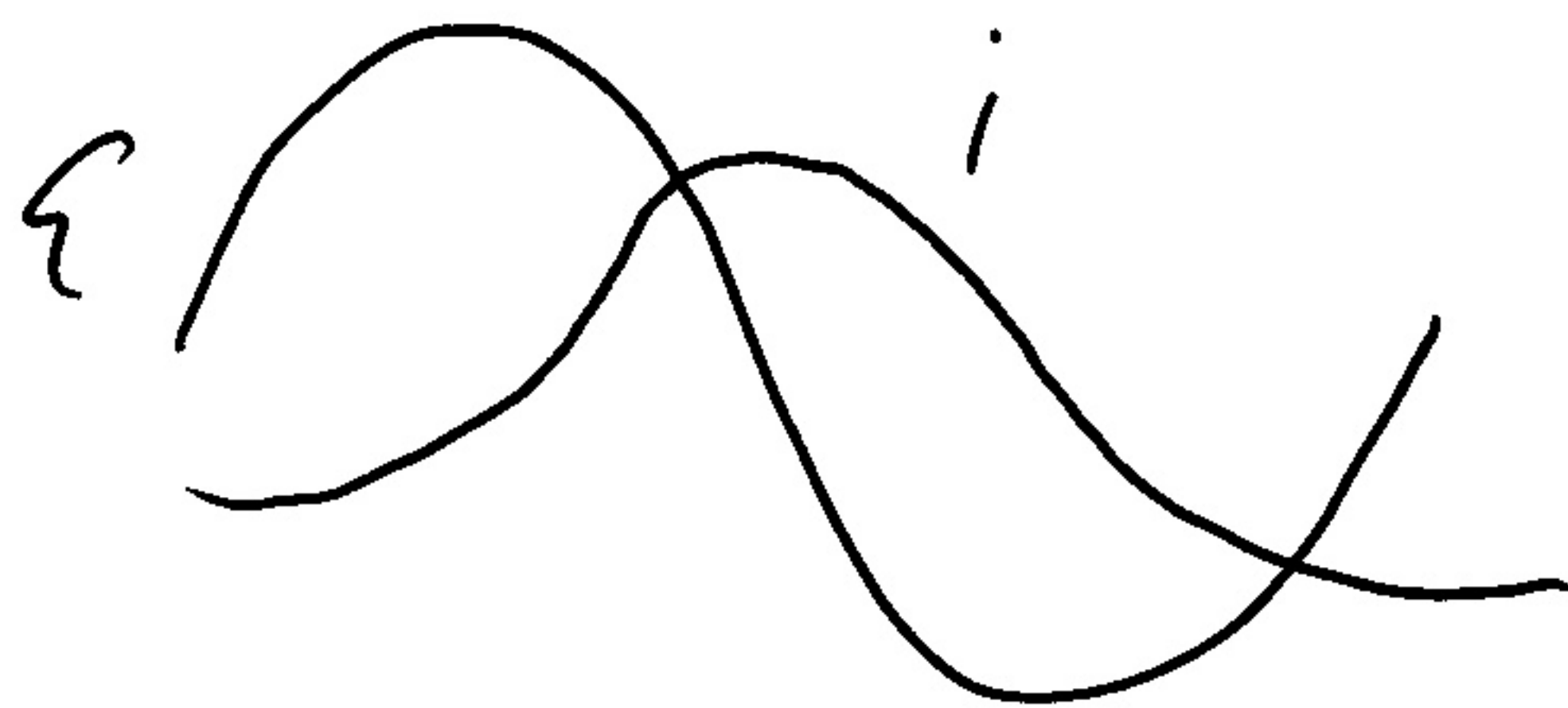


C1:



a. i lags ϵ

so if $\epsilon = \epsilon_m \sin \omega t$

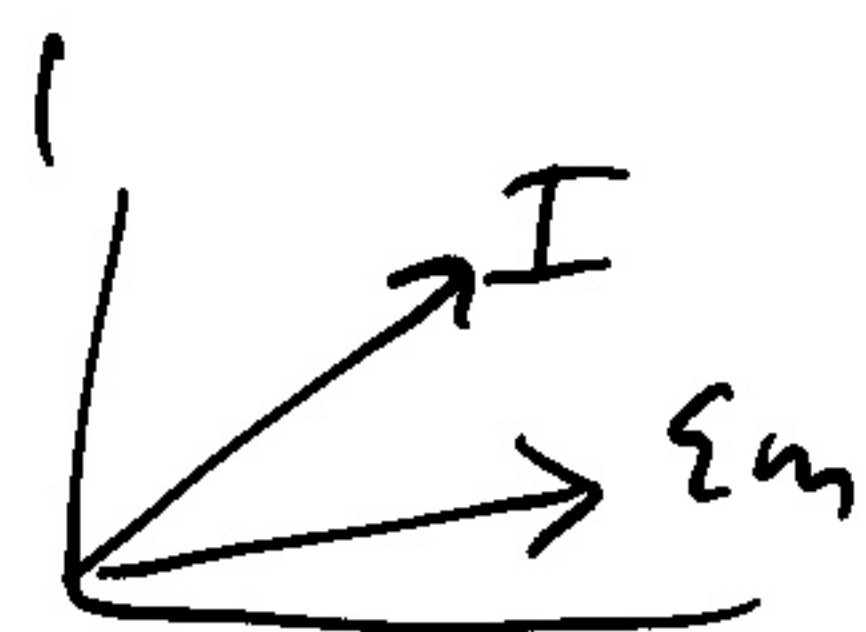
$$i = \epsilon_m \sin(\omega t - \phi)$$

$$\phi > 0$$

b. circuit is inductive,
so want to decrease X_L & L

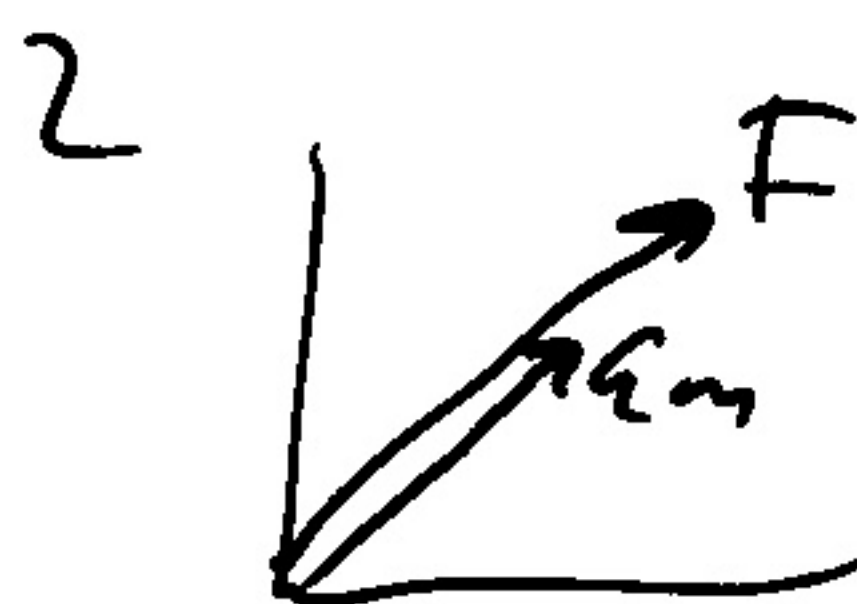
c. want to increase X_C , so
decrease C

C2:



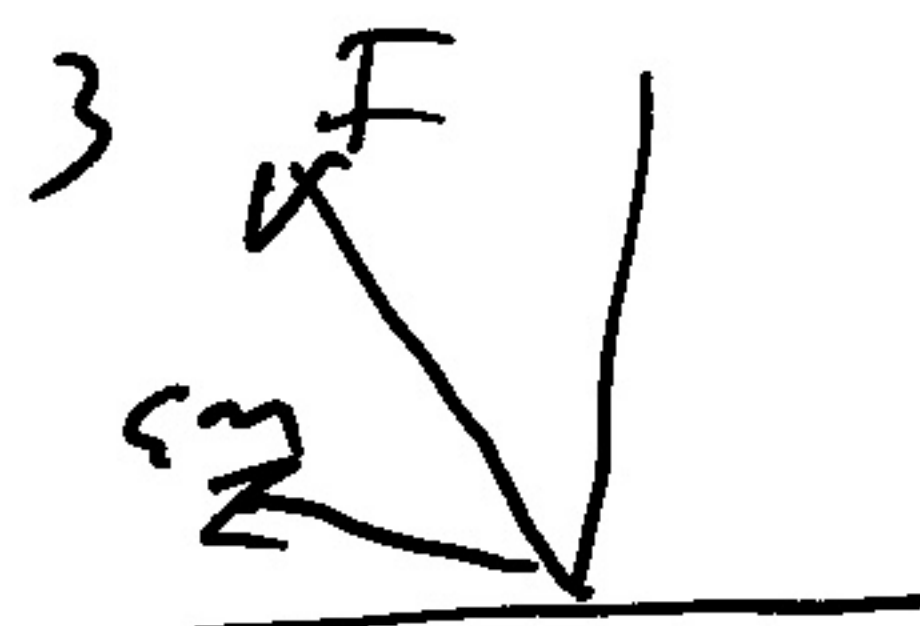
capacitive

$$\omega_d < \omega_r$$



resistive

$$\omega_d = \omega_r$$



inductive

$$\omega_d > \omega_r$$

C3



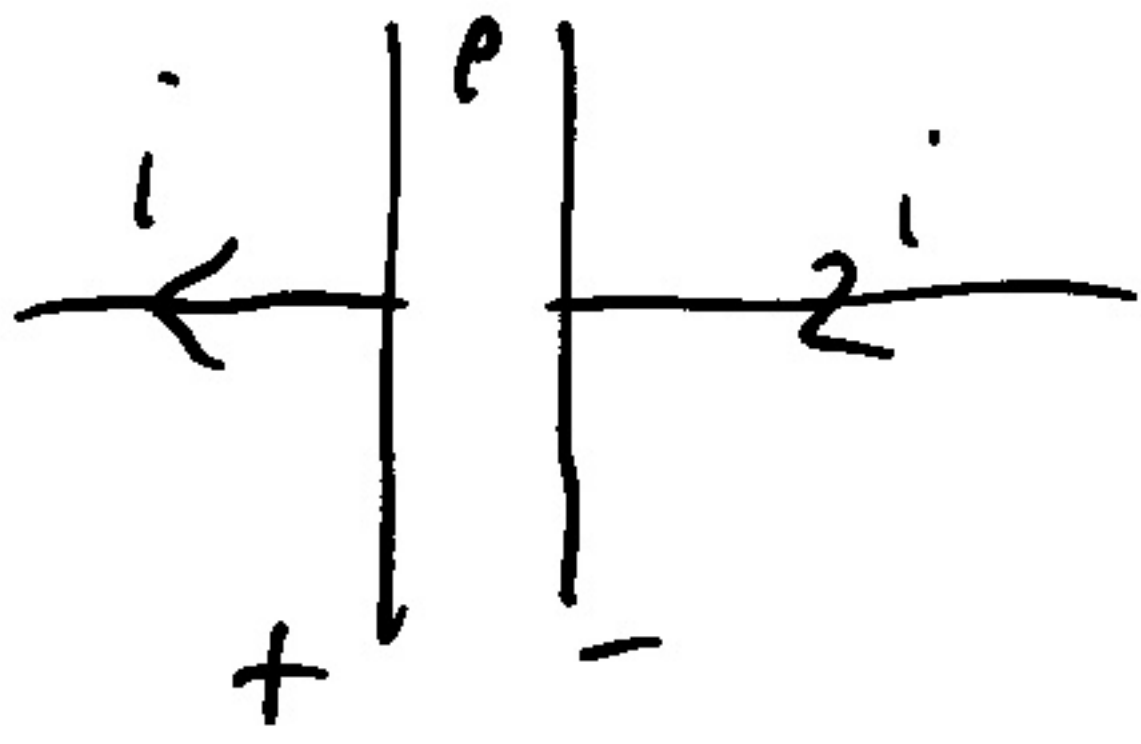
capacitive

- increasing L, C, ω

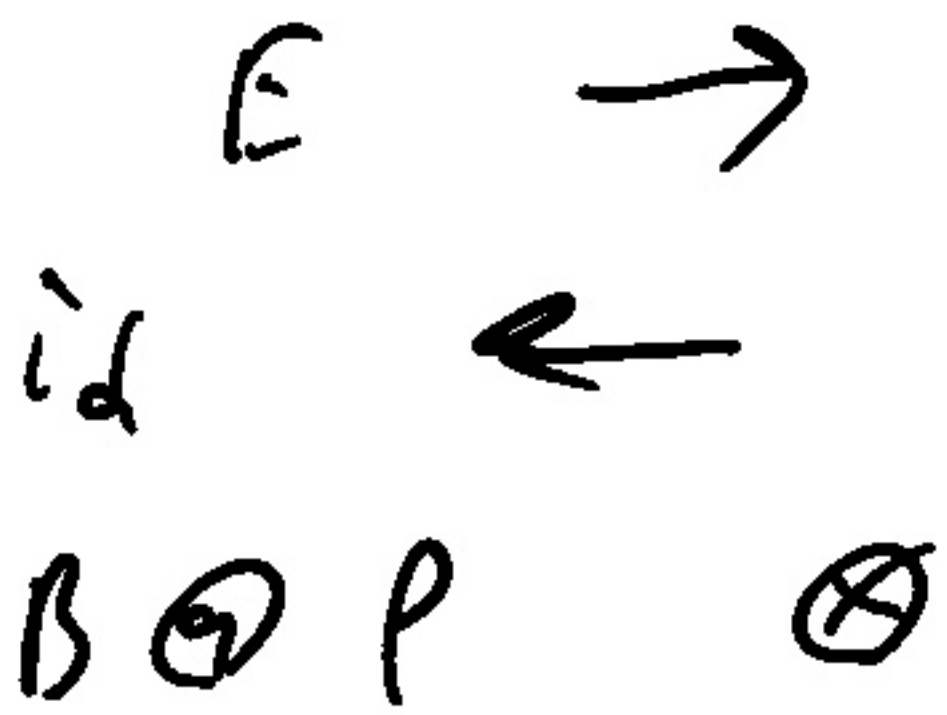
- all make circuit more inductive

- shift i right & increase amplitude

C4:



Capacitor
discharging

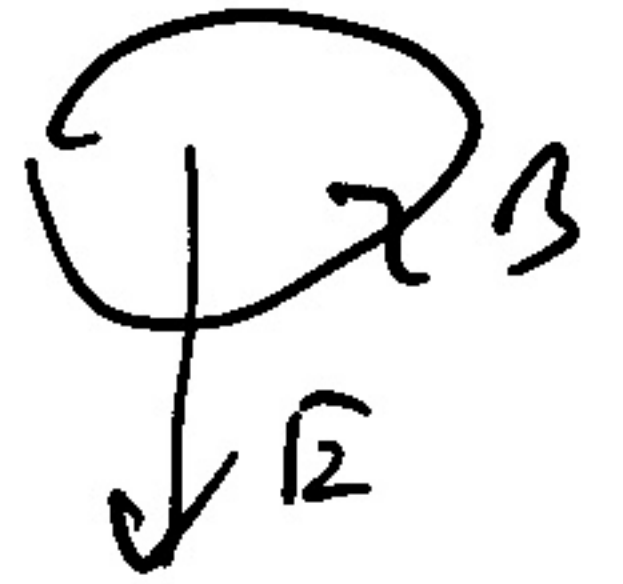


C5:

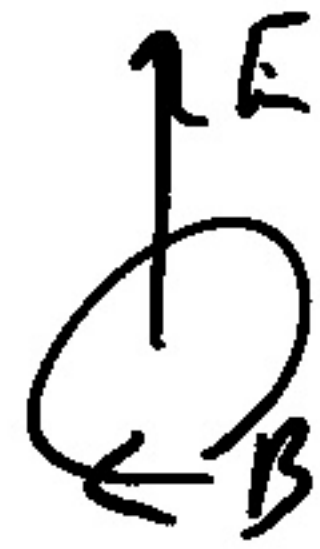
$$\oint \vec{B} \cdot d\vec{l} = \mu_0 \epsilon_0 \frac{d\phi_E}{dt}$$
$$= \mu_0 \epsilon_0 A \frac{dE}{dt}$$

for fixed area

a. RHR gives dE/dt up,
so $|\vec{E}|$ decreasing



b. dE/dt down, so $|\vec{E}|$
decreasing



$$M1: a. X_C = \frac{1}{\omega C} \quad \omega = 2\pi f$$

$$b. Z = \sqrt{R^2 + (\omega L - \frac{1}{\omega C})^2}$$

$$c. I = \frac{\epsilon_m}{Z}$$

$$M2: a. P_G = \epsilon_i \\ = \epsilon_m \sin(\omega t) \cdot \frac{\epsilon_m}{Z} \sin(\omega t - \phi)$$

$$b. P_C = V_C i \\ = \frac{q}{C} \cdot i \\ = -\frac{1}{\omega C} I \cos(\omega t - \phi) \cdot I \sin(\omega t - \phi) \\ = -\frac{\epsilon_m^2}{Z^2} \cdot X_C \cdot \cos(\omega t - \phi) \sin(\omega t - \phi)$$

$$c. P_L = V_L i \\ = i L \frac{di}{dt} \\ = I \sin(\omega t - \phi) \cdot L \cdot \omega \cdot I \cos(\omega t - \phi) \\ = \frac{\epsilon_m^2}{Z^2} \cdot X_L \cdot \sin(\omega t - \phi) \cos(\omega t - \phi)$$

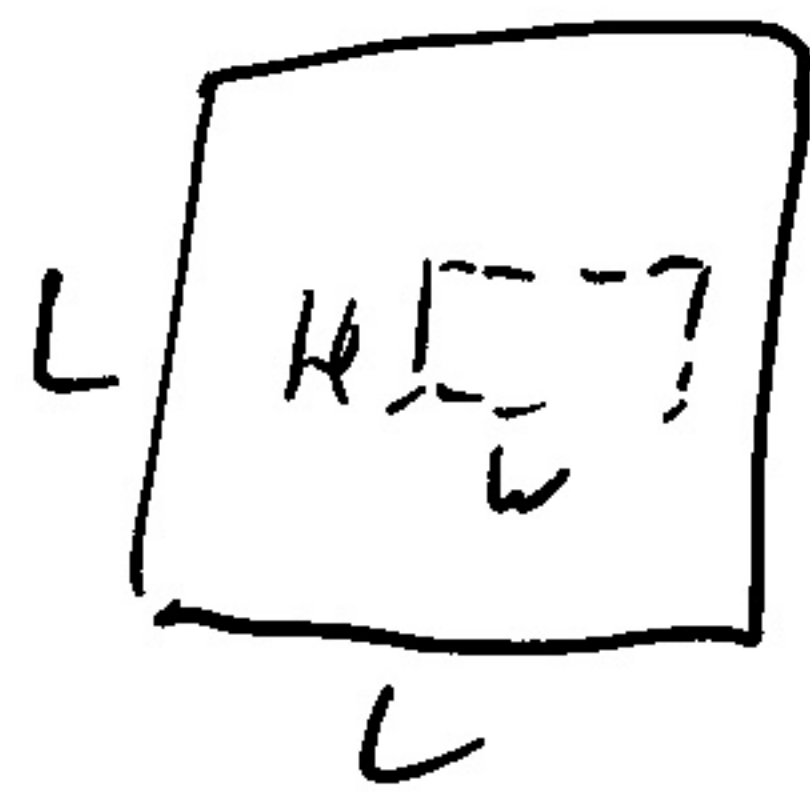
$$d. P_R = i^2 R \\ = \frac{\epsilon_m^2}{Z^2} \cdot R \cdot \sin^2(\omega t - \phi)$$

$$P_G = P_C + P_L + P_R$$

$$M3: \oint \vec{B} \cdot d\vec{s} = \mu_0 \epsilon_0 \frac{d\phi_E}{dt}$$

$$= \mu_0 i_{\text{enc}}$$

$$i_{\text{enc}} = i \cdot H \cdot w / L^2$$



$$M4: \oint \vec{B} \cdot d\vec{s} = B \cdot 2\pi r$$

$$= \mu_0 i_{\text{enc}}$$

$$= \mu_0 i \cdot \frac{\pi r^2}{\pi R^2}$$

$$\Rightarrow B = \frac{\mu_0 i r}{2\pi R^2}$$

$$i = \mathcal{E}/R e^{-t/RC} \quad w/ \quad C = \epsilon_0 A/d$$

$$M5: V = V_0 e^{-t/\tau}$$

$$E = V/d$$

$$q_{0E} = E A = E \cdot \pi r^2 = \frac{V_0}{d} \cdot \pi r^2 e^{-t/\tau}$$

$$|d\phi_E/dt| = \frac{\pi r^2 V_0}{\tau d} e^{-t/\tau}$$

$$|\vec{B}| = \mu_0 \epsilon_0 |d\phi_E/dt| \cdot \frac{1}{2\pi r}$$

$$= \frac{\mu_0 \epsilon_0 r V_0}{2\tau d} e^{-t/\tau}$$

Parallel Eqs.

$$\oint \vec{B} \cdot d\vec{\ell} = \mu_0 \epsilon_0 \frac{dq_{\text{enc}}}{dt}$$

$$\oint \vec{E} \cdot d\vec{\ell} = - \frac{dq_{\text{enc}}}{dt}$$

- Why difference in sign?

(-) in Faraday's Law

\Rightarrow changing B produces EMF that drives current that opposes change in B

(+) in Ampere's Law

\Rightarrow Changing E produces an effective current that "completes the circuit" and reinforces the change

- If both were (+) or both (-) light waves would not oscillate