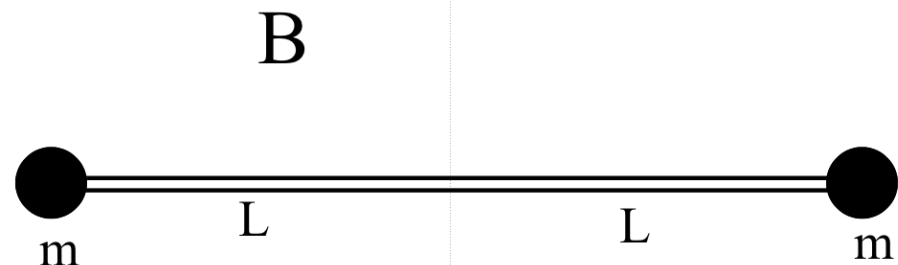
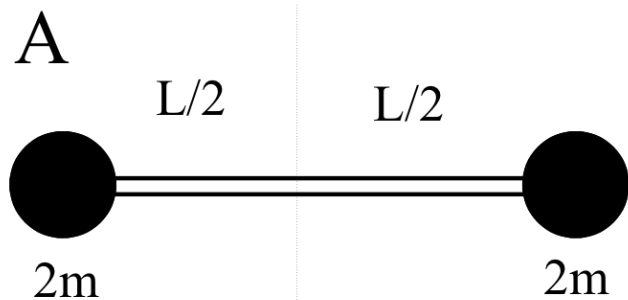
A: I_A is bigger

B : I_B is bigger

C: $I_A = I_B$

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A: I_A is bigger

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$$I = \sum m r^2$$

$$I_1 = 2m \cdot (L/2)^2 + 2m (L/2)^2$$

$$= 2m L^2/4 + 2m L^2/4$$

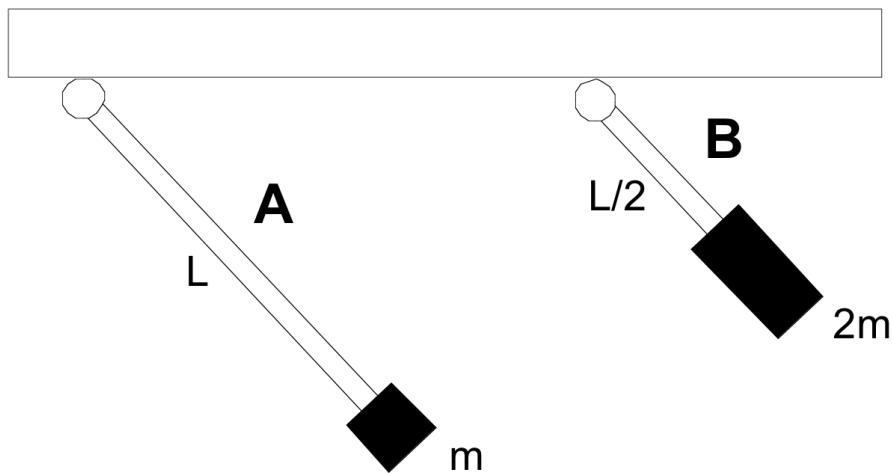
$$= mL^2$$

$$I_2 = mL^2 + mL^2$$

$$= 2mL^2$$

Concept Check

Two light (massless) rods, labeled A and B, each are connected to the ceiling by a frictionless pivot. Rod A has length L and has mass m at the end of the rod. Rod B has length $L/2$ and has a mass $2m$ at its end. Both rods are released from rest in a horizontal position.



Which one experiences the larger torque?

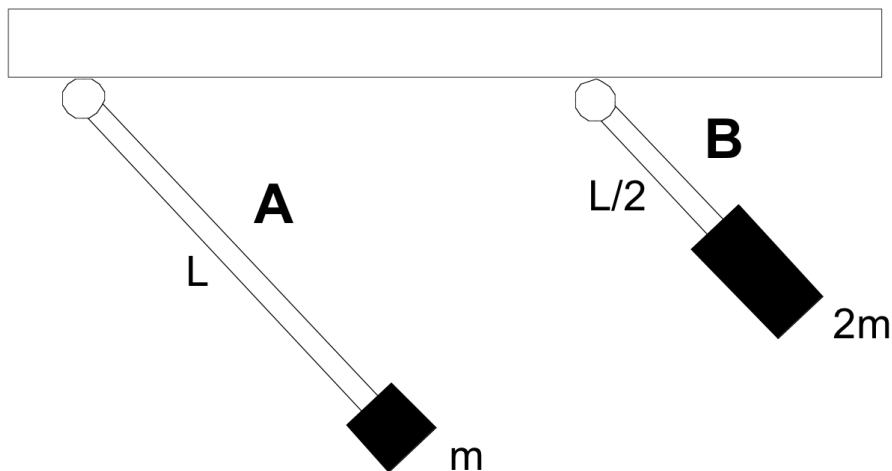
A: A

B: B

C: Both have the same size τ .

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A: A

B: B

C: Both have the same size τ .

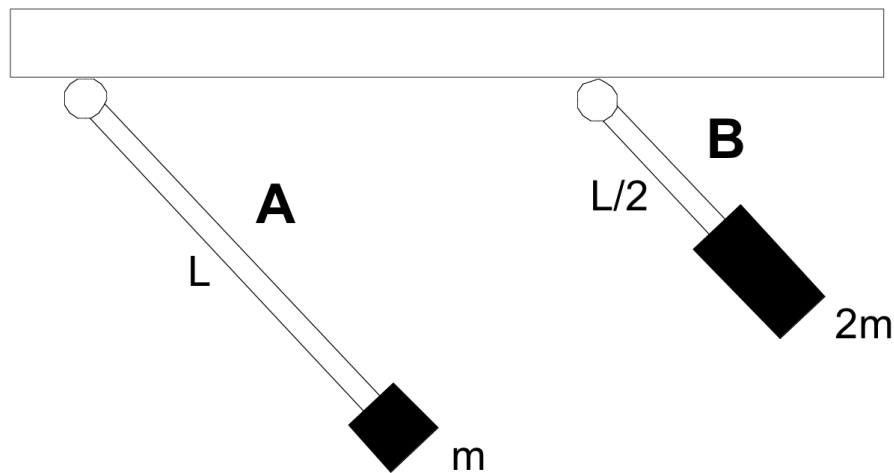
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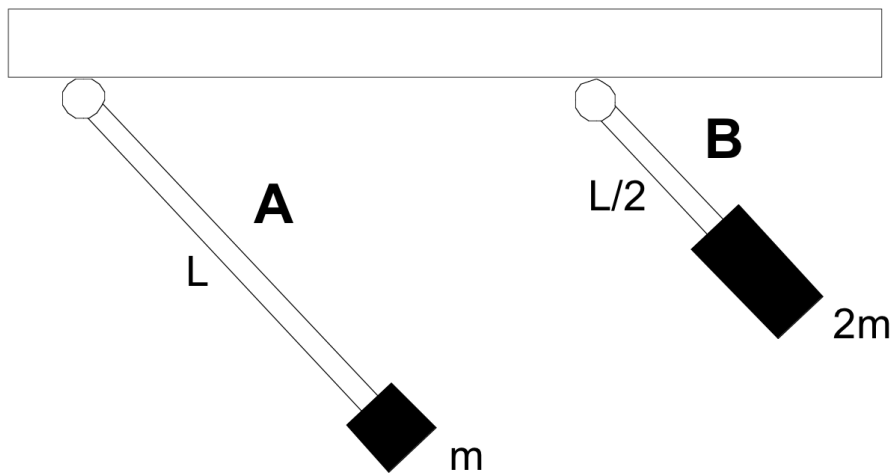
Which one falls to the vertical position fastest?

A: A B: B C: Both fall at the same rate.

(Hint: $\alpha = \frac{\tau}{I}$)

Concept Check

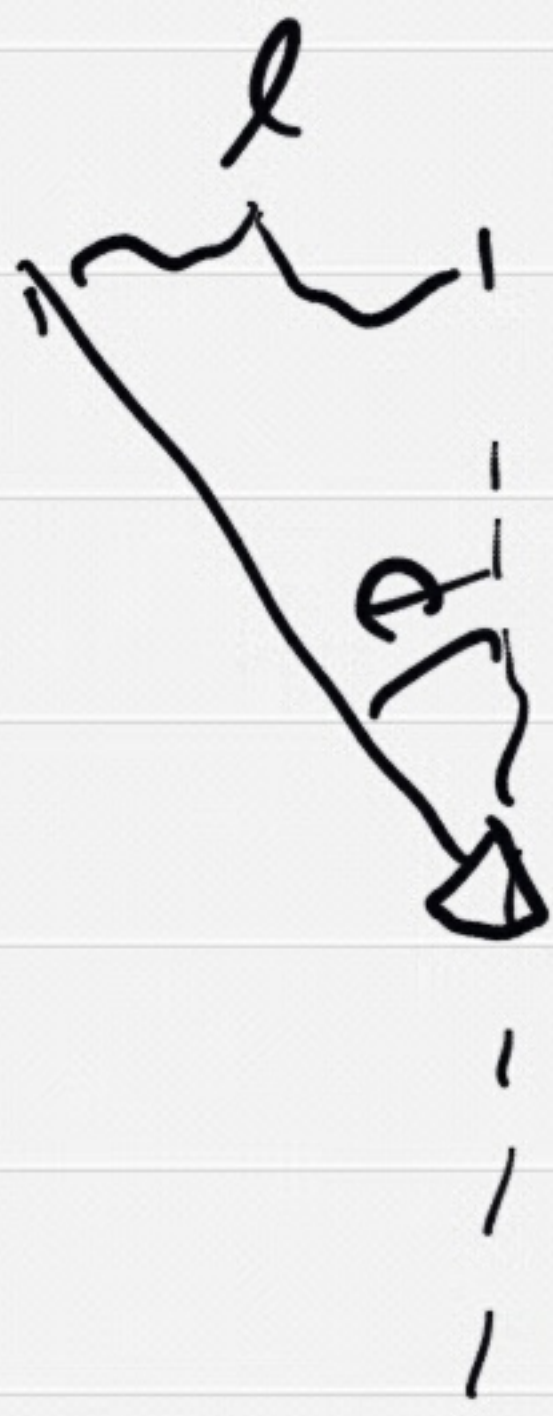
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(Hint: $\alpha = \frac{\tau}{I}$)



$$l = L \sin \theta$$

$$\begin{aligned} \tau &= F l \\ &= mg L \sin \theta \end{aligned}$$

$$I = mL^2$$

$$\begin{aligned} \alpha &= \tau / I \\ &= \frac{mgL \sin \theta}{mL^2} \end{aligned}$$

$$= \frac{g \sin \theta}{L}$$



$$l = \frac{L}{2} \sin \theta$$

$$\begin{aligned} \tau &= F l \\ &= 2mg \cdot \frac{L}{2} \sin \theta \end{aligned}$$

$$= mgL \sin \theta$$

$$\begin{aligned} I &= 2m \left(\frac{L}{2}\right)^2 \\ &= \frac{1}{2} mL^2 \end{aligned}$$

$$\begin{aligned} \alpha &= \tau / I \\ &= \frac{mgL \sin \theta}{\frac{1}{2} mL^2} \end{aligned}$$

$$= \frac{2g \sin \theta}{L}$$