# College Physics I: 1511 Mechanics & Thermodynamics

Professor Jasper Halekas Van Allen Lecture Room 1 MWF 8:30-9:20 Lecture

### Harmonic Oscillator: Spring



#### Harmonic Oscillator: Pendulum



# **General Harmonic Oscillator**

- Why is the frequency  $1/(2\pi) \sqrt{(k/m)}$ ?
- Set by the ratio between the restoring force constant and the inertia
- In the case of a pendulum, force and inertia each have a factor of mass, so m cancels out

# **General Harmonic Oscillator**

- Given a restoring force F = -kx:
  - Frequency =  $1/(2\pi) \sqrt{k/m}$
- Works with angular variables too, so given τ = k<sub>rot</sub>θ:
  - Frequency =  $1/(2\pi) \sqrt{(k_{rot}/I)}$
  - For pendulum  $k_{rot} = mgL$ ,  $I = mL^2$ , so  $f = 1/(2\pi) \sqrt{(g/L)}$

- Imagine you form a harmonic oscillator with a mass m on a spring with constant k, and set it oscillating with amplitude A. As the mass reaches its greatest displacement (x = A), you attach a second mass m. What happens to the maximum velocity v<sub>m</sub> of the subsequent motion?
- A.  $v_m$  stays the same
- B. v<sub>m</sub> doubles
- C.  $v_m$  is cut in half
- D.  $v_m^{'''}$  is cut by a factor  $\sqrt{2}$

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PEmm = V2KX2 = J2KA2 = KEmax = Jzm/m<sup>2</sup>  $f_{2}mV_{m}^{2} = f_{2}(2m)V_{m}^{2}$ 

$$V_{m}^{2} = 2V_{m}^{2}$$

$$V_{m}^{2} = \pm V_{m}^{2}$$

$$V_{m}^{2} = \frac{1}{2}V_{m}^{2}$$

$$V_{m}^{2} = \frac{1}{\sqrt{2}}V_{m}$$

$$A \mid so see \quad V_{m} = \sqrt{\frac{k}{m}} A$$

$$V_{m}^{2} = \sqrt{\frac{k}{2m}} A$$

= TE Vm

#### **Harmonic And Rotational Motion**



 $\omega = 2\pi f = 2\pi/T$  for both kinds of motion

# Frequency Vs. Angular Frequency: A Tale of Two Omegas

- Whatever the type of harmonic oscillator, it's useful to think about its frequency as an angular frequency (similar to angular velocity, and same units, but more general):
  - $\omega_h = 2\pi f$  (applicable to any cyclical oscillation)
  - For general harmonic oscillator:
    - $\omega_h = \sqrt{(k/m)}$
  - For pendulum:
    - $\omega_h = \sqrt{(g/L)}$

 $hh = 2\pi f$ - J/m for spring  $\Rightarrow V_m = W_h X_m = W_h A$  $\alpha m = \omega_h^2 A$ 

# **Conservation of Energy**

- $E = PE_{tot} + KE_{tot}$ 
  - =  $PE_{grav} + PE_{spring} + KE_{trans} + KE_{rot}$
  - = mgh +  $1/2kx^2 + 1/2mv^2 + 1/2I\omega^2$
  - = Conserved in the absence of friction etc.

#### Be careful!!!

- We have two meanings for the symbol ω
  - One is angular velocity for circular motion
  - One is angular frequency for harmonic motion ω<sub>h</sub>
  - They are related, but not always interchangeable
  - Be careful to only use angular velocity in 1/2Iω<sup>2</sup>

#### **Period Independent of Amplitude**

- The period T =  $2\pi/\omega_h = 2\pi\sqrt{(m/k)}$ 
  - Does not depend on amplitude
  - How can this be?
  - Maximum velocity and acceleration both depend on the amplitude of the motion
    - Bigger displacement -> faster motion

• 
$$x_{max} = A$$

• 
$$v_{max} = \omega_h A$$

• 
$$a_{max} = \omega_h^2 A$$

# **Physical Pendulum**



# **Physical Pendulum**

Found that angular frequency of oscillation of a simple pendulum was:

• 
$$\omega_h = \sqrt{(mgL/I)} = \sqrt{(mgL/mL^2)} = \sqrt{(g/L)}$$

- For a physical pendulum almost the same formula applies:
  - $\omega_h = \sqrt{(mgL_{CM}/I)}$
  - But now the details depend on the center of mass  $L_{\rm CM}$  and the moment of inertia  ${\rm I}$

# Example of physical pendulum



 $L_{CM} = L/2$ 

$$ω_h = \sqrt{(mgL/2/(1/3ML^2))}$$
  
=  $\sqrt{(3g/2L)}$ 

Faster than simple pendulum since moment of inertia smaller

- A person swings on a swing. When the person sits still, the swing oscillates back and forth at its natural frequency. If, instead, the person stands on the swing, the natural frequency of the swing is..
- A: greater.
- B: the same.
- **C:** smaller.

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