College Physics I: 1511 Mechanics & Thermodynamics

Professor Jasper Halekas Van Allen Lecture Room 1 MWF 8:30-9:20 Lecture

Announcements

- All labs and discussion sections will meet this week, and homework is due Thursday as usual
- I will be gone Wednesday
 - Prof. Baalrud will substitute
 - Office hours extended this Tuesday to 1:30-4:00
 - Office hours canceled Wednesday & Thursday
 - Available by e-mail
 - Back Friday

Announcements

- Midterm #1 Equation Sheet Posted (on notes page)
- Sample problems will be posted the week before the midterm

A car rounds a curve while maintaining a constant speed. Is there a net force on the car as it rounds the curve?



- A: No-its speed is constant.
- B: Yes.
- C: Depends

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Position/Velocity in Circular Motion



Acceleration in Circular Motion



Acceleration in Uniform Circular Motion



Circles: Radius and Circumference



Circles: Arc Length and Angle



Speed/Velocity of Circular Motion

- Average speed |v| = distance/time
 - Average speed for an arc $|v| = S/\Delta t$
 - Average speed for the whole circle $|v| = 2\pi r/T$
 - (T = period of revolution)
- Note that the average velocity over a full circle is zero (since displacement = o)
 - Later in the course we will learn about "angular velocity"



11 · 2 · 0 $\theta = \frac{1}{r} - \frac{1}{r} = \frac{1}{r} + \frac{1}{r}$ $\Theta = 18V/V$ $\Delta V_V = V \Delta t$



Acceleration of Uniform Circular Motion



Small angle approximation: $\theta \sim \sin\theta \sim \tan\theta$ for small θ

Centripetal Force

 mv^2

Note that to stay in circular motion, there must be a constantly applied force!

[Circular Motion] In equilibrium: $\vec{F}_{net} = \vec{\Sigma} \vec{F} = 0$

Circular motion is not equilibrium:

 $\vec{F}_{net} = \Sigma \vec{F} = M \alpha_c = M v^2 v = F_c$ If force removed, an object follows Newtoin's first law and goes straight

In a game of tetherball, a ball is tied to a pole with a string. While the ball whirls around the pole, in what direction is the acceleration of the ball (at the moment shown?)



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Fc = mvy = Fnet (not an individual force but the net force) $T_{y} = T_{x}$ $T_{x} = T_{y} = T_{y$ $F_{X_{net}} = F_c = \frac{mv^2}{r} = T_{sin} \Phi$



Fynet = T cost - mg = 0 $= mq = T \cos \theta$ $= T - mq \cos \theta$ Plug into 1-x

mv2 = mg/osp-Lsin20 If v² goes up o must go up to provide needed centripetal force



Centripetal Force: Real



Centrifugal Force: Not Real



Non-Inertial Reference Frames





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 $Fnet = N = mv \frac{2}{r}$ Fr = MN = Mmvir To balance W and Keep rider from slipping, need i mmuly = mg

